PETER electronic

User manual

Frequency Inverter
Serie CV/3CV 200-240V/380 – 480V 0,37 bis 55kW

PETER electronic GmbH & Co. KG, Bruckäcker 9, D-92348 Berg

Tel. (09189) 4147-0, Fax (09189) 4147-47
eMail: mail@peter-electronic.com
Internet: www.peter-electronic.com

Quick Start Guide

This guide is to assist in installing and running the inverter to verify that the drive and motor are working properly. Starting, stopping and speed control will be from the keypad. If your application requires external control or special system programming, consult the 7300CV Instruction Manual supplied with your inverter.

Step 1 Before Starting the Inverter

Please review Preface and Safety Precautions (page 0-1 through 1-3) of the 7300CV Instruction Manual. Verify drive was installed in accordance with the procedures as described in 7300CV Ambient Environment and Installation on pages 3-1 through 3-8. If you feel this was abnormal, do not start the drive until qualified personnel have corrected the situation. (Failure to do so could result in serious injury.)

- **Check inverter and motor nameplates to determine that they have the same HP and voltage ratings. (Ensure that full load motor amps do not exceed that of the inverter.)**

- **Remove the terminal cover to expose the motor and power terminals.**

  a. Verify that AC power is wired to L1, L2, and L3 (pages 3-12).
  b. Verify that Motor leads are connected to T1, T2, and T3 (pages 3-12).
  (The two leads may need to be reversed if motor rotation is not correct.

1. SEQ LED：1_00 =1, LED Lit.

2. FRQ LED：1_01 = 1/2/3/4, LED Lit

3. FWD LED：Forward Direction, LED action(Flash in stop, Keep Lit in operation).

4. REV LED：Reverse Direction, LED action(Flash in stop, Keep Lit in operation).

5. Four action of FUN、Hz/RPM、VOLT、AMP LED and display of four 7-segment display, refer to operation description of the keypad.

6. LCD keypad without FUN, Hz/RPM, VOLT, AMP LED.

Step 2 Apply Power to the Drive

- **Apply AC power to the Drive and observe Operator. Four 7-segment Display should read Power Voltage for 3~5 seconds and then read Frequency/Speed, 05.00. Four 7-segment Display and FWD LED should be flashed all the time.**

Step 3 Check Motor Rotation Without Load

- **Press RUN key (FWD LED should light); Four 7-segment Display should run from 00.00 to 05.00.**
- **Check motor rotation.**
  If it is not correct:
  Press STOP key. Remove AC power. Wait for LED "charge" lamp to extinguish.
  Reverse motor leads T1 and T2.Restart the drive and check new rotation**.**
- **Press STOP key to stop the drive.**

Step 4 Check Full Speed at 50Hz/60Hz

- **Frequency/Speed can be changed by pressing the up or down Arrow keys. To move right or left for next digit, press SHIFT / RESET key. Press the READ / ENTER key to set the speed.**
- **Set frequency up to 50Hz/60Hz in accordance with the last rule.**
- **Press RUN key. Check drive acceleration to full speed.**
- **Press STOP key to stop drive and check deceleration.**

Step 5 Other Operations

For information, see 7300CV Instruction Manual.
Please refer to the following pages:

Set Accel .....p. 4-11
Set Decel ..... p. 4-11
Set Max Speed ..... p. 4-11
Set Min Speed ..... p. 4-11
Set Motor Rated Current ..... p. 4-9
Set Control Mode (Vector, V/F) ..... p. 4-7

Table of Content

Quick Start Guide		i
Chapter 0	**Preface**	0-1
0.1	Preface	0-1
0.2	Products Inspection	0-1
Chapter 1	**Safety Precautions**	1-1
1.1	Operation Precaution	1-1
	1.1.1 Before Power ON	1-1
	1.1.2 During Power ON	1-2
	1.1.3 Before Operation	1-2
	1.1.4 During Operation	1-3
	1.1.5 During Maintenance	1-3
Chapter 2	**Definition of Model**	2-1
Chapter 3	**Ambient Environment and Installation**	3-1
3.1	Environment	3-1
3.2	Environmental Precautions	3-2
3.3	Inflammable Materials	3-3
	3.3.1 Notice for Wiring	3-3
	3.3.2 Applicable Specification of Magnetic Contactor and Wires	3-5
	3.3.3 Precautions for Peripheral Applications	3-6
3.4	Specifications	3-9
	3.4.1 Products Individual Specifications	3-9
	3.4.2 General Specifications	3-10
3.5	Wiring Diagram 7300CV Series Inverter	3-12
3.6	Description of Terminals Troubleshooting Inverter	3-13
3.7	Outline Dimension	3-15
Chapter 4	**Software Index**	4-1
4.1	Keypad Description	4-1
	4.1.1 Keypad Display and Operation Instruction	4-1
	4.1.2 Operation Instruction of the Keypad	4-2
	4.1.3 Operation Instruction of the LED Keypad	4-3
	4.1.4 Operation Instruction of the LCD Keypad	4-4
	4.1.5 Keypad Operating Example	4-5
4.2	Control Mode Selection	4-7
4.3	7300CV Programmable Functions List	4-8
4.4	Parameter Function Description	4-20
4.5	Specification Description on Built-in PLC Function	4-63
	4.5.1 Basic Instruction	4-63
	4.5.2 Function of Basic Instruction	4-64
	4.5.3 Application Instructions	4-65
Chapter 5	**Troubleshooting and Maintenance**	5-1
5.1	Error Display and Remedy	5-1
	5.1.1 Error which can not be Recovered Manually	5-1
	5.1.2 Error which can be recovered manually and automatically	5-2
	5.1.3 Error which can be recovered manually but not auto matically	5-3
	5.1.4 Special Conditions	5-4
	5.1.5 Operation Errors	5-5
5.2	General Troubleshooting	5-6
5.3	Quick Troubleshooting 7300CV Series	5-7
5.4	Routine Inspection and Period Inspection	5-13

5.5	Maintenance and Inspection	5-14
Chapter 6	**Peripheral Components**	6-1
6.1	Reactor Specification at Input Side	6-1
6.2	Reactor Specification at DC Side	6-1
6.3	Braking Resistor	6-2
6.4	Digital Operator and Extension Cable	6-3
6.5	EMC Filter	6-5
6.6	Interface Card	6-7
	6.6.1 RS-485 Interface Card	6-7
	6.6.2 RS-232 Interface Card	6-8
	6.6.3 Program Copy Unit	6-9
	6.6.4 PDA Link	6-9
AppendixⅠ	7300CV Motor Internal Parameter List	App1
AppendixⅡ	7300CV Parameters Setting List	App2

Chapter 0 Preface

0.1 Preface

To extend the performance of the product and ensure your safety, please read this manual thoroughly before using the inverter. Should there be any problem in using the product and can not be solved with the information provided in the manual, contact your nearest Teco's distributor or our sales representatives who will be willing to help you. Please keep using Teco's products in the future.

※Precautions

The inverter is an electrical electronic product. For your safety, there are symbols such as "Danger", "Caution" in this manual to remind you to pay attention to safety instructions on handling, installing, operating, and checking the inverter. Be sure to follow the instructions for highest safety.

Danger	Indicates a potential hazard could cause death or serious personal injury if misused.
⚠ Caution	Indicates that the inverter or the mechanical system might be damaged if misused.

Danger
● Do not touch any circuit boards or components if the charging indicator is still lit after turned the power off. ● Do not wire when the inverter is electrified. Do not check parts and signals on circuit boards during the inverter operation. ● Do not disassemble the inverter and modify internal wires, circuits and parts. Ground the ground terminal of the inverter properly. As for 200V class ground to 100 Ω or below, 400v class ground to 10Ω or below.

⚠ Caution
● Do not perform a voltage test on parts inside the inverter. High voltage will easily destroy these semiconductor parts. ● Do not connect T1 (U), T2 (V), and T3 (W) terminals of the inverter to AC power supply. ● CMOS ICs on the inverter's main board are susceptible to static electricity. Do not touch the main circuit board

0.2 Products Inspection

Teco's inverters are all passed the function test before delivery. Please check the followings when you received and unpacked the inverter:

- The model and capacity of the inverter are the same as those specified in your purchase order.
- Check where there are any damages caused by transportation. Please do not apply the power, and do contact Teco's sales representatives if any of the above problems happened.

Chapter 1 Safety Precautions

1.1 Operation Precaution

1.1.1 Before Power ON

⚠ Caution
The line voltage applied must comply with the inverter's specified input voltage.

Danger
Make sure the main circuit connections are correct. L1(L), L2 and L3(N) are power-input terminals and must not be mistaken for T1, T2 and T3. Otherwise, the inverter might be damaged.

⚠ Caution
● To avoid the front cover from disengaging, do not pull the cover during handling for the heat sink should be fallen off. Accident falling down will damage the inverter or injure to person, which should be avoided. ● To avoid the risk of fire, do not install the inverter on a flammable object. Install it on nonflammable object such as metal. ● If several inverters are placed in the same control panel, add extra heat sink to keep the temperature below 40□ to avoid overheat or fire. ● When removing or installing the operator, turn OFF the power first, and manipulate the operator following the instruction of the diagram to avoid operator error or no display caused by bad contact.

Warning
This is a product of the restricted sales distribution class according to IEC 61800-3. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

1.1.2 During Power ON

Danger

- Do not plug or unplug the connectors on the inverter when electrified to avoid the control panel damage resulting from erratic transition voltage surge due to contact bounce.
- When momentary power loss is longer than 2 seconds (the larger of horse power, the longer of time), the inverter does not have enough storage power to control the circuit; Therefore, when power is regenerated, the operation of the inverter is based on the setup of 1-00 / 2-05 and the condition of external switch, this is considered to be 「restart」 in the following paragraphs.
- When the momentary power loss is short, the inverter still has enough storage power to control the circuit. Therefore, when power is regenerated, the inverter will automatically restart depending on the setup of 2-00/2-01.
- When restart the inverter, the operation of the inverter is based on the setup of 1-00 and 2-05 and the condition of external switch (FWD/REV button). Attention: the start operation is irrelevant with 2-00/2-01/2-02/2-03.

  1. When 1-00=0000, the inverter will not automatically run after restart.

  2. When 1-00=0001 and the external switch (FWD/REV button) is OFF, the inverter will not run after restart.

  3. When 1-00=0001, the external switch (FWD/REV button) is ON, and 2-05=0000, the inverter will run automatically after restart. Attention: In the sake of safety, please turn off the external switch (FWD/REV button) after power loss to avoid underling damage to the machine and the human body after sudden regeneration of power.
- To ensure the safety of people and machine, please refer to the description and suggestion of 2-05

1.1.3 Before Operation

Danger

Make sure the model and capacity are the same as those set by 15-0.

⚠ Caution

The inverter will flash the power voltage set by 0-07 for 5 seconds when applying power.

1.1.4 During Operation

Danger
Do not engage or disengage the motor during operation. Otherwise, the over-current will cause the inverter to disconnect or the main circuit to burn.

Danger
• To avoid electric shock, do not take the front cover off during electrifying • The motor will restart automatically after stop when auto-restart function is on. In this case, do not get close to the machine. • Note: The stop switch is different from the usage of the emergency stop switch. It must be set first to be effective.

Caution
• Do not touch heat-generating components such as heat sink and braking resistor. • The inverter can drive the motor running from low speed to high speed. Verify the allowable capacities range of the motor and the mechanism. • Note the settings related to the braking reactor. • Do not check signals on circuit boards while the inverter is running.

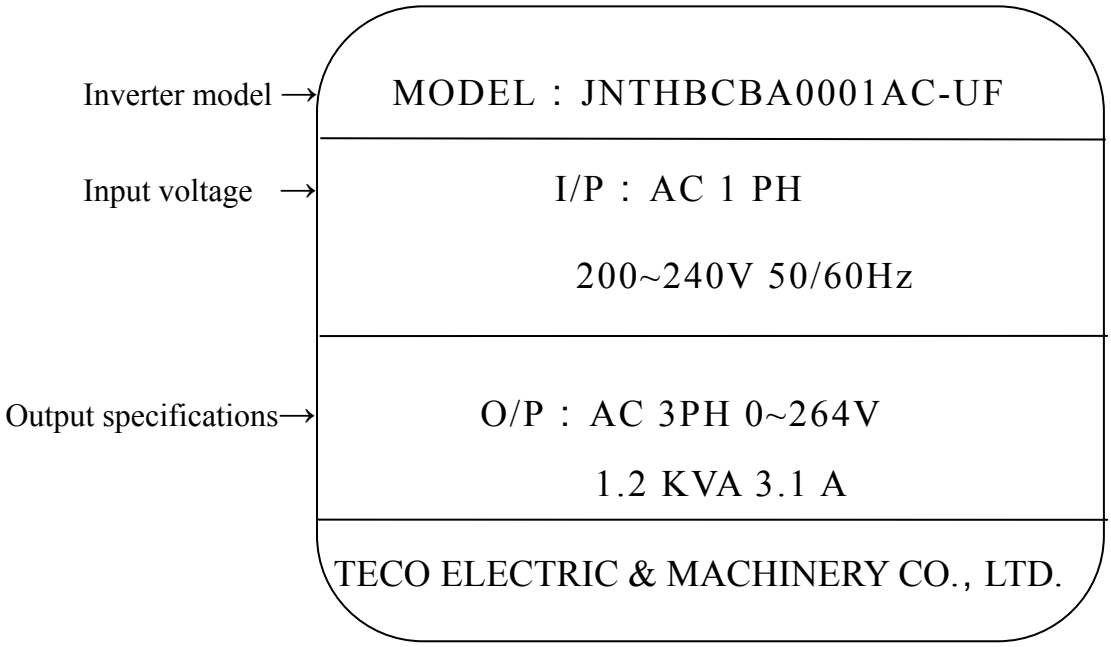
Caution
It is after 5 minutes that disassembling or checking the components could be performed as power supply OFF and the indicator turned off.

1.1.5 During Maintenance

Caution
The inverter should be used in a non-condensed environment with temperature from –10□ to +40□ and relative humidity of 95% non-condense.

Caution
When the inverter top cover has removed, it can be used in a non-condensed environment with temperature from –10□ to +50 □ and relative humidity of 95%, but the environment should be free from water and metal dust.

Chapter 2 Definition of model



JNTH BC BA 0001 AC - U F

Series:

Keypad Panel

BC : LED

BG : LCD

Horsepower :

R500 : 0.5 HP

0001 : 1.0 HP

0002 : 2.0 HP

0003 : 3.0 HP

0005 : 5.0 HP

7R50 : 7.5 HP

0010 : 10 HP

UL Approval :

U : Yes

Noise Filter :

- : None

Power supply:

AC : Single phase 220V

BC : Three phase 220V

Enclosure :

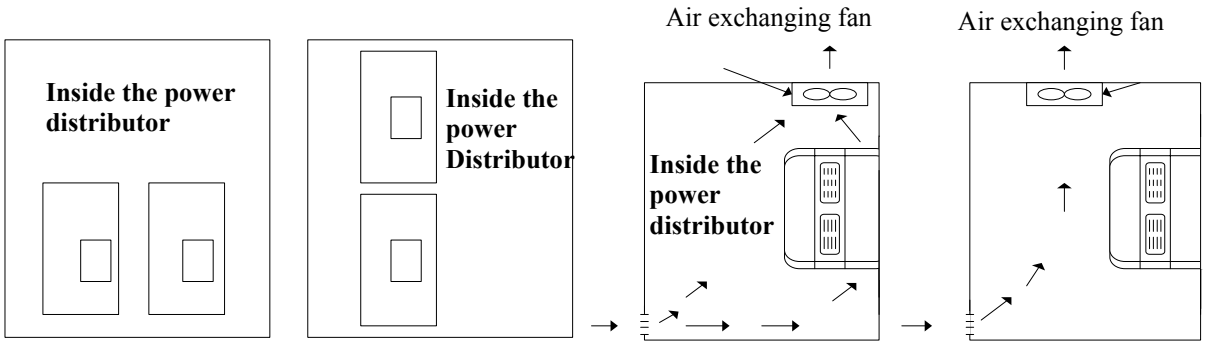
BA : Open chassis type

Chapter 3 Ambient Environment and Installation

3.1 Environment

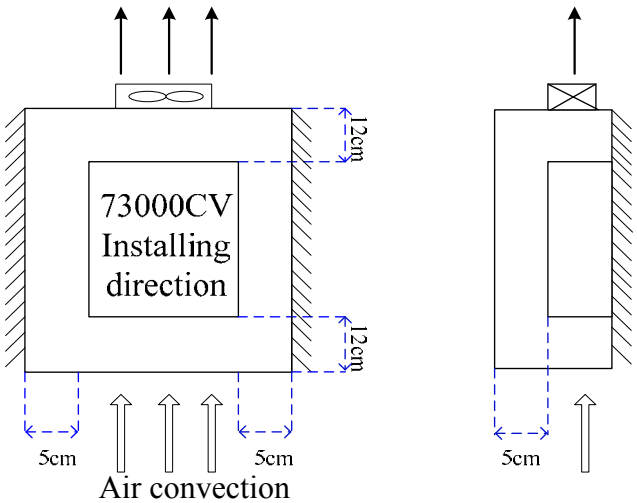
The environment will directly affect the proper operation and the life span of the inverter, so install the inverter in an environment complying with the following conditions:

- Ambient temperature: -10°C ~ +40°C; without cover: -10°C ~ +50°C
- Avoid exposure to rain or moisture.
- Avoid direct sunlight.
- Avoid oil mist and salinity.
- Avoid erosive liquid and gas.
- Avoid dust, bats, and small metal pieces.
- Keep away from radioactive and flammable materials.
- Avoid electromagnetic interference (soldering machine, power machine).
- Avoid vibration (punching machine). Add a vibration-proof pad if the situation cannot be avoided.
- If several inverters are placed in the same control panel, add extra heat sinks to keep the temperature below 40°C.



(Correct configuration) (Incorrect configuration) (Correct configuration) (Incorrect configuration)

- Place the front side of the inverter onward and top upward to in favor of heat sink.
  - Install the inverter according to the following figures: (take the dustproof cover off in favor of heat sinking if it is installed in a box or the environment allows to do so)

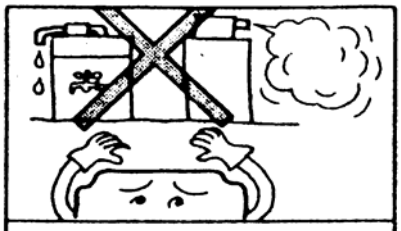


(a) Front view (b) Side view

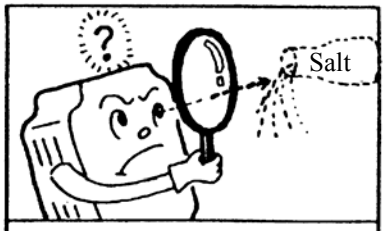
3.2 Environmental precautions

Do not use the inverter in an environment with the following conditions:

Direct sunlight

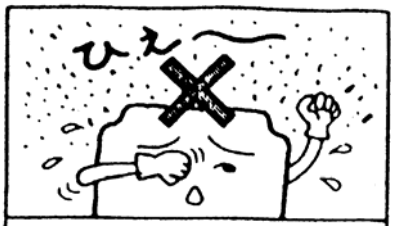

Corrosive gas and liquid

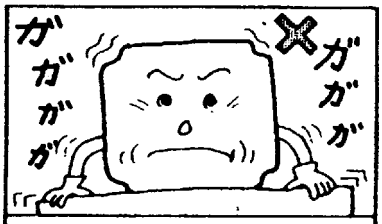
Oil Mist



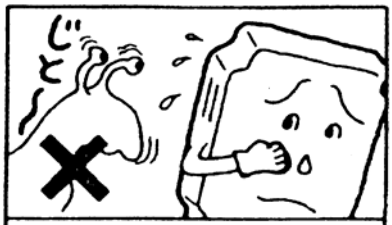
Salt

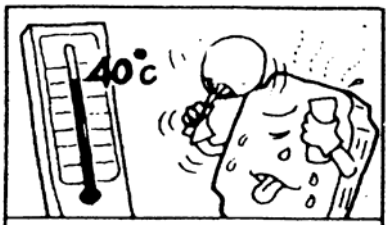
Wind, rain, and water drops may get into


Iron filings, dust

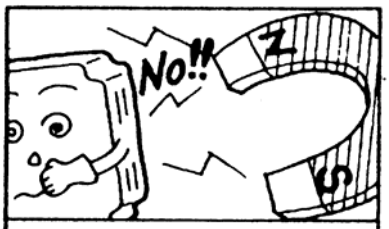


Strong vibration

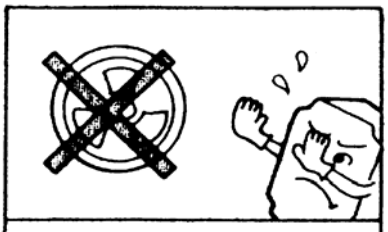

Extreme low temperature

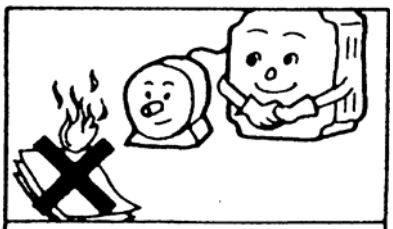


Excessive high temperature



Electromagnetic wave and ultra high wave
(Near an electric welding machine)


Radioactive materials


Inflammable materials

3.3 Inflammable materials

3.3.1 Notice for wiring

A. Screwdriver torque:

Wiring with a screwdriver or other tools and follow the torque listed below:

Securing torque			
Horsepower	Power source	Nominal torque for TM1 terminal	
0.5/1/2(3φ)	200-240V	0.59/0.08 (LBS-FT / KG-M)	7.10/8.20 (LBS-IN/KG-CM)
1/ 2	380-480V		
2(1φ)/3/5/7.5/10	200-240V	1.5/0.21 (LBS-FT/KG-M)	18.00/20.28 (LBS-IN/KG-CM)
3/ 5/ 7.5/ 10/15	380-480V		
15/20/25	200-240V	1.84/0.3 (LBS-FT / KG-M)	22.1/30 (LBS-IN/KG-CM)
20/25/30	380-480V		
30/40	200-240V	4.42/0.66 (LBS-FT/KG-M)	53.1/66 (LBS-IN/KG-CM)
40/50/60/75	380-480V		

B. Power wires:

Power wires are connecting to L1, L2, L3, T1, T2, T3, P, BR and P1. Choose wires in accordance with the following criteria:

(1) Use copper wires only. Deciding diameters of wires should be based on rating working at 105°C.
(2) For rating voltage of wires, the minimum voltage of 230VAC type is 300V, and 460VAC type is 600V.
(3) For safety reason, the power wires should be fixed by type terminal.

C. Control wires:

Control wires are wires connecting to TM2 control terminal. Choose the wire in accordance with the following criteria:

(1) Use copper wires only. Deciding diameters of wires should be based on rating working at 105°C.
(2) For rating voltage of wires, the minimum voltage of 230VAC type is 300V, and 460VAC type is 600V.
(3) To avoid noise interference, do not route the control wires in the same conduit with power wires and motor wires.

D. Nominal electrical specifications of the terminals Block:

The following list is nominal values of TM1:

Horsepower	Power source	Volts	Amps
0.5/1/ 2(3φ)	200-240V	600	15A
1/ 2	380-480V		
5/ 7.5/ 10	200-240V		40A
2(1φ)/3/ 5/ 7.5/ 10/15	380-480V		
15/20/25	200-240V		80A
20/25/30	380-480V		60A
30	200-240V		100A
40/50	380-480V		
40	200-240V		150A
60/75	380-480V		

Note: Nominal values of input and output signals (TM2) – follow the specifications of class 2 wiring.

E. Fuse types

Drive input fuses are provided to disconnect the drive from power in the event that a component fails in the drive's power circuitry. The drive's electronic protection circuitry is designed to clear drive output short circuits and ground faults without blowing the drive input fuses. Below table shows the 7300CV input fuse ratings.

To protect the inverter most effectively, use fuses with current-limit function.

RK5, CC/T TYPE FUSE FOR 7300CV

220V class(1φ)

JNTHBCBA-	HP	KW	KVA	100% CONT Output AMPS (A)	Max.RK5 FUSE Rating(A)	Max.CC or T FUSE Rating(A)
R500AC	0.5	0.4	1.2	3.1	10	20
0001AC	1	0.75	1.7	4.5	15	30
0002AC	2	1.5	2.9	7.5	20	40
0003AC	3	2.2	4.0	10.5	25	50

220V class(3φ)

JNTHBCBA	HP	KW	KVA	100% CONT Output AMPS (A)	Max.RK5 FUSE Rating(A)	Max.CC or T FUSE Rating(A)
R500BC	0.5	0.4	1.2	3.1	8	10
0001BC	1	0.75	1.7	4.5	12	15
0002BC	2	1.5	2.9	7.5	15	20
0003BC	3	2.2	4.0	10.5	20	30
0005BC	5	3.7	6.7	17.5	30	50
7R50BC	7.5	5.5	9.9	26	50	60
0010BC	10	7.5	13.3	35	60	70
0015BC	15	11.0	20.6	48	80	100
0020BC	20	15.0	27.4	64	100	125
0025BC	25	18.5	34.0	80	125	150
0030BC	30	22.0	41.0	96	160	200
0040BC	40	30.0	54.0	130	200	250

440V class(3φ)

JNTHBCBA-	HP	KW	KVA	100% CONT Output AMPS (A)	Max.RK5 FUSE Rating(A)	Max.CC or T FUSE Rating(A)
0001BE	1	0.75	1.7	2.3	6	10
0002BE	2	1.5	2.9	3.8	10	15
0003BE	3	2.2	4.0	5.2	10	20
0005BE	5	3.7	6.7	8.8	20	30
7R5BE	7.5	5.5	9.9	13	25	35
0010BE	10	7.5	13.3	17.5	30	50
0015BE	15	11.0	20.6	25	50	60
0020BE	20	15.0	27.4	32	60	70
0025BE	25	18.5	34.0	40	70	80
0030BE	30	22.0	41.0	48	80	100
0040BE	40	30.0	54.0	64	100	125
0050BE	50	37.0	68.0	80	125	150
0060BE	60	45.0	82.0	96	150	200
0075BE	75	55.0	110.0	128	200	250

*Fuse ratings are based upon 300V fuses for 230V inverter, and 500V for 460V inverters

□Notice

- To avoid shock hazards, do not touch any electrical component when the power is applied or just after five minutes the power plug is unplugged. The other action should be performed after the charge indicator went off.
- Do not perform wiring on the inverter while it is still electrified. Disregard of this notice could cause serious injure or death to persons.

□This product is designed to use in Pollution Degree 2 environment or equivalent environments.

3.3.2 Applicable specification of magnetic contactor and wires

Molded-case circuit breaker/magnetic contactor

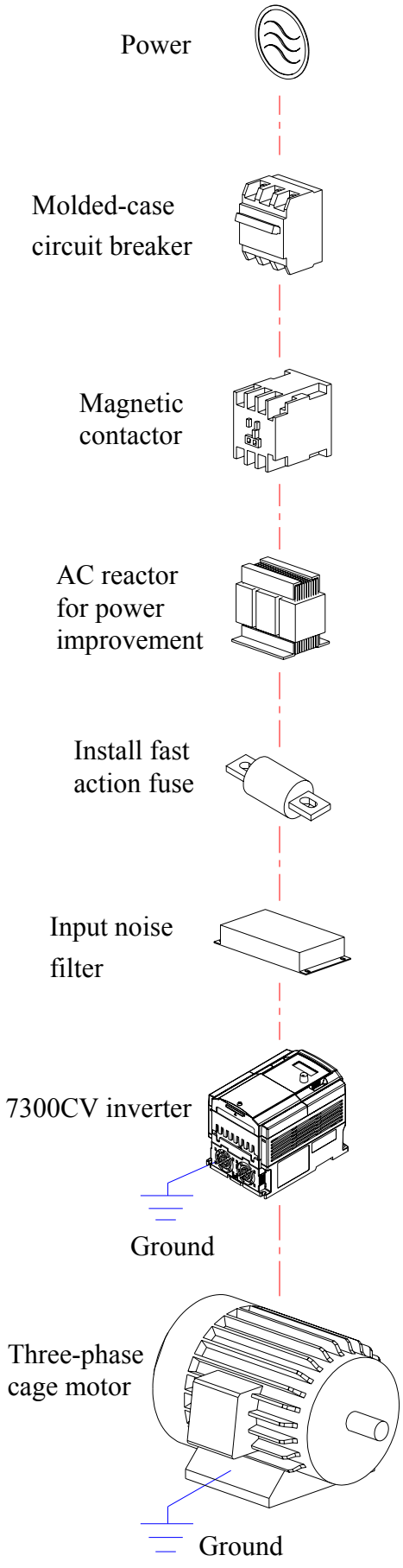
- Teco bears no responsibility to service for failures caused by the following conditions:
  (1) A molded-case circuit breaker is not installed, or an improper or overrated breaker is used, between the power source and the inverter.
  (2) A magnetic contactor, a phase capacitor, or a burst absorber is connected between the inverter and the motor.

7300CV model	JNTHBCBA□□□□AC / JNTHBCBA□□□□BC											
	R500	0001	0002	0003	0005	7R50	0010	0015	0020	0025	0030	0040
Molded-case circuit breaker made by Teco	TO-50E 10A	TO-50E 20A	TO-50E 30A	TO-50E 30A	TO-50E 30A	TO-50E 50A	TO-100S 60A	TO-100S 100A	TO-100S 100A	TO-225S 150A	TO-225S 175A	TO-225S 175A
Magnetic contactor (MC) made by Teco	CN-11				CN-16	CN-18	CN-25	CN-50	CN-65	CN-80	CN-100	CN-125
Main circuit terminals (TM1)	Wire gauge 2.0 mm^2			Wire gauge 3.5 mm^2		Wire gauge 5.5 mm^2		Wire gauge 14 mm^2	Wire gauge 22 mm^2		Wire gauge 38mm^2	Wire gauge 60mm^2
Signal terminals (TM2)	Wire gauge 0.75mm^2 (# 18 AWG)											

7300CV model	JNTHBCBA□□□□BE										
	0001/ 0002/ 0003/ 0005	7R50	0010	0015	0020	0025	0030	0040	0050	0060	0075
Molded-case circuit breaker made by Teco	TO-50E 15A	TO-50E 20A	TO-50E 30A	TO-50E 50A	TO-100S 50A	TO-100S 75A	TO-100S 100A	TO-100S 100A	TO-125S 125A	TO-225S 175A	TO-225S 175A
Magnetic contactor (MC) made by Teco	CN-11	CN-16	CN-18	CN-25	CN-35	CN-50	CN-50	CN-65	CN-80	CN-100	CN-125
Main circuit terminals (TM1)	Wire gauge 2.0mm^2	Wire gauge 3.5mm^2		Wire gauge 5.5mm^2	Wire gauge 8mm^2		Wire gauge 14mm^2	Wire gauge 22mm^2		Wire gauge 38mm^2	Wire gauge 60mm^2
Signal terminals (TM2)	Wire gauge 0.75mm^2 (# 18 AWG), terminal screw M3										

- Use three-phase cage induction motor with capacity suitable for the inverter.
- One inverter is driving several motors, the total current of all motors running simultaneously must be less than the rated current of the inverter, and each motor has to be equipped with a proper thermal relay.
- Do not add capacitive component, such as a phase capacitor, LC or RC, between the inverter and the motor.

3.3.3 Precautions for peripheral applications:



Power supply:

- Make sure the voltage applied is correct to avoid damaging the inverter.
- A molded-case circuit breaker must be installed between the AC source and the inverter

Molded-case circuit breaker:

- Use a molded-case circuit breaker that conforms to the rated voltage and current of the inverter to control the power ON/OFF and protect the inverter.
- Do not use the inverter as the switch for run/stop switch.

Leakage breaker:

- Install a leakage breaker to prevent error operation caused by electric leakage and to protect operators
- Setting current should be 200mA or above and the operating time at 0.1 second or longer to prevent malfunction.

Magnetic contactor:

- Normal operations do not need a magnetic contactor. But a contactor has to be installed in primiary side when performing functions such as external control and auto restart after power failure, or when using brake controller.
- Do not use the magnetic contactor as the run/stop switch of the inverter.

AC reactor for power improvement:

- When inverters below 200V/400V 15KW are supplied with high capacity (above 600KVA) power source or an AC reactor can be connected to improve the power performance.

Install fast action fuse:

- To ensure the safety of peripheral devices, please install the fast action fuse. Regarding the specification, please refer to P3-4.

Input noise filter:

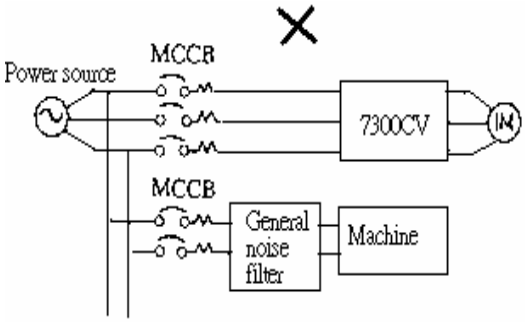
- A filter must be installed when there are inductive load around the inverter

Inverter:

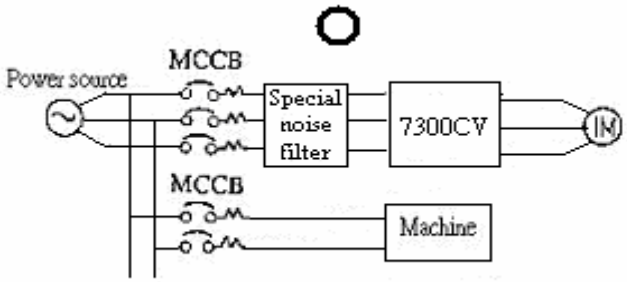
- Input power terminals L1, L2, and L3 can be used in any sequence regardless of phases.
- Output terminals T1, T2, and T3 are connected to U, V, and W terminals of the motor. If the motor is reversed while the inverter is forward, just swap any two terminals of T1, T2, and T3.
- To avoid damaging the inverter, do not connect the input terminals T1, T2, and T3 to AC power.
- Connect the ground terminal properly. 200 V series: class 3 grounding, <100Ω; 400 V series : <10Ω.

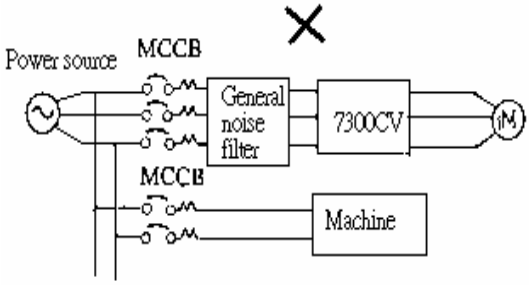
Make external connections according to the following instruction. Check connections after wiring to make sure all connections are correct. (Do not use the control circuit buzzer to check connections)

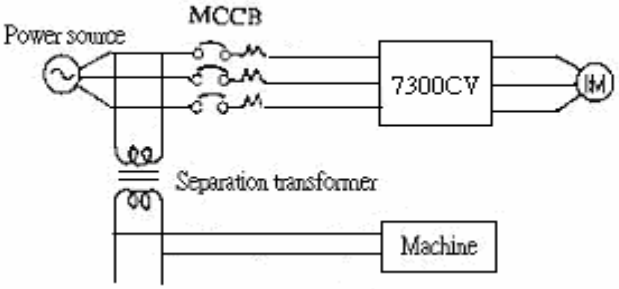
- The inverter uses dedicated power line A general noise filter may not provide rightful results



- Add a noise filter or separation transformer whenter shares the power line with other machines.
- the inverter shares the power line with other machines.

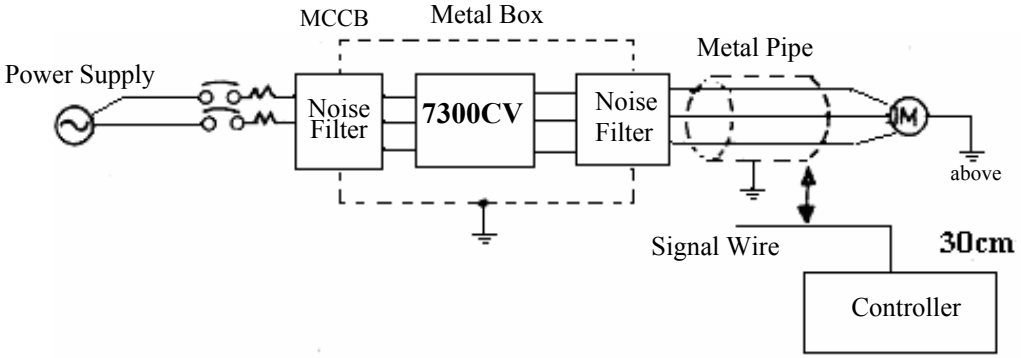






(A) Main circuit's wiring must separate from other high voltage or high current power line to avoid noise interference. Refer to the figures below:

- A noise filter in the output of the main circuit can suppress conductive noise. To prevent radiative noise, the wires should be put in a metal pipe and distance from signal lines of other control machines for more than 30 cm.

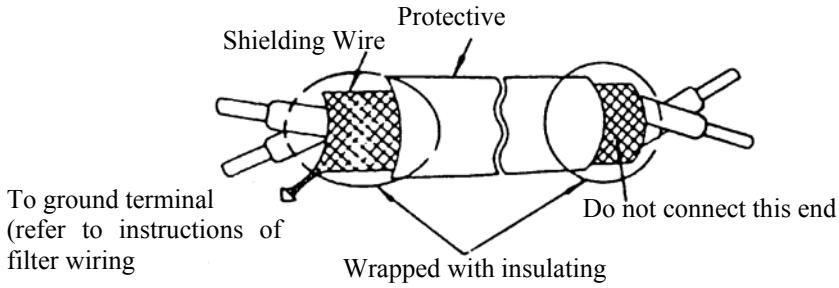


- When the connection between the inverter and the motor is too long, consider the voltage drop of the circuit. Phase-to-phase voltage drop (V) = $\sqrt{3}$ ×resistance of wire (Ω/km)×length of line (m)×current×10^{-3}. And the number of carriers must be adjusted based on the length of the line.

The length of the line between the inverter and the motor	Below 25m	Below 50m	Below 100m	Over 100m
Number of carriers allowed	Below 16KHz	Below 12KHz	Below 8KHz	Below 5KHz
Settings of 3-22parameter	16	12	8	5

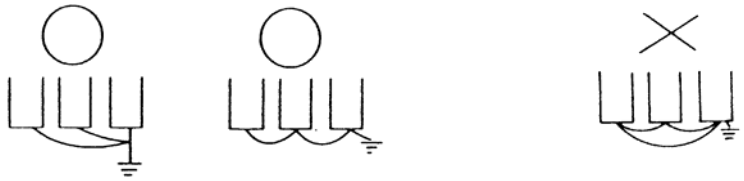
(B) The wiring of the control circuit must be separated and routed away from the main circuit control line or other high voltage or current power lines to avoid noise interference

- To avoid error actions caused by noise interference, shield the control circuit wiring with a twisted wire, and connect the shielded wire to a ground terminal. Refer to the figure below.
  The wiring distance should not exceed 50 m.



(C) Ground the ground terminal of the inverter properly. For 200V class ground 100Ω or less; for 400V class ground 10Ω or less.

- Ground wiring is based on the electrical equipment technical basis (AWG). The shorter, the better.
- Do not share the ground of the inverter to other high current loads (welding machine, high power motor). Connect the terminals to ground respectively.
- Do not make a loop when several inverters share a common ground point.



(a) **Good** (b) **Good** (c) **Bad**

(D) To ensure maximum safety, use proper wire gauges (AWG) for the main power circuit and control circuit according to relative regulations.

(E) After wiring, check that the wiring is correct, wires are intact, and terminal screws are secured.

3.4 Specifications

3.4.1 Products Individual Specifications

Single phase, 200-240V model

JNTHBCBA□□□□AC-U(F)	R500	0001	0002	0003
Horsepower(HP)	0.5	1	2	3
Suitable Motor Capacity(KW)	0.4	0.75	1.5	2.2
Rated Output Current(A)	3.1	4.5	7.5	10.5
Rated Capacity(KVA)	1.2	1.7	2.9	4.0
Max. Input Voltage	Single Phase: 200~240V +10% -15% , 50/60H_Z ± 5%			
Max. Output Voltage	Three Phases: 0~240V			
Input Current(A)	8.5	12	16	23.9
Net Weight(KG)	1.2(1.3)	1.2(1.3)	1.5(1.8)	1.9(2.3)
Allowable momentary power loss time (second)	1.0	1.0	2.0	2.0

Three phases, 200 – 240V model

JNTHBCBA□□□□BC-U	R500	0001	0002	0003	0005	7R50	0010	0015	0020	0025	0030	0040
Horsepower(HP)	0.5	1	2	3	5	7.5	10	15	20	25	30	40
Suitable Motor Capacity(KW)	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30
Rated Output Current(A)	3.1	4.5	7.5	10.5	17.5	26	35	48	64	80	96	130
Rated Capacity(KVA)	1.2	1.7	2.9	4.0	6.7	9.9	13.3	20.6	27.4	34	41	54
Max. Input Voltage	Three Voltage: 200~240V +10% -15% , 50/60H_Z ± 5%											
Max. Output Voltage	Three Voltage: 0~240V											
Input Current(A)	4.5	6.5	11	12.5	20.5	33	42	57	70	85	108	138
Net Weight(KG)	1.2	1.2	1.2	1.75	1.9	5.6	5.6	15	15	15	33	34
Allowable momentary power loss time (second)	1.0	1.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0

Three phases, 380 – 480V model

JNTHBCBA□□□□BE-U(F)	0001	0002	0003	0005	7R50	0010	0015	0020	0025	0030	0040	0050	0060	0075
Horsepower(HP)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75
Suitable Motor Capacity(KW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
Rated Output Current(A)	2.3	3.8	5.2	8.8	13.0	17.5	25	32	40	48	64	80	96	128
Rated Capacity(KVA)	1.7	2.9	4.0	6.7	9.9	13.3	19.1	27.4	34	41	54	68	82	110
Max. Input Voltage	Three Voltage:380~480V +10% -15% , 50/60H_Z ± 5%													
Max. Output Voltage	Three Voltage: 0~480V													
Input Current(A)	4.2	5.6	7.3	11.6	17	23	31	38	48	56	75	92	112	142
Net Weight(KG)	1.2 (1.3)	1.2 (1.3)	1.8 (2.2)	1.8 (2.2)	5.6 (6.6)	5.6 (6.6)	5.6 (6.6)	15	15	15	33	33	50	50
Allowable momentary power loss time (second)	1.0	1.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0

NOTE1: DC Reactor is built-in for 30hp above in 200V class series.

NOTE2: DC Reactor is built-in for 40hp above in 400V class series.

3.4.2 General Specifications

Item		7300CV TYPE
Control Mode		V/F or Current Vector Control
Frequency Control	Range	0.1~650.0 Hz
	Start control torque	150%/1Hz (Current Vector)
	Speed control range	1:50 (Current Vector)
	Speed Control Precision	±0.5% (Current Vector)
	Setting resolution	Digital: 0.01Hz(Note *1): Analog: 0.06Hz/ 60Hz(10bits)
	Keypad setting	Set directly with▲▼ keys or the VR on the keypad
	Display Function	Four digital LED (or 2×16 LCD) and status indicator; display frequency/ speed/ line speed/ DC voltage/ Output voltage/ Current/ Rotation direction/ Inverter parameter/ Trouble Log/ Program Version
	External signal setting	1. External variable resistor/ 0-10V/ 0-20mA/ 10-0V/ 20-0mA 2. Performs up/down controls, speed control or automatic procedure control with multifunctional contacts on the terminal block (TM2)
	Frequency Limit Function	Respectively setting upper/lower frequency limits and three-stage prohibited frequencies
General Control	Carrier frequency	2 ~ 16 kHz
	V/F pattern	18-fixed patterns, 1 programmable pattern
	Acc/Dec control	Two-stage Acc/Dec time (0.1 – 3,600 seconds) and two-stage S curves (refer to descriptions on 3-05)
	Multifunctional analog output	6 functions (refer to description on 8-00/8-01)
	Multifunctional input	30 functions (refer to description on 5-00~5-06)
	Multifunctional output	16 functions (refer to description on 8-02~8-03)
	Digital Input Signal	NPN (SINK) / PNP (SOURCE) toggle
	Other Function	Momentary Power Loss Restart, Speed Search, Overload Detection, 8 preset speeds (PLC use 16 preset speeds). Acc/Dec Switch (2 Stages), S Curves, 3-wire Control, PID control, torque boost, Slip Compensation, Frequency Upper/ Lower Limit, Auto energy saving, Modbus slave and PC/PDA Link, Auto Restart, Built-in Simple PLC Function.

Item		7300CV TYPE
Communication Control		1. Control by RS232 or RS485 2. One to one or One to more (RS485 ONLY) control. 3. BAUD RATE/STOP BIT/PARITY/bit can be set
Braking Torque		About 20%, the model built-in braking transistor and connected braking resistor is 100%
Operation temperature		-10 ~ 50℃(note 2)
Storage temperature		-20 ~ 60℃
Humidity		0 – 95% Relative Humidity(Non-condense)
Height		Below 1000M
Vibration Sustention		1G (9.8m/s^2)
EMC		Comply with requirement EN 61800-3 (with optional Filter).
LVD		Comply with requirement EN 50178
Enclosure		IP00 or IP20 (NEMA 1 by external box attached)
Safety Level		UL 508C
Protective Functions	Overload protection	The relays to protect the motor (the curve can be set) and the inverter (150 % / 1min)
	FUSE protection	The motor stops after FUSE melt
	Over Voltage	200V class：DC Voltage > 410V 400V class：DC Voltage > 820V
	Under Voltage	200V class：DC Voltage < 190V 400V class：DC Voltage < 380V
	Momentary Power Loss Restart	Stop for more than 15ms-power-loss can be restarted with spin start after momentary power loss in Max 2 sec.
	Stall Prevention	Stall prevention for Acceleration/ Deceleration/ Operation.
	Short-circuit output terminal	Electronic Circuit Protection
	Grounding Fault	Electronic Circuit Protection
	Other Function	Protection for overheating of heat sink, over torque detection, error contact control, reverse restriction, restrictions for direct start after power up and error recovery, parameter lock up.

Note 1: The setting resolution of above 100Hz is 0.1Hz when controlled with operation keypad, and 0.01 Hz when controlled using computer PC or programmable controller (PLC).

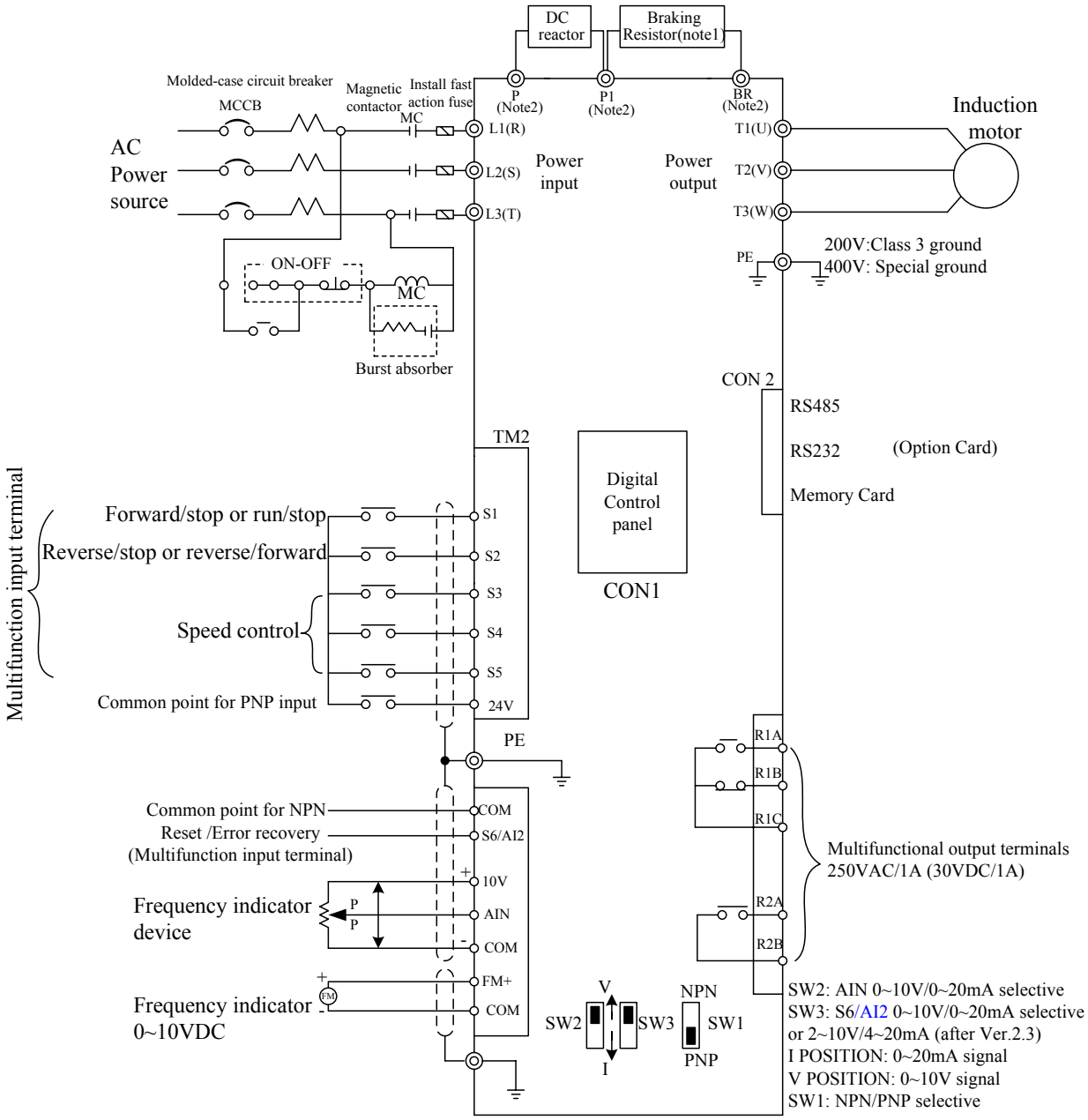
Note 2: –10 ~ 50℃ in distributor (without dustproof cover)

–10 ~ 40℃ outside distributor (with dustproof cover)

Note 3: 220V 15HP and above capacity are not CE complied

3.5 Wiring diagram 7300CV series inverter

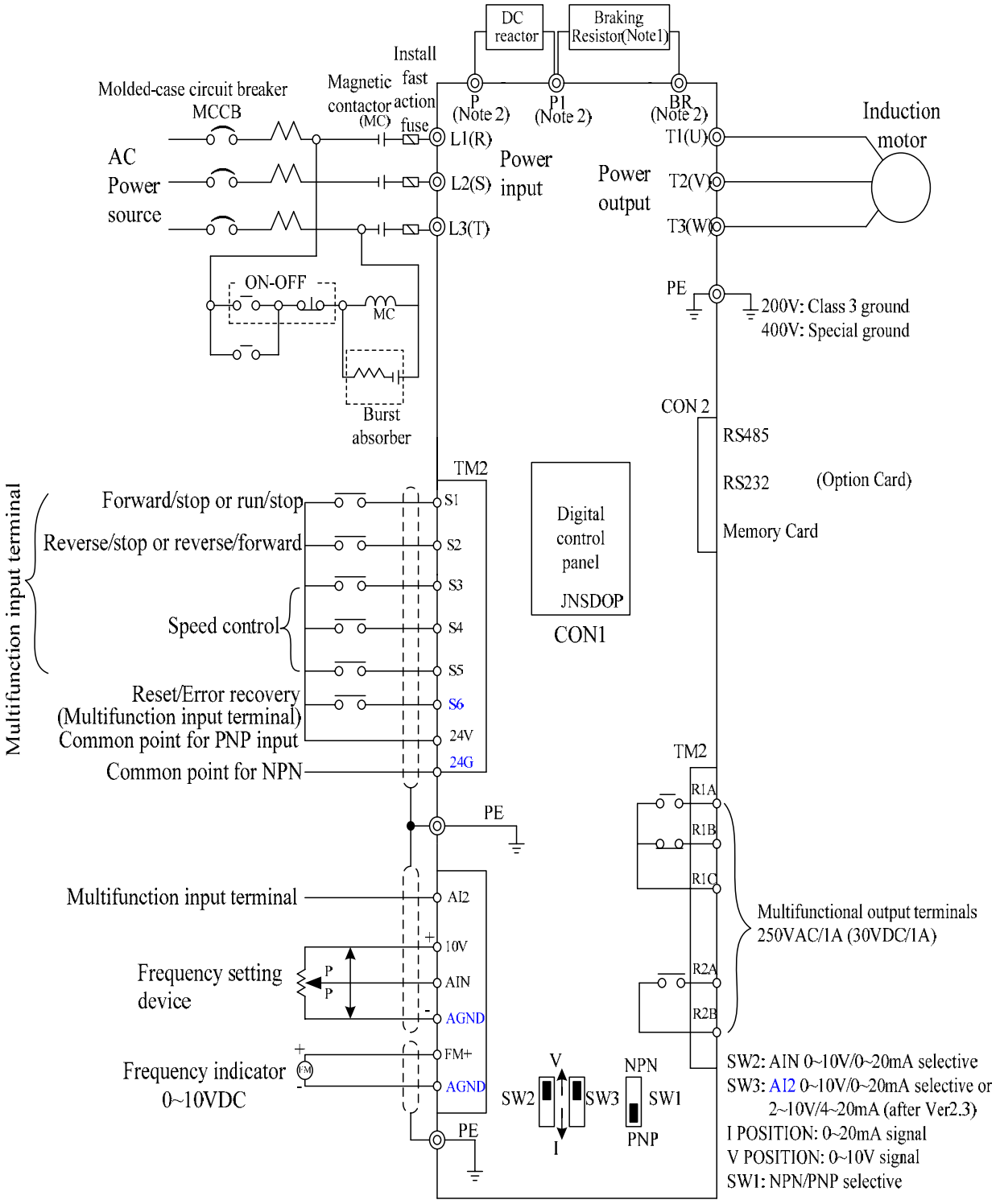
Wiring diagram I:



Note 1: Please refer to description of main circuit terminals (P1, BR) and specification of braking resistor for value selection.

Note 2: Above wiring diagram refers for 0.4~1.5KW at 220V and 0.75~1.5KW at 440V only.

Wiring diagram II:



Note 1: Please refer to description of main circuit terminals (P1, BR) and specification of braking resistor for value selection.

Note 2: Above wiring diagram refers for 2.2~7.5KW at 220V and 2.2~11KW at 440V only.

3.6 Description of terminals of troubleshooting inverter

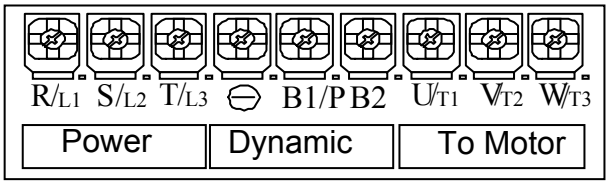
Descriptions of main circuit terminals

Symbol	Description		
R / L1 (L)	Main power input	Single-phase: L/N Three-phase: L1/L2/L3	
S / L2			
T / L3 (N)			
P1	Braking resistor or connecting terminal: Used in cases where the inverter frequently disconnects due to large load inertia or short deceleration time (refer to specifications of braking resistor)		For 220V:0.5~10HP, 440V:1~15HP
BR			
P1/ P	DC reactor connecting terminals		
B1/P	●B1/P- ⊖: DC power supply input B1/P-B2: External braking resistor For 220V: 15~20HP and 440V: 20HP		-
B2			
⊖			●⊕- ⊖: DC power supply input or External braking unit. Check Chapter 6.3 For 220V: 25~40HP and 440V: 25~75HP
⊕	-		
U / T1	Inverter outputs		
V / T2			
W / T3			

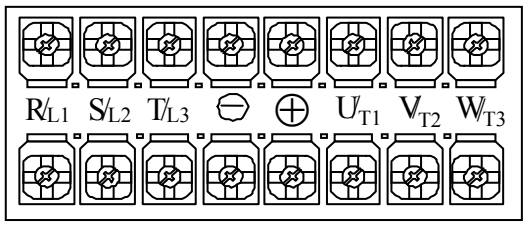
Descriptions of 7300CV control circuit terminals

Symbol	Description		
R2A	Multifunctional terminal – Normal open		Contact rated capacity: (250VAC/1A or 30VDC/1A) Contact using description:(refer to 8-02, 8-03)
R2B			
R1C	Common contact	Multifunctional output terminals	
R1B	Normal close contact		
R1A	Normal open contact		
10V	Frequency knob (VR) power source terminal (pin 3)		
AIN	Analog frequency signal input terminal or multifunction input terminals S7 (H level:>8V, L level:<2V, PNP only) (refer to5-06 description)		
24V	Common contact for S1~S5 (S6, S7) in PNP (Source) input. Shift to PNP position (refer to wiring diagram) of SW1 when used PNP input		
COM 24G AGND	1. Common contact and analog input /output signal for S1~S5 in NPN (Sink) input. Shift to NPN position (refer to wiring diagram I) of SW1 when used NPN input. 2. AGND for AIN,AI2 and FM+ (analog input /output signal) & 24G for S1~S6 (digital input /output signal in NPN (Sink) input). Shift to NPN position (refer to wiring diagram II) of SW1 when used NPN input.		
FM+	The positive analog output for multifunction (refer to 8-00 description), the signal for output terminal is 0-10VDC (below 2mA).		

. 220V: 15 ~ 20 HP 440V: 20HP

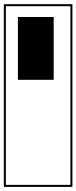
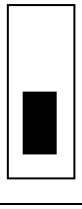


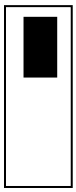
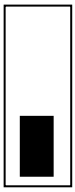
. 220V: 25 ~ 40HP 440V: 25~75HP



Symbol	Function Description
S1	Multifunction input terminals(refer to 5-00 ~ 5-04 description) (S5 = Encoder input terminal, the Encoder voltage range: 19.2V~24.7V)
S2	
S3	
S4	
S5	
S6	1. Multifunction input terminals (Digital terminal H level:>8V, L level:<2V, PNP only) or analog input terminal AI2(0~10Vdc/4~20mA)(refer to 5-05 description) 2. The V2.9 version (contains) above the edition, S6 only is the Multi-function input terminal use, AI2 have replaced S6 to take analog input use. (Above wiring diagram refers for 2.2~7.5KW at 220V and 2.2~11KW at 440V only.)

Descriptions of SW function

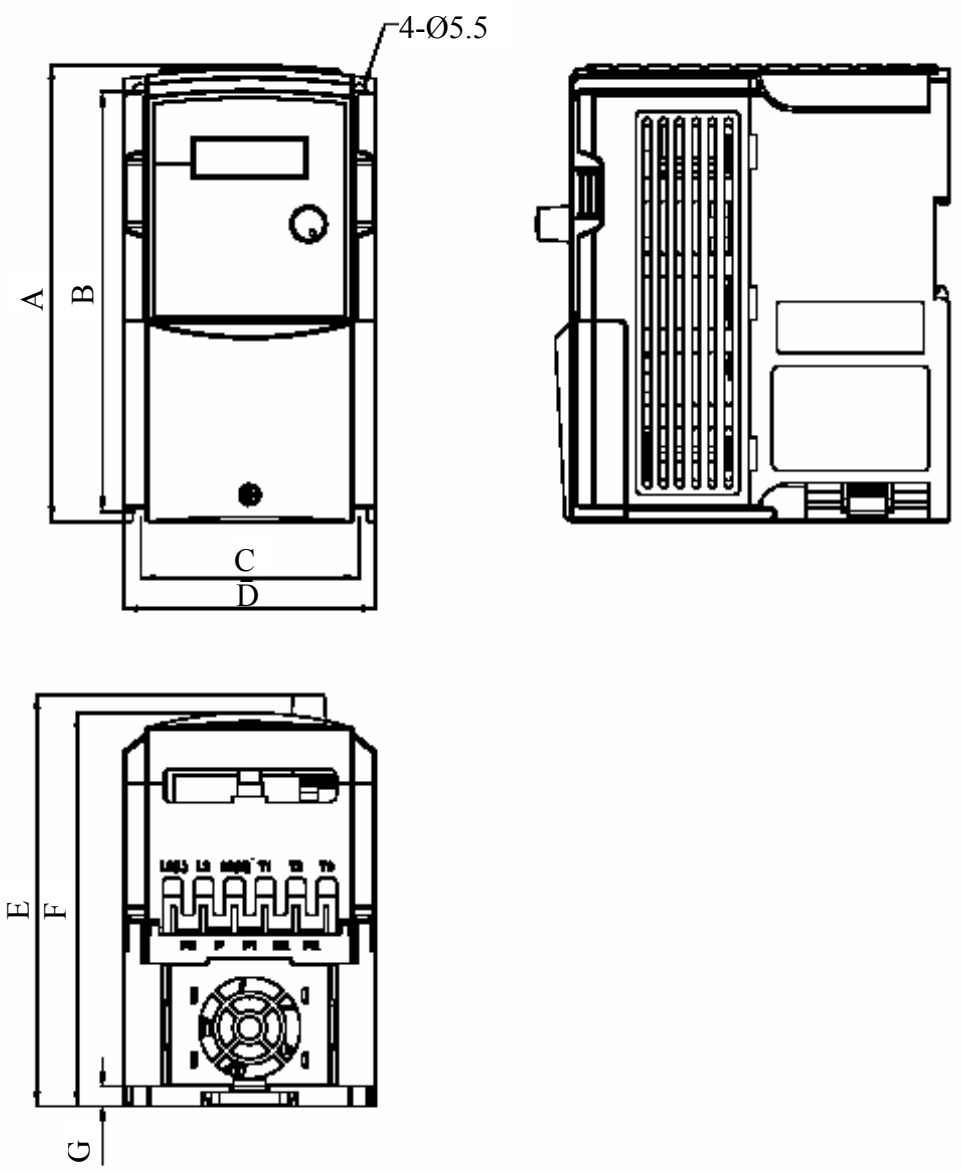
SW2/SW3	Type of external signal	Remarks
	0~10VDC analog signal	(1) External control is available as 1-06=0002 (2) Factory setting is voltage input
	0~20mA analog signal	

SW1	Type of external signal	Remarks
	NPN (SINK) input	
	PNP (SOURCE) input	Factory default

3.7 Outline Dimensions

(1) Frame1 : Single phase JNTHBCBA__AC: R500, 0001
Three phase JNTHBCBA__BC/BE: R500, 0001, 0002

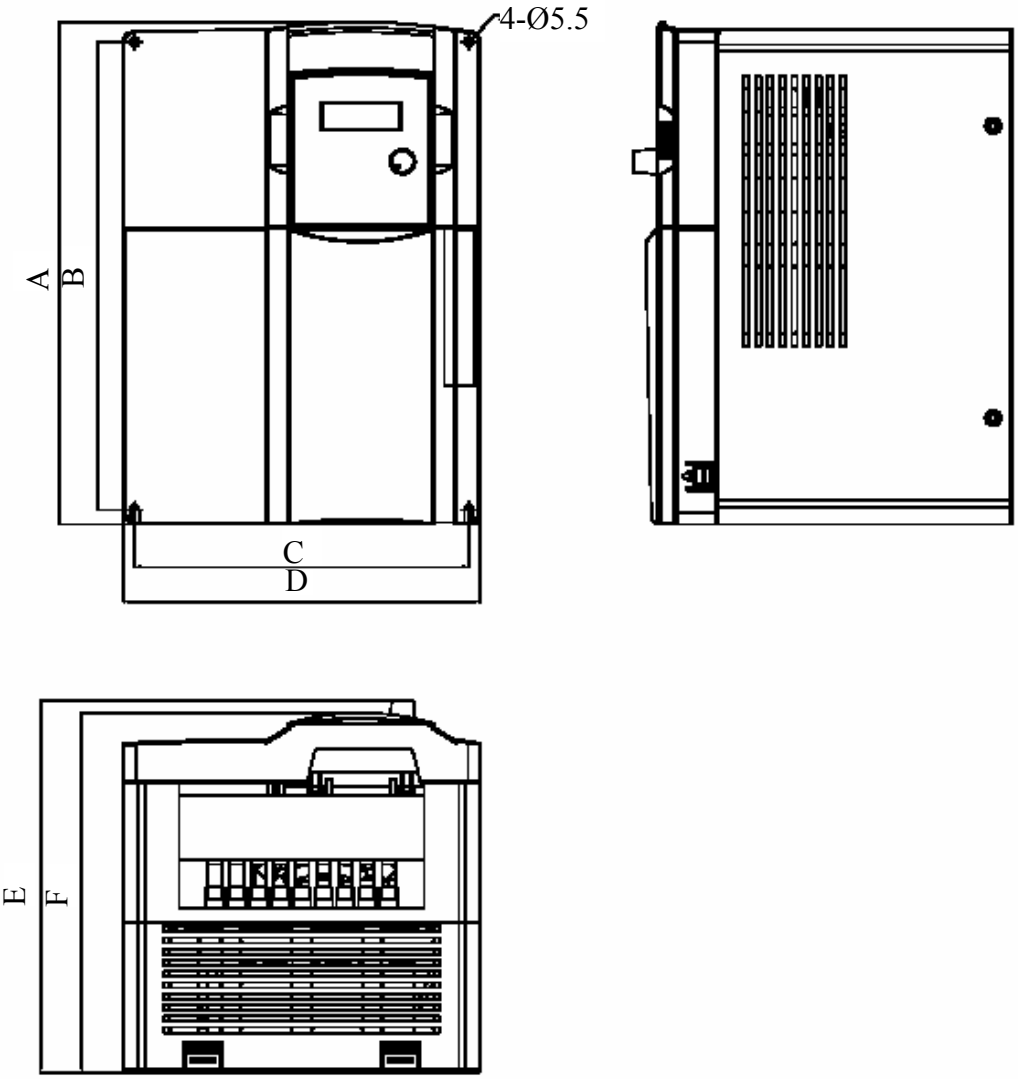
(2) Frame2 : Single phase JNTHBCBA__AC: 0002, 0003
Three phase JNTHBCBA__BC/BE: 0003, 0005



Unit : mm/inch

LENGTH / MODEL	A	B	C	D
Frame 1	163/6.42	150/5.9	78/3.07	90/3.54
Frame 2	187.1/7.36	170.5/6.71	114.6/4.51	128/5.04
LENGTH / MODEL	**E**	**F**	**G**	
Frame 1	147/5.79	141/5.55	7/0.28	
Frame 2	148/5.83	142.1/5.59	7/0.28	

(3) Frame3 : Three phase JNTHBCBA__BC: 7R50, 0010
JNTHBCBA __BE: 7R50, 0010, 0015

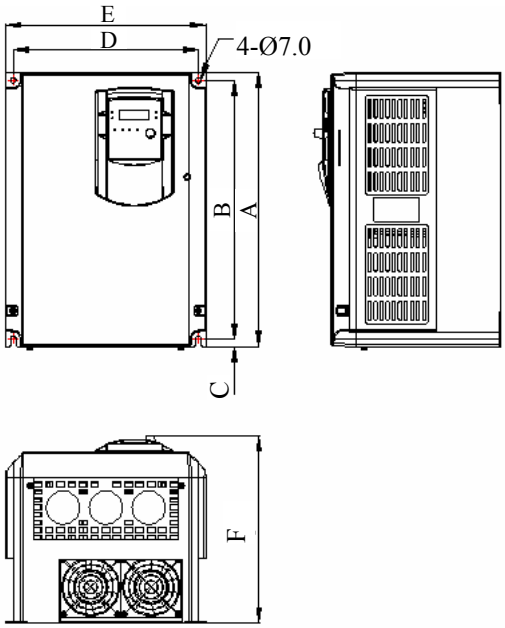


Unit : mm/inch

LENGTH / MODEL	A	B	C	D	E	F
Frame 3	260/10.24	244/9.61	173/6.81	186/7.32	195/7.68	188/7.4

(4) Frame4 : Three phase JNTHBCBB __ BC: 0015, 0020, 0025

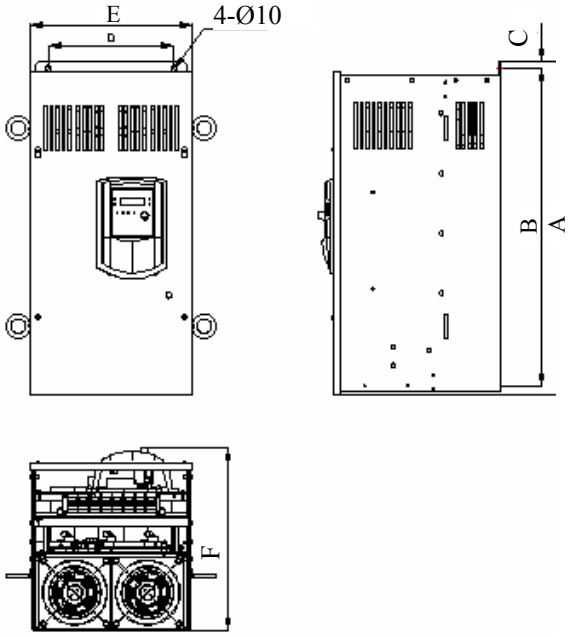
JNTHBCBB __ BE: 0020, 0025, 0030



(5) Frame5 : Three phase JNTHBCBA __ BC: 0030, 0040

JNTHBCBA __ BE: 0040, 0050

(6) Frame6 : Three phase JNTHBCBA __ BE: 0060, 0075



(Open Chassis Type - IP00) Unit : mm/inch

LENGTH / MODEL	A	B	C	D	E	F
Frame4	360/14.2	340/13.4	10/0.4	245/9.6	265/10.4	247.5/9.7
Frame5	553/21.8	530/20.9	10/0.4	210/8.3	269/10.6	303.6/12
Frame6	653/25.7	630/24.8	10/0.4	250/9.8	308/12.1	308.6/12.1

Chapter 4 Software Index

4.1 Keypad Description

4.1.1Keypad Display and Operation Instruction

1. SEQ LED：1_00 =1/2/3, LED Lit.

2. FRQ LED：1_06 = 1/2/3/4, LED Lit

3. FWD LED：Forward Direction, LED action(Flash in stop, Keep Lit in operation).

4. REV LED：Reverse Direction, LED action(Flash in stop, Keep Lit in operation).

5. Four action of FUN、Hz/RPM、VOLT、AMP LED and display of four 7-segment display, refer to operation description of the keypad.
6. LCD keypad without FUN, Hz/RPM, VOLT, AMP LED and FREQ.SET knob.

⚠ Caution
To avoid impairing the keypad, do not operate it with screwdriver or sharp and hard tool.

Remote/Local Mode

.Local mode – Operation Command by RUN/STOP key on keypad

– Frequency Command by ▲▼ key on keypad

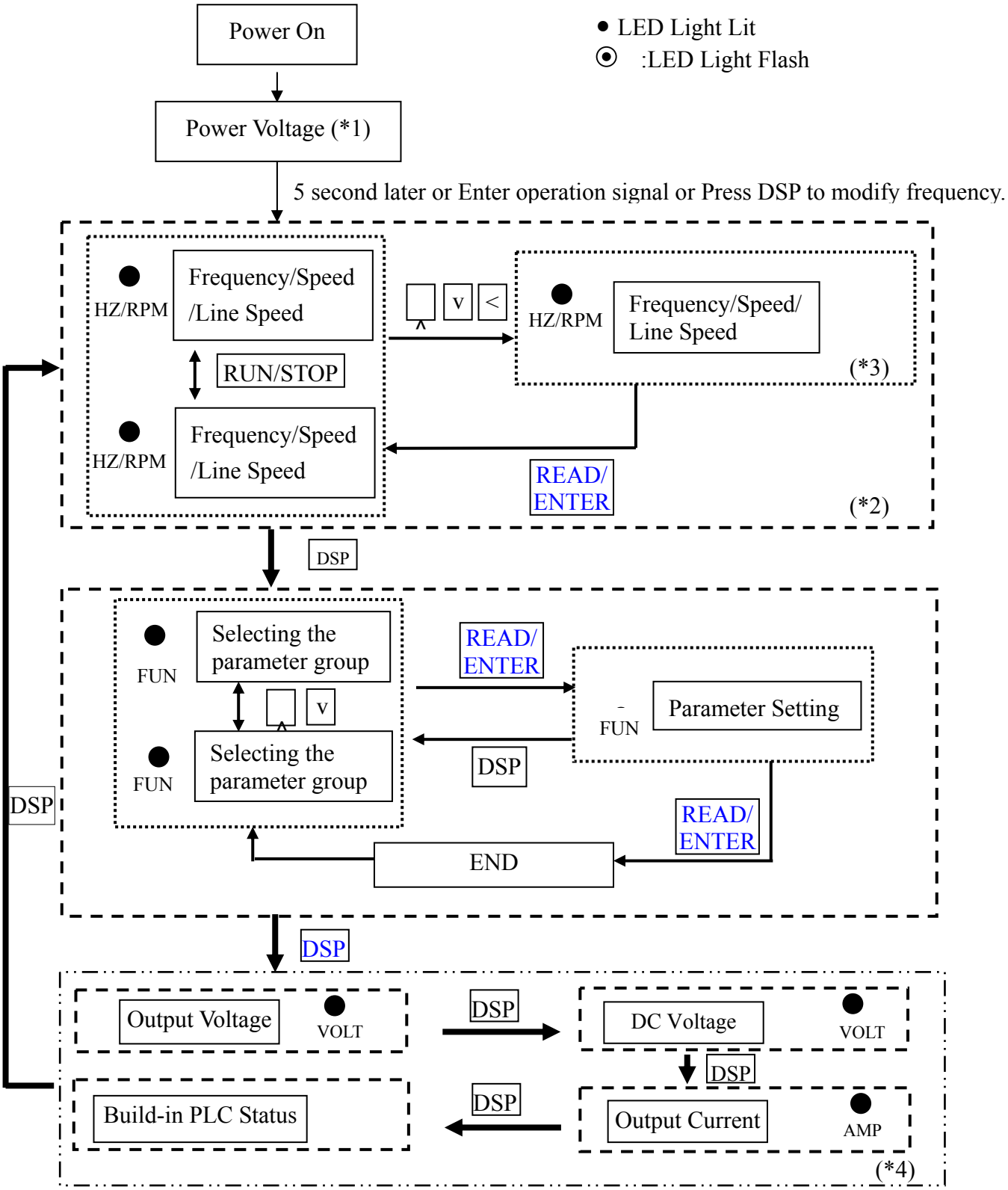
.Remote mode – Operating Command by 1-00

– Frequency Command by 1-06

To Change the Remote/Local mode, you must push FWD/REV and 《/RESET key at the same time.

The Remote /Local mode of change can used in STOP mode, it can't used in Run mode.

4.1.2 Operation Instruction of the keypad

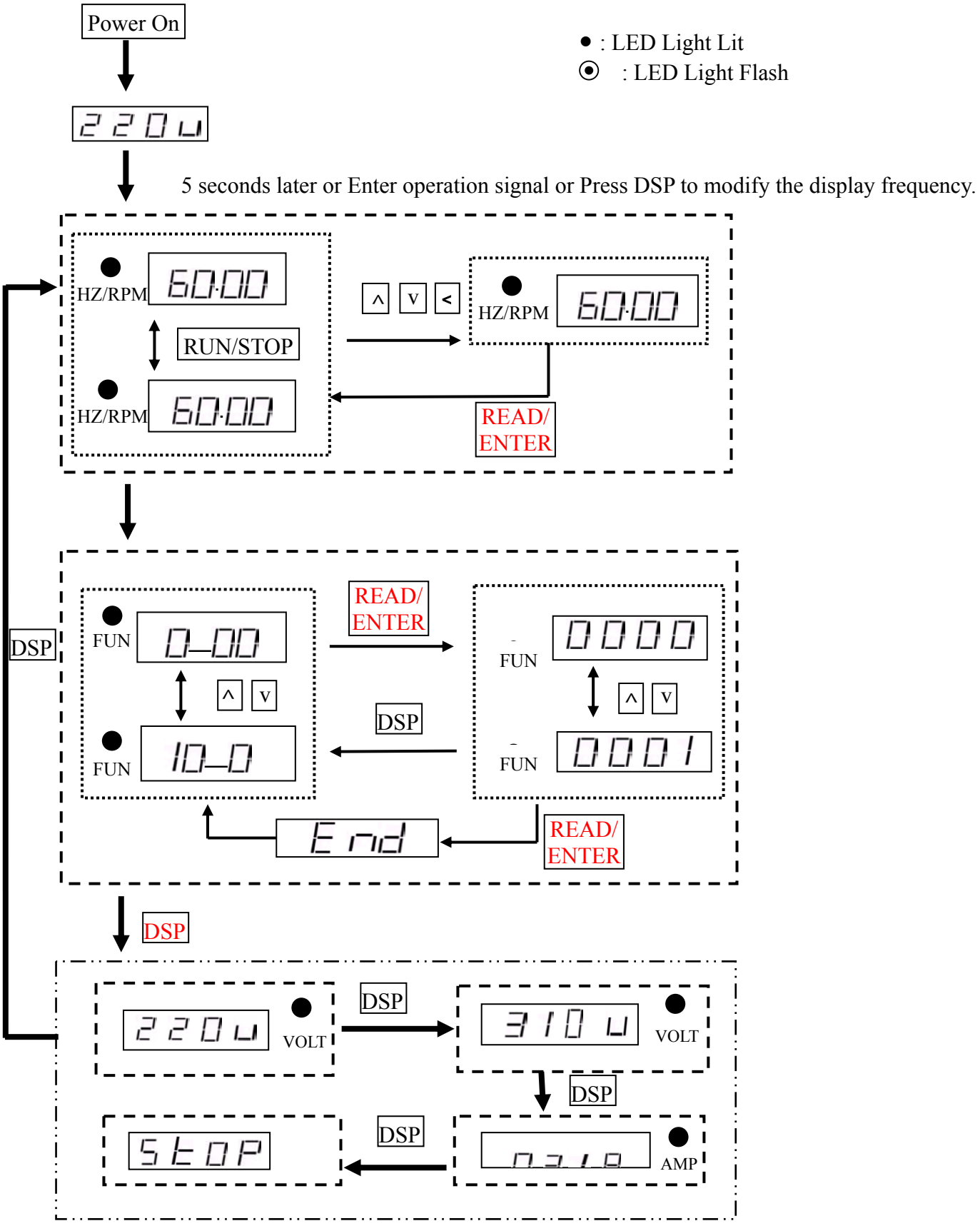


*1：The inverter will flash the current setting of 0-07 (power supply voltage) after power up.

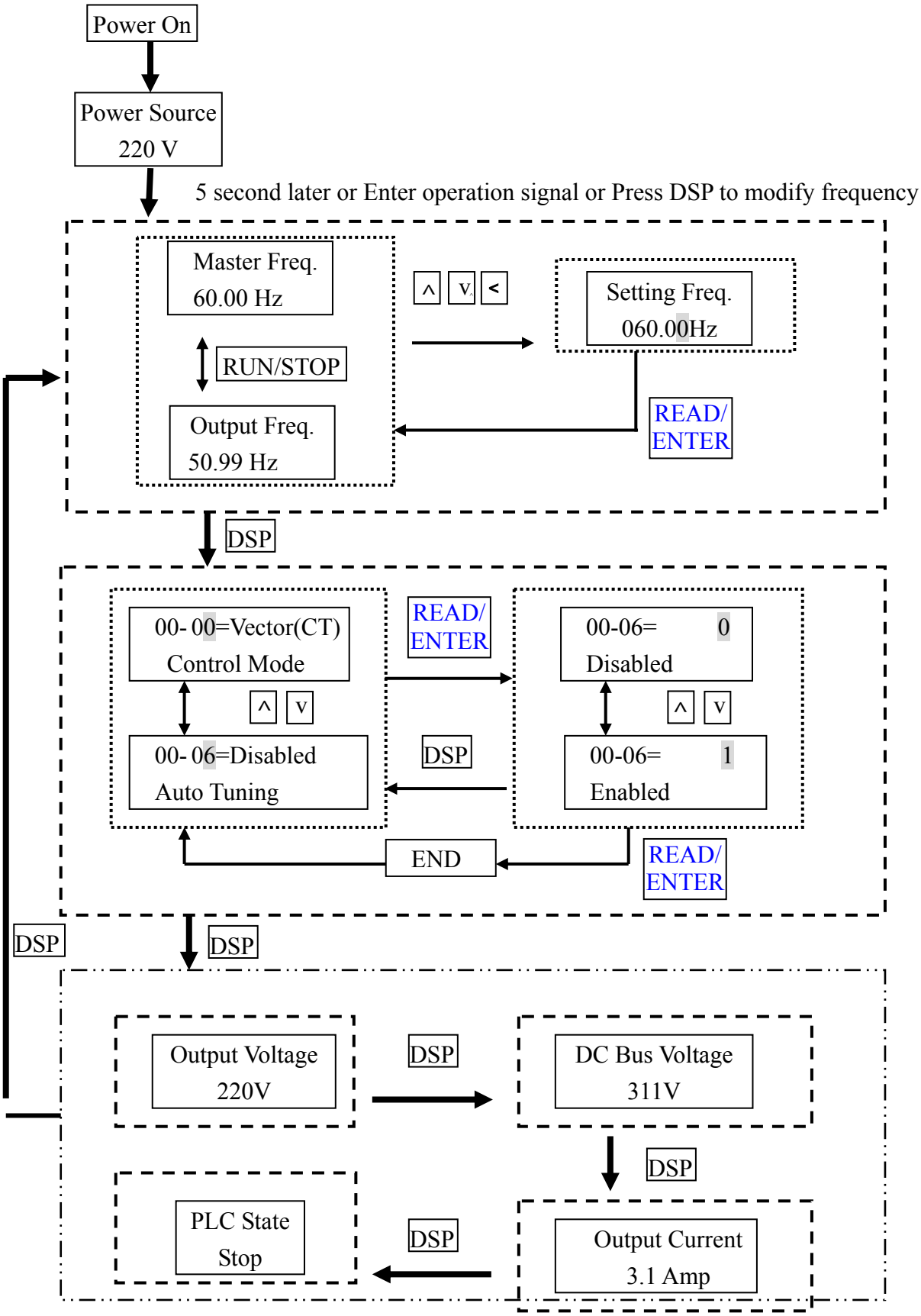
*2：4-04, 4-05 determines the displaying of frequency, speed or line speed.

*3：It is not necessary to press ENTER key when stopped for modification. Refer to example 1, 2.

4.1.3 Operation Instruction of the LED keypad

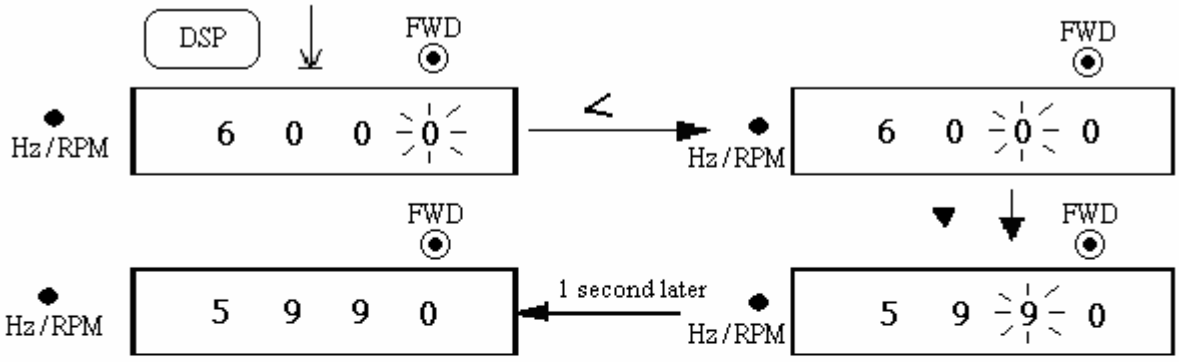


4.1.4 Operation Instruction of the LCD keypad

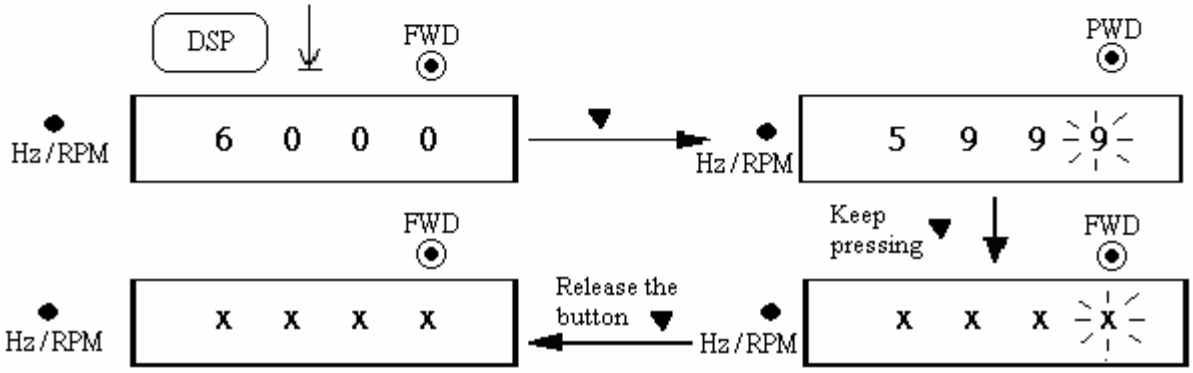


4.1.5 Keypad Operating Example

Example 1. Modify frequency in stopping

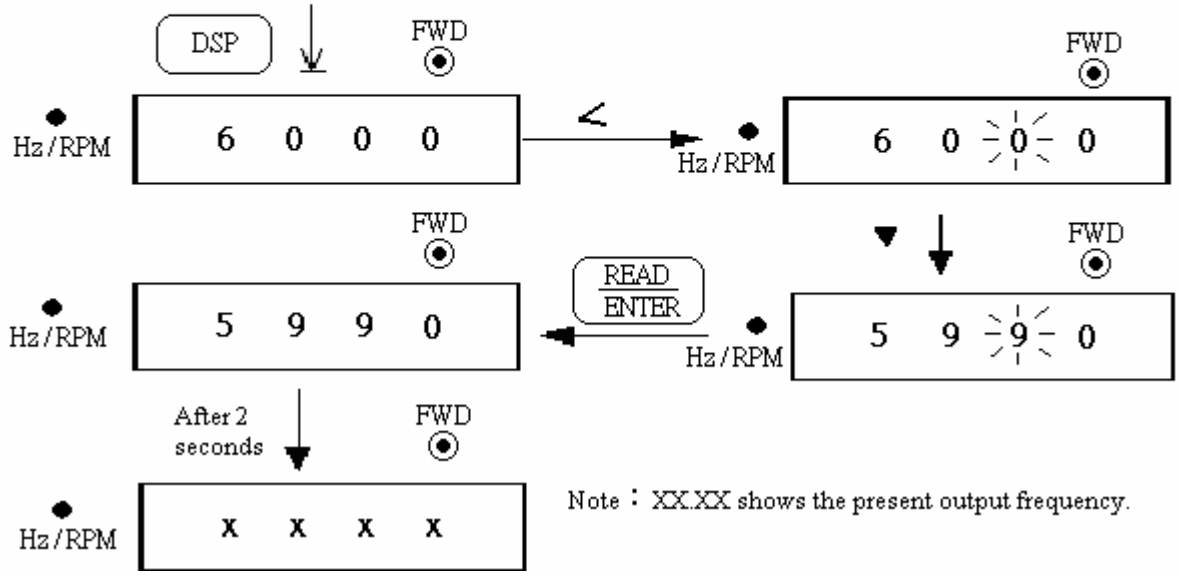


Example 2. Modify frequency in operating



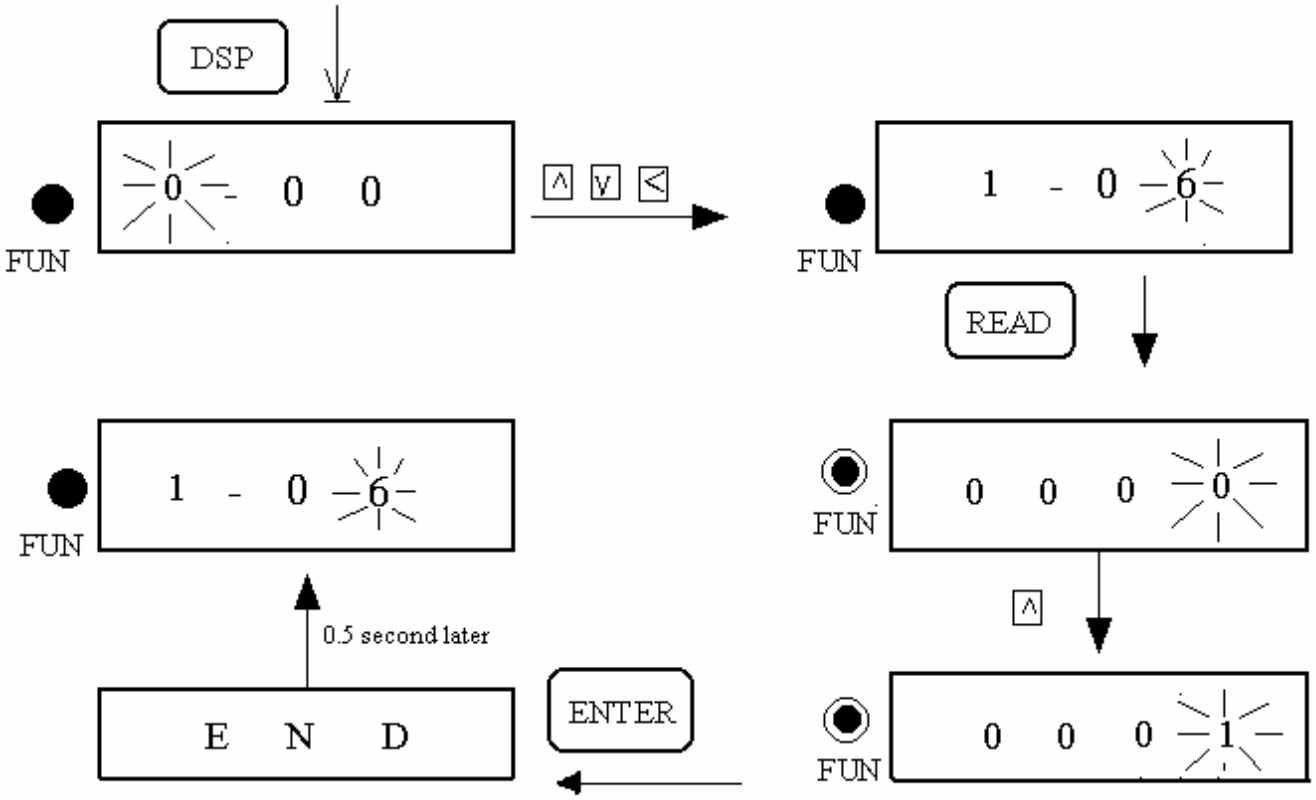
Note：XX.XX shows the present output frequency. The value ranges from 59.58 to 0 Hz, depending on the length of time the key ▼ pressed.

Example 3. Modify frequency in running

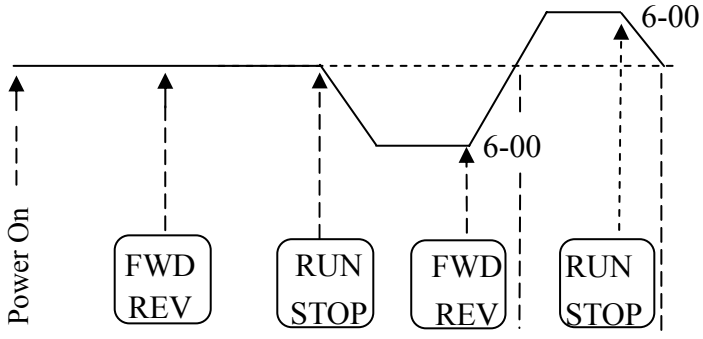


Note：XX.XX shows the present output frequency.

Example4. Modify the Value of Parameter



Example 5. Operation Control



FWD LED	⊙	○	○	●	⊙
REV LED	○	⊙	●	○	○

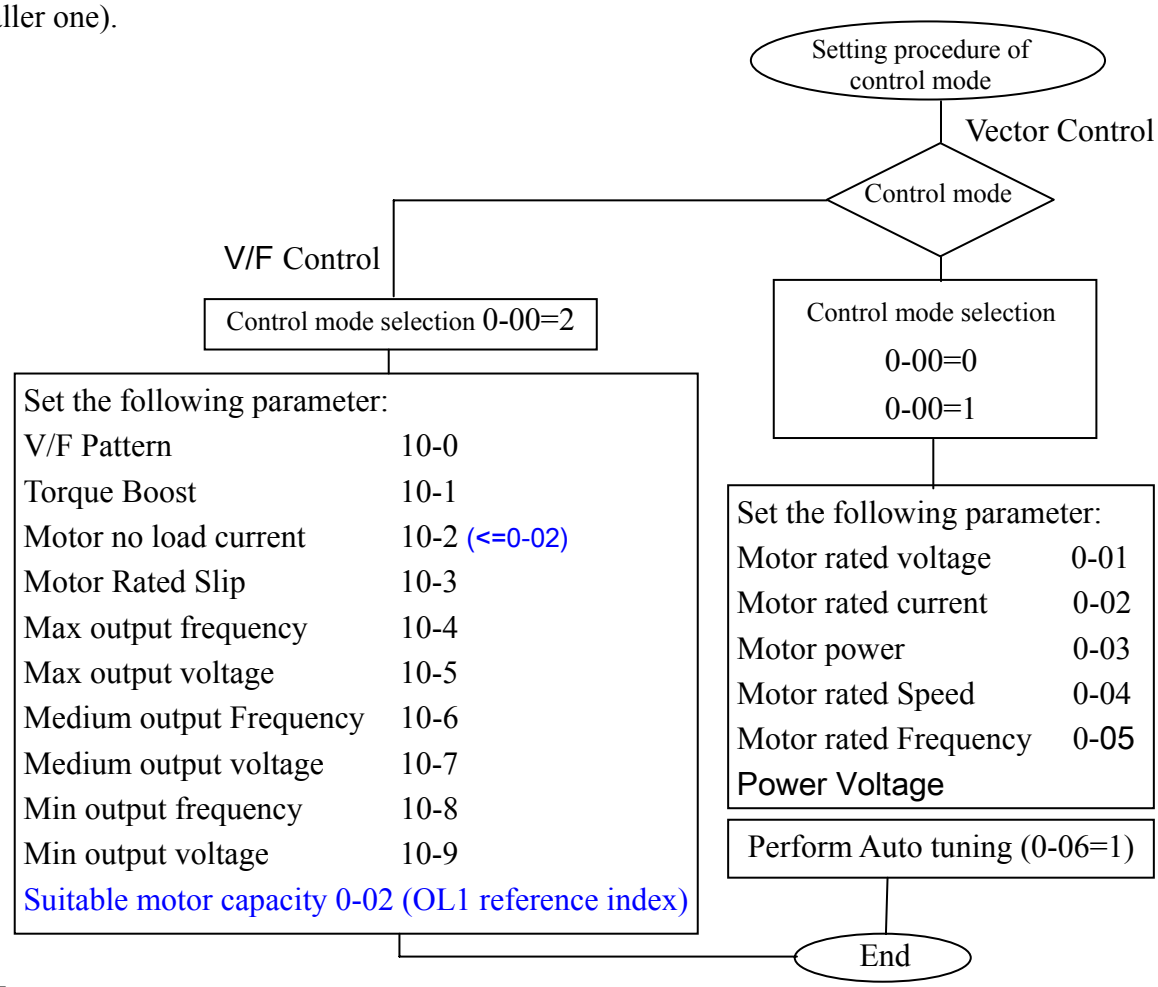
●: LED Lit ⊙: LED Flash ○: LED Go Out

4.2 Control Mode Selection

7300CV Series inverter has three control modes:

1. General Vector Control Mode
2. VT Vector Control Mode (Special for Blower, Pump).
3. V/F Control Mode。

The user can choose these modes with the digital keypad according to the application characteristics. The factory setting is general vector control mode. Before operation, please set the control mode and the relative parameters of the motor in accordance with the following flow chart. (The Vector control mode only suits for the inverter with same capacity comparing to the motor, or a grade bigger or smaller one).



※Note:

1. Use V/F Control Mode:
   (1) Use one inverter to drive several motors simultaneously
   (2) Motor's nameplate is unknown or motor's specifications are too special, it will cause Auto-tuning fault.
   (3) Specification of inverter and motor differ more than 1 class.
2. One inverter drives several motors (Only V/F mode available), set the motor parameter complying with the following rules:
   (1). As for the current, sum the rated current of all motors.
   (2). As for others, input correct VF Pattern parameter (10-4~10-9).
3. When the nameplate of the motor is unknown, the inverter will set the internal parameter according to the standard TECO motor.

4. When parameter 0-00 does set to 2, the keypad will display ‘Err2’ in performing Auto tuning.
5. When VF control, 0-01~0-05 max. & min. value by the TECO standard motor specification limit(one more & one less level). When VF control, no district.

4.3 7300CV Programmable Functions List

Parameter Group No.	Description
0-	Drive Operation Mode
1-	Start/Stop and Frequency Control Modes
2-	Manual/Automatic Restart Modes
3-	Operating Parameters
4-	Digital Display Operation Mode
5-	Multifunction Input Terminals (MFIT)
6-	Jog, and Preset (MFIT) Speed Setting on Keypad
7-	Analog Input Signal Operation
8-	Multifunction Output Relays and Output Signal Operation
9-	Drive and Load Protection Modes
10-	Volts/Hz Pattern Operation Mode
11-	PID Operation Mode
12-	PID "Limits" and "Out of Range" Mode
13-	Communication Mode
14-	Motor Auto-Tuning Parameters
15-	Drive Status and Function Reset

0- Drive Operation Mode

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
0-00	(Control Mode)	Control Mode	0000: Vector (General Purpose) 0001: Vector (Variable Torque) 0002: Volts/Hz (Refer to Parameter Group 10- Volts/Hz Mode)	0000	*3
0-01	(Motor Rated Volt)	Motor Rated Voltage (Vac)	-----		*3*5
0-02	(Motor Rated Amp)	Motor Rated Current (Amp)	-----		*3*5
0-03	(Motor Rated KW)	Motor Rated Power (kW)	-----		*3*5
0-04	(Motor Rated RPM)	Motor Rated Speed (RPM)X100*7	-----		*3*5
0-05	(Motor Rated Hz)	Motor Rated Frequency (Hz)	-----		*3*5
0-06	(Auto Tuning)	Motor Parameter Auto Tuning	0000: Invalid 0001: Valid	0000	
0-07	(AC Input Volt)	AC Line Input Voltage (Vac)	220V SERIES:170.0~264.0 440V SERIES:323.0~528.0		*3
0-08	(Select Language)	Language Selection	0000: English 0001: German 0002: French 0003: Italian 0004: Spanish	0000	Only for LCD keypad

1- Start/Stop and Frequency Control Modes

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
1-00	(Run Source)	Run Command Source Selection	0000: Keypad 0001: External Run/Stop Control (See 1-01) 0002: Communication 0003: Built-In PLC	0000	
1-01	(MFIT Run Mode)	Run/Stop-Forward/Reverse Operation Mode with External Terminals	0000: Forward/Stop-Reverse/Stop 0001: Run/Stop-Forward/Reverse 0002: 3-Wire Control Mode-Run/Stop	0000	
1-02	(Reverse Oper)	Prohibition of Reverse operation	0000: Enable Reverse Command 0001: Disable Reverse Command	0000	
1-03	(Keypad Stop)	Keypad Stop Button	0000: Stop Button Enabled 0001: Stop Button Disabled	0000	
1-04	(Starting Method)	Starting Method Selection	0000: Normal Start 0001: Enable Speed Search	0000	
1-05	(Stopping Method)	Stopping Method Selection	0000: Controlled Deceleration-to-Stop with DC Injection Braking (Rapid Stop) 0001: Free run Stop		

1-06	(Frequency Source)	Frequency Command Source Selection	0000: Keypad 0001: Potentiometer on Keypad 0002: External Analog Signal Input or Remote Potentiometer 0003: Up/Down Frequency Control Using MFIT (S1 - S6) 0004: Communication setting frequency 0005: Impulse (S5) setting frequency (ver2.3)	0000	
1-07	(Keypad Up/Down)	Keypad Operation with Up/Down Keys in Run Mode	0000: 'Enter' must be pressed after frequency change with Up/Down Keys on keypad. 0001: Frequency will be changed directly when Up/Down Keys are Pressed	0000	

2- Manual/Automatic Restart Modes

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
2-00	(PwrL Selection)	Momentary Power Loss and Restart	0000: Momentary power loss and restart disable 0001: Momentary power loss and restart enable 0002: Momentary power loss and restart enable while CPU is operating. (According to the capacity of DC power)	0000	
2-01	(PwrL Ridethru T)	Momentary Power Loss Ride-Thru Time (Seconds)	0.0 - 2.0	0.5	
2-02	(Delay of Restart)	Auto Restart Delay Time (Seconds)	0.0 - 800.0	0.0	
2-03	(Num of Restart)	Number of Auto Restart Attempts	0 - 10	0	
2-04	(Auto Restart)	Auto Restart Method	0000: Enable Speed Search 0001: Normal Start	0000	
2-05	(Direct Start Sel)	Direct Running After Power Up	0000: Enable Direct running after power up 0001: Disable Direct running after power up	0000	
2-06	(Delay-on Timer)	Delay-ON Timer (Seconds)	0.0-300.0	0.0	
2-07	(Reset Mode Sel)	Reset Mode Setting	0000: Enable Reset Only when Run Command is Off 0001: Enable Reset when Run Command is On or Off	0000	
2-08	(KEB_Decel_Time)	Kinetic Energy Back-up Deceleration Time	0.0:Disable 0.1~25.0: KEB Deceleration Time	0.0	

3- Operating Parameters

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
3-00	(Freq Upper Limit)	Frequency Upper Limit (Hz)	0.01 - 650.00	50.00 / 60.00	*4
3-01	(Freq Lower Limit)	Frequency Lower Limit (Hz)	0.00 - 650.00	0.00	
3-02	(Accel Time 1)	Acceleration Time # 1 (Seconds)	0.1 – 3600.0	10.0	*1
3-03	(Decel Time 1)	Deceleration Time # 1 (Seconds)	0.1 – 3600.0	10.0	*1
3-04	(S-Curve 1)	S-Curve Acc/Dec # 1 (Seconds)	0.0 - 4.0	0.2	
3-05	(S-Curve 2)	S-Curve Acc/Dec # 2(Seconds)	0.0 - 4.0	0.2	
3-06	(Accel Time 2)	Acceleration Time # 2 (MFIT) (Seconds)	0.1 – 3600.0	10.0	*1
3-07	(Decel Time 2)	Deceleration Time # 2 (MFIT) (Seconds)	0.1 – 3600.0	10.0	*1
3-08	(Jog Acc Time)	Jog Acceleration Time (MFIT) (Seconds)	0.1 - 25.5	0.5	*1
3-09	(Jog Dec Time)	Jog Deceleration Time (MFIT) (Seconds)	0.1 - 25.5	0.5	*1
3-10	(DCInj Start Freq)	DC Injection Brake Start Frequency (Hz)	0.1 - 10.0	1.5	
3-11	(DCInj Level)	DC Injection Brake Level (%)	0.0 – 20.0	5.0	*7
3-12	(DCInj Time)	DC Injection Brake Time (Seconds)	0.0 - 25.5	0.5	
3-13	(Skip Freq 1)	Skip Frequency # 1 (Hz)	0.00 - 650.00	0.0	*1
3-14	(Skip Freq 2)	Skip Frequency # 2 (Hz)	0.00 - 650.00	0.0	*1
3-15	(Skip Freq 3)	Skip Frequency # 3 (Hz)	0.00 - 650.00	0.0	*1
3-16	(Skip Bandwidth)	Skip Frequency Bandwidth(± Hz)	0.00 - 30.00	0.0	*1
3-17	(Parameter Lock)	Parameter Lock	0000: Enable all Functions 0001: 6-00 - 6-08 cannot be changed 0002: All Functions Except 6-00 - 6-08 cannot be changed 0003: Disable All Function	0000	
3-18	(ROM Pack Operate)	Copy Unit	0000: Disable 0001: Inverter to Copy Unit 0002: Copy Unit to Inverter 0003: Verify	0000	
3-19	(Fan Control)	Fan Control	0000: Auto (Depend on temp.) 0001: Operate while in RUN mode 0002: Always Run 0003: Always Stop	0000	
3-20	(Energy Save Mode)	Energy Saving Mode *[1]	0000: Disabled 0001: Controlled by MFIT at Set Frequency	0000	*6
3-21	(Energy Save Gain)	Energy Saving Gain (%)*[1]	0 - 100	80	*6
3-22	(Carrier Freq)	Carrier Frequency (kHz)	2 - 16	10	
3-23	reserved				

3-24	reserved				
3-25	reserved				
3-26	reserved				
3-27	reserved				
3-28	reserved				
3-29	reserved				

※ Notes: 1. Energy Saving Mode is available only under Volts/Hz Mode (0-00 = 0002).

4- Digital Display Operation Mode

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
4-00	(Motor Curr Disp)	Motor Current Display Selection	0000: Disable Motor Current Display 0001: Enable Motor Current Display	0000	*1
4-01	(Motor Volt Disp)	Motor Voltage Display Selection	0000: Disable Motor Voltage Display 0001: Enable Motor Voltage Display	0000	*1
4-02	(Bus Volt Disp)	DC Bus Voltage Display Selection	0000: Disable Bus Voltage Display 0001: Enable Bus Voltage Display	0000	*1
4-03	(PLC Status Disp)	PLC Status Display Selection	0000: Disable PLC Status Display 0001: Enable PLC Status Display	0000	*1
4-04	(Display Scaling)	Custom Units (Line Speed) Value	0 - 9999	1800	*1
4-05	(Display Units)	Custom Units (Line Speed) Display Mode	0000: Drive Output Frequency is Displayed 0001: Line Speed is Displayed in Integer (xxxx) 0002: Line Speed is Displayed with One Decimal Place (xxx.x) 0003: Line Speed is Displayed with Two Decimal Places (xx.xx) 0004: Line Speed is Displayed with Three Decimal Places (x.xxx)	0000	*1
4-06	(PID Feed Disp)	PID Feedback Display Selection	0000: Disable PID Feedback Display 0001: Enable PID Feedback Display	0000	*1

5- Multifunction Input Terminals (MFIT)

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks

5-00	(MFIT S1 Sel)	Multifunction Input Term. S1	0000: Forward/Stop Command *1 0001: Reverse/Stop Command *2 0002: Preset Speed # 1 (6-02) 0003: Preset Speed # 2 (6-03) 0004: Preset Speed # 3 (6-05) *3 0005: Jog 0006: Acc/Dec # 2 0007: Emergency Stop A Contact 0008: Base Block 0009: Speed Search 0010: Energy Saving 0011: Control Signal Selection 0012: Communication Selection 0013: Acc/Dec Disabled 0014: Up Command 0015: Down Command 0016: Master/Auxiliary Speed 0017: PID Function Disabled 0018: Reset 0019: Encoder input terminal (terminal S5) 0020: PID feedback signal A12 (terminal S6) 0021: AI2 Bias signal 1 input (terminal S6) 0022: AI2 Bias signal 2 input (terminal S6) 0023: Analog input (terminal AIN) 0024: PLC Application 0025: Traverse Run 0026: Traverse run upper deviation 0027: traverse run lower deviation 0028: Power Source Detect for KEB Function 0029: Emergency Stop B Contact *7	0000	
5-01	(MFIT S2 Sel)	Multifunction Input Term. S2		0001	
5-02	(MFIT S3 Sel)	Multifunction Input Term. S3		0002	
5-03	(MFIT S4 Sel)	Multifunction Input Term. S4		0003	
5-04	(MFIT S5 Sel)	Multifunction Input Term. S5		0004	
5-05	(MFIT S6 Sel)	Multifunction Input Term. S6		0018	
5-06	(MFIT AIN Sel)	Multifunction Input Term. AIN		0023	
5-07	(MFIT Scan Time)	Multifunction Input Term. S1 - S6 Signal Verification Scan Time (mSec X 4)	1 – 100	5	

5-08	(Stop Sel by MFIT)	Stop Mode Using MFIT	0000: When the MFITs are Programmed for Up/Down Frequency Control, the Set Frequency will remain when the Drive stops. And when the Drive stops, Up/Down Function Disabled. 0001: Up/Down is used. The preset frequency is reset to 0 Hz as the inverter stops. 0002: When the MFITs are Programmed for Up/Down Frequency Control, the Set Frequency will remain when the Drive stops. And when the Drive stops, Up/Down Function Enabled. *7	0000	
5-09	(Step Up/Down Fun)	Step of Up/Down Function (Hz)	0.00 – 5.00	0.00	
5-10	(Pulse Inp. Mult.)	Encoder Impulse Ratio	0.001 – 9.999	1.000	*7
5-11	(Ref.Source2)	Select the source of auxiliary frequency command	0 - 4	0	*7

※Notes: 1. To switch to Run/Stop with Function 1-01 = 0001.
2. To switch to Forward/Reverse with Function 1-01 = 0001.
3. Preset Speed # 3 is obtained by activating Terms. S3 and S4 simultaneously.

6- Jog, and Preset (MFIT) Frequency Setting on Keypad

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
6-00	(Keypad Freq)	Keypad Frequency (Hz)	0.00 - 650.00	5.00	*1
6-01	(Jog Freq)	Jog Frequency (Hz)	0.00 - 650.00	2.00	*1
6-02	(Preset Speed #1)	Preset Speed # 1 (Hz)	0.00 - 650.00	5.00	*1
6-03	(Preset Speed #2)	Preset Speed # 2 (Hz)	0.00 - 650.00	10.00	*1
6-04	(Preset Speed #3)	Preset Speed # 3 (Hz)	0.00 - 650.00	20.00	*1
6-05	(Preset Speed #4)	Preset Speed # 4 (Hz)	0.00 - 650.00	30.00	*1
6-06	(Preset Speed #5)	Preset Speed # 5 (Hz)	0.00 - 650.00	40.00	*1
6-07	(Preset Speed #6)	Preset Speed # 6 (Hz)	0.00 - 650.00	50.00	*1
6-08	(Preset Speed #7)	Preset Speed # 7 (Hz)	0.00 - 650.00	60.00	*1

7- Analog Input Signal Operation

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
7-00	(AIN Gain)	AIN Gain (%)	0 - 200	100	*1
7-01	(AIN Offset)	AIN Bias (%)	0 - 100	0	*1
7-02	(AIN Bias)	AIN Bias Selection	0000: Positive 0001: Negative	0000	*1
7-03	(AIN Slope)	AIN Slope	0000: Positive 0001: Negative	0000	*1
7-04	(AIN Scan Time)	AIN Signal Verification Scan Time (AIN, AI2) (mSec x 2)	1 - 100	50	

7-05	(AI2 Gain)	AI2 Gain (%)(S6)	0 - 200	100	*1

※ Notes: Group 7 is available when 5-06=0023 (AIN term.=Analog input)

8- Multifunction Output Relays and Output Signal Operation

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
8-00	(AO Mode Sel)	Analog Output Voltage Mode (0 - 10 VDC, Term. FM+)	0000: Output Frequency 0001: Frequency Setting 0002: Output Voltage 0003: DC Voltage 0004: Output Current 0005: PID Feedback *7	0000	*1
8-01	(AO Gain)	Analog Output Gain (%)	0 - 200	100	*1
8-02	(Relay R1 Sel)	Output Relay R1 Operation Mode	0000: Run 0001: Frequency Reached (Frequency Command) (Set Frequency ± 8-05) 0002: Set Frequency (8-04 ± 8-05) 0003: Frequency Threshold Level (> 8-04) - Frequency Reached 0004: Frequency Threshold Level (< 8-04) - Frequency Reached 0005: Over torque Threshold Level 0006: Fault 0007: Auto Restart 0008: Momentary AC Power Loss 0009: Rapid Stop Mode 0010: Coast-to-Stop Mode 0011: Motor Overload Protection 0012: Drive Overload Protection 0013: PID Feedback Signal Loss 0014: PLC Operation 0015: Power On *7	0006	
8-03	(Relay R2 Sel)	Output Relay R2 Operation Mode		0000	
8-04	(Freq Agree)	Frequency Reached (Hz) (Refer to 8-02: 0001)	0.00 - 650.00	0.00	*1
8-05	(Freq Agree width)	Frequency Reached Bandwidth (± Hz)	0.00 - 30.00	2.00	*1

9- Drive and Load Protection Modes

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
9-00	(Trip ACC Sel)	Trip Prevention Selection During Acceleration	0000: Enable Trip Prevention During Acceleration 0001: Disable Trip Prevention During Acceleration	0000	
9-01	(Trip ACC Level)	Trip Prevention Level During Acceleration (%)	50 - 300	200	
9-02	(Trip DEC Sel)	Trip Prevention Selection During Deceleration	0000: Enable Trip Prevention During Deceleration 0001: Disable Trip Prevention During Deceleration	0000	

9-03	(Trip DEC Level)	Trip Prevention Level During Deceleration (%)	50 - 300	200	
9-04	(Trip RUN Sel)	Trip Prevention Selection in Run Mode	0000: Enable Trip Prevention in Run Mode 0001: Disable Trip Prevention in Run Mode	0000	
9-05	(Trip Run Level)	Trip Prevention Level In Run Mode (%)	50 - 300	200	
9-06	(Dec Sel Trip RUN)	Trip Prevention Deceleration Time Selection in Run Mode	0000: Trip Prevention Deceleration Time Set by 3-03 0001: Trip Prevention Deceleration Time Set by 9-07	0000	
9-07	(Dec Time Trip RUN)	Deceleration Time In Trip Prevention Mode (Seconds)	0.1 – 3600.0	3.0	
9-08	(Motor OL1 Sel)	Electronic Motor Overload Protection Operation Mode	0000: Enable Electronic Motor Overload Protection 0001: Disable Electronic Motor Overload Protection	0000	
9-09	(Motor Type)	Motor type Selection	0000: Electronic Motor Overload Protection Set for Non-Inverter Duty Motor 0001: Electronic Motor Overload Protection Set for Inverter Duty Motor	0000	
9-10	(Motor OL1 Curve)	Motor Overload Protection Curve Selection	0000: Constant Torque (OL =103 %) (150 % for 1 Minute) 0001: Variable Torque (OL = 113 %) (123 % for 1 Minute)	0000	
9-11	(Motor OL1 Operat)	Operation After Overload Protection is Activated	0000: Coast-to-Stop After Overload Protection is Activated 0001: Drive Will Not Trip when Overload Protection is Activated (OL1)	0000	
9-12	(Torq Det Sel)	Over torque Detection Selection	0000: Disable Over torque Operation 0001: Enable Over torque Operation Only if at Set Frequency 0002: Enable Over torque Operation while the Drive is in Run Mode	0000	
9-13	(Torq Det Operat)	Operation After Over torque Detection is Activated	0000: Drive will Continue to Operate After Over torque is Activated 0001: Coast-to-Stop After Over torque is Activated	0000	
9-14	(Torq Det Level)	Over torque Threshold Level (%)	30 - 200	160	
9-15	(Torq Det Delay)	Over torque Activation Delay Time (Seconds)	0.0 - 25.0	0.1	

10- Volts/Hz Operation Mode

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
10-0	(V/F Selection)	Volts/Hz Patterns	0 - 18	0/9	*4*6
10-1	(Torque Boost)	Volts/Hz Curve Modification (Torque Boost) (%)	0 – 30.0	0.0	*1*6
10-2	(Motor noLoad Amp)	Motor No Load Current (Amps AC)	-----		*5*6
10-3	(Motor rated Slip)	Motor Slip Compensation (%)	0.0 – 100.0	0.0	*1*6
10-4	(Max frequency)	Maximum Frequency (Hz)	0.20 - 650.00	50.00/ 60.00	*4*6
10-5	(Max Voltage)	Maximum Frequency Voltage Ratio (%)	0.0 - 100.0	100.0	*6
10-6	(Mid frequency)	Mid Frequency (Hz)	0.10 - 650.00	25.00/ 30.00*7	*4*6
10-7	(Mid Voltage)	Mid Frequency Voltage Ratio (%)	0.0 - 100.0	50.0*7	*6
10-8	(Min frequency)	Minimum Frequency (Hz)	0.10 - 650.00	0.50/ 0.60	*6
10-9	(Min Voltage)	Minimum Frequency Voltage Ratio (%)	0.0 - 100.0	1.0*7	*6

11- PID Operation Mode

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
11-0	(PID Mode Sel)	Mode Selection	0000: Disabled 0001: Bias D Control 0002: Feedback D Control 0003: Bias D Reversed Characteristics Control 0004: Feedback D Reversed Characteristics Control 0005: Frequency Command + Bias D Control 0006: Frequency Command + Feedback D Control 0007: Frequency Command + Bias D Reversed Characteristics Control 0008: Frequency Command + Feedback D Reversed Characteristics Control	0000	
11-1	(Feedback Gain)	Feedback Gain (%)	0.00 - 10.00	1.00	*1
11-2	(PID Gain)	Proportional Gain (%)	0.0 - 10.0	1.0	*1
11-3	(PID I Time)	Integration Time (Seconds)	0.0 - 100.0	10.0	*1
11-4	(PID D Time)	Differentiation Time (Seconds)	0.00 - 10.00	0.00	*1
11-5	(PID Offset)	PID Offset	0000: Positive 0001: Negative	0000	*1
11-6	(PID Offset Adj)	PID Offset Adjust (%)	0 - 109	0	*1

11-7	(Output Filter T)	Output Lag Filter Time (Seconds)	0.0 - 2.5	0.0	*1

12- PID "Limits" and "Out of Range" Mode

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
12-0	(Fb Los Det Sel)	Feedback Loss Detection Mode	0000: Disabled 0001: Enabled - Drive Continues to Operate After Feedback Loss 0002: Enabled - Drive "STOPS" After Feedback Loss	0000	
12-1	(Fb Los Det Lvl)	Feedback Loss Detection Level (%)	0 - 100	0	
12-2	(Fb Los Det Time)	Feedback Loss Detection Delay Time (Seconds)	0.0 -25.5	1.0	
12-3	(PID I Limit)	Integration Limit Value (%)	0 - 109	100	*1
12-4	(I Time value Sel)	Integration Value Resets to Zero when Feedback Signal Equals the Intended Value	0000: Disabled 0001: 1 Second 0030: 30 Seconds	0000	
12-5	(I Error Margin)	Allowable Integration Error Margin (Units) (1 Unit = 1/8192)	0 - 100	0	
12-6	(PID Comm. Source)	PID Feedback signal	0000: 0~10V or 0~20mA 0001: 2~10V or 4~20mA	0000	*7
12-7	(Sleep Level)	Sleep Function Operation Level	0.00-650.00	0.0	
12-8	(Sleep Delay Time)	Sleep Function Delay Time	0.0-25.5	0.0	

13- Communication Mode

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
13-0	(Serial Comm Adr)	Assigned Communication Station Number	1 - 254	1	*2*3
13-1	(Serial Baud Rate)	Baud Rate Setting (bps)	0000: 4800 0001: 9600 0002: 19200 0003: 38400	0003	*2*3
13-2	(Comm Stop Bit)	Stop Bit Selection	0000: 1 Stop Bit 0001: 2 Stop Bits	0000	*2*3
13-3	(Comm Parity Sel)	Parity Selection	0000: Without Parity 0001: With Even Parity 0002: With Odd Parity	0000	*2*3
13-4	(Comm Data Format)	Data Format Selection	0000: 8-Bits Data 0001: 7-Bits Data	0000	*2*3

14- Motor Auto-Tune Parameters

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
14-0	(Stator Resistor)	Stator Resistance (Ohms)	-----		*3*5
14-1	(Rotor Resistor)	Rotor Resistance (Ohms)	-----		*3*5
14-2	(Equi Inductance)	Equivalent Inductance (mH)	-----		*3*5
14-3	(Magnet Current)	Magnetizing Current (Amps AC)	-----		*3*5
14-4	(Ferrite Loss)	Ferrite Loss Conductance (gm)	-----		*3*5

15- Drive Status and Function Reset

Function Code No.	LCD Display	Description	Range/Code	Factory Setting	Remarks
15-0	(Drive Model)	Drive Horsepower Code	(See page 4-53)		*3
15-1	(Software Version)	Software Version	-----	-----	*3
15-2	(Fault Log)	Fault Jog (Last 3 Faults)	(See page 4-53)	-----	*3
15-3	(Elapsed Hours)	Accumulated Operation Time (Hours)	0 - 9999	-----	*3
15-4	(Elapsed Hr*10000)	Accumulated Operation Time (Hours X 10000)	0 - 27	-----	*3
15-5	(Elapsed Time Sel)	Accumulated Operation Time Mode	0000: Time Under Power 0001: Run Mode Time Only	0000	*3
15-6	(Reset Parameter)	Reset Drive to Factory Settings	1110: Reset for 50 Hz Motor Operation 1111: Reset for 60 Hz Motor Operation 1112: Reset PLC Program	0000	*4

※Notes: *1 can be modified during operation

*2 cannot be modified during communication

*3 do not change while making factory setting

*4 as parameter related to factory setting

*5 the parameter will be changed by replacing model (see descriptions of the POSTSCRIPT 1)

*6 only available in V/F mode

*7 only for version 2.3 and above.

4.4 Parameter Function Description

Parameter Group 0: Drive Operation Mode

0-00：Control Mode

0000：Vector mode (General Mode)

0001：Vector mode (VT Mode)

0002：V/F mode

To select the most suitable vector control mode or V/F mode according to the load characteristics.

1. Vector (general mode) is inclined to control the general load or rapidly-changed torque load.
2. Vector (VT mode) is suitable for Blower/ Pump and HVAC load. The magnetic current of motor will be variable with the torque, which will reduce the current to save the energy.
3. As V/F mode is selected, please set the parameter group10 comply with the load features.

0-01:Motor Rated Voltage（Vac）
0-02:Motor Rated Current（A）
0-03:Motor Rated Power (kW)
0-04:Motor Rated Speed (RPM)
0-05:Motor Rated Frequency (Hz)
0-06:Motor Parameter Auto Tuning
0000: Disabled 0001: Enabled

It is necessary to input the data on nameplate and auto tuning as long as changing the motor as vector mode is selected.

Auto tuning: firstly input the data to 0-01~0-05 according to the nameplate after power off, then set 0-06=0001and perform auto tuning; the motor will run. It will stop as the inverter finishes auto tuning. The detected internal data will auto be written to parameter group 14.

ex. If the motor rated speed is 1700 rpm, please set 0-04 to 17.0

⚠ Precaution

1. The motor parameter auto tuning is the stationary auto tuning. During motor auto tuning, the motor does not rotate, and the keypad display -AT-.
2. During motor parameter auto tuning, the input signal in control circuit is invalid.
3. Before motor parameter auto tuning, please confirm the stop state of the motor.
4. The motor parameter auto tuning is only available for vector control mode (0-00=0000or 0-00=0001).

0-07 AC Line Input Voltage (Volts AC)

220V series：170.0~264.0

440V series：323.0~528.0

To make sure the voltage level of inverter, please input the actual on-site voltage value.

0-08 Language Selection

0000: English

0001: German

0002: French

0003: Italian

0004: Spanish

The function is only available for the products with LCD operation keypad. The operation is not necessary for the one with LED.

Parameter Group 1 - Start/Stop and Frequency Control Modes

1-00 : Run Command Source Selection

0000:Keypad

0001:External terminal control

0002:Communication control

0003:Built-in PLC

1.) 1-00=0000 the inverter is controlled by the keypad.
2.) 1-00=0001 the inverter is controlled by the external terminals, and the Stop key for emergency does work. (Refer to 1-03 description).
Note: 1-00=0001, please refer to parameter group 2-00, 2-01, 2-02 and 2-03 for detail description to make secure of persons and machines.
3.) 1-00=0002 the inverter is communication controlled.
4.) 1-00=0003 the inverter is built-in PLC controlled, and 1-06 preset value is invalid.

1-01 : Operation modes for external terminals

0000:Forward/stop-reverse/stop

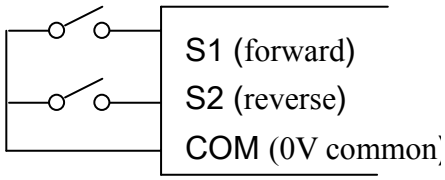
0001:Run/stop-forward/reverse

0002:3-wire control mode -run/stop

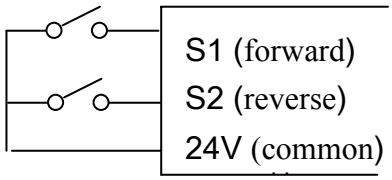
1.) When operation command 1-00 = 0001 (external terminal), 1-01 is valid.
2.) When operation command 1-00 = 0001 (external terminal control), the stop button for emergency is available. (Refer to 1-03 for detail description).
3.) That both forward and reverse commands are ON will be treated as STOP.

1-01 = 0000, Control mode is as below:

(1).Input signal is NPN:

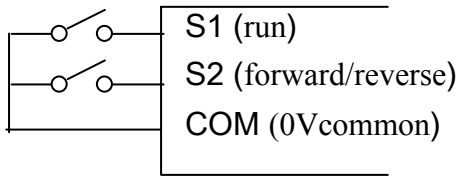


(2). Input signal is PNP:

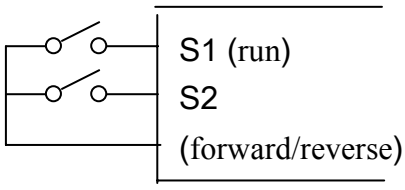


1-01 = 0001, Control mode is as below:

(1). Input signal is NPN:

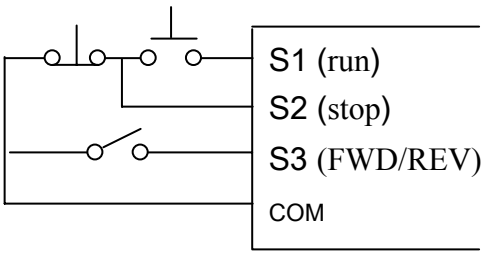


(2). Input signal is PNP:

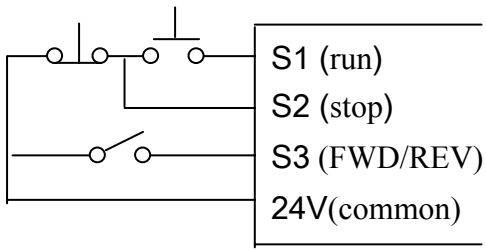


1-01 = 0002, Control mode is as below:

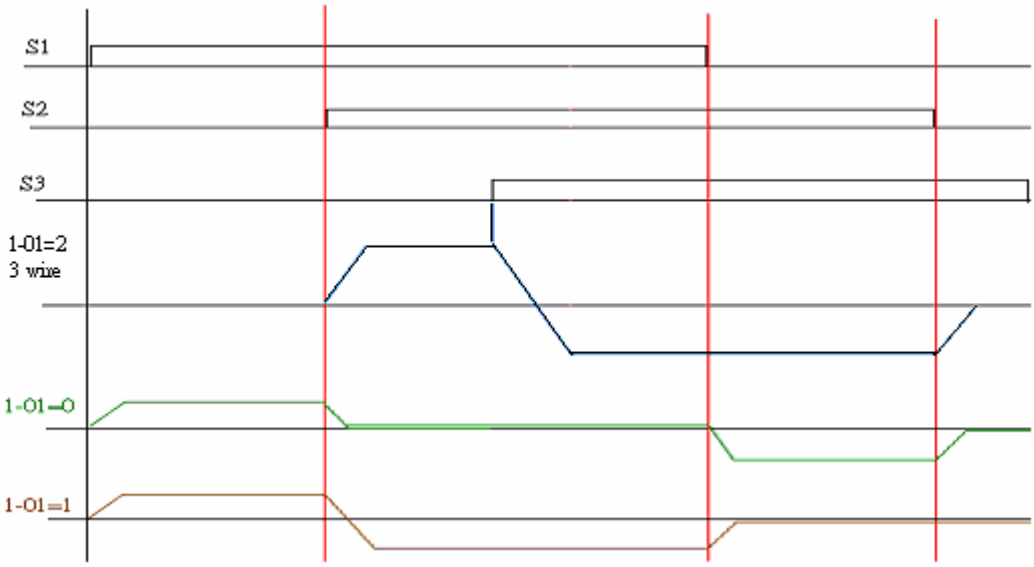
(1). Input signal is NPN:



(2). Input signal is PNP:



※Note: As 3 wire control mode is selected, the terminal S3 is not controlled by 5-02.



※Note: 1-02=0001, the reverse command is unavailable.

1-02 : Prohibition of Reverse Operation	**0000: Enable Reverse Command** **0001: Disable Reverse Command**

1-02=0001, the reverse command is invalid.

1-03 : Keypad Stop Button	**0000: Stop Button Enable** **0001: Stop Button Disable**

1-03=0000，The STOP key is available for controlling the inverter to stop.

1-04 : Starting Method Selection	**0000: Normal Start** **0001: Enable Speed Search**

1.) 1-04=0000：As starting, the inverter accelerates from 0 to target frequency in the set time.

2.) 1-04=0001：As starting, the inverter accelerates to target frequency from the detected speed of motor.

1-05 : Stopping Method	**0000: Controlled Deceleration-to- Stop with DC Injection Braking**

(Rapid Stop)

0001: Free run stop

1.) 1-05=0000: the inverter will decelerate to 0Hz in preset deceleration time after receiving the stop command.

2.) 1-05=0001: the inverter will stop output as receiving the stop command. The motor will inertia free run to stop.

1-06 : Frequency Command Source Selection

0000: Set the Frequency with Keypad

0001: Potentiometer on Keypad

0002: External Analog Signal Input or Remote Potentiometer

0003: Up/Down Frequency Control Using MFIT (S1 - S6)

0004: Communication Setting Frequency

0005: Impulse frequency (S5) setting frequency (ver2.3)

1.) 1-06=0001 ，as one of the parameter in group 5-00~ 5-06is set 16 and multifunction terminal is OFF, the frequency is set by the KNOB(VR for principal speed) on keypad. While the multifunction is ON, the frequency is set by analog signal (auxiliary speed) on terminal block (TM2).

2.) 1-06=0002 ，as one of the parameter in group 5-00~ 5-06 is set 16 and the multifunction terminal is OFF, he frequency is set by analog signal (principal speed) on terminal block (TM2), While the multifunction is ON, the frequency is set by the KNOB(VR for auxiliary speed) on keypad.

3.) Please refer to description of parameter group 5-00~ 5-06 (multifunction input terminals) for the function Up/Down terminal.

4.) The priority in reading frequency is PLC frequency control >traverse run >Jog> preset speed>▲▼ on keypad or Up / Down or communication control.

5.) Impulse frequency command input source should be setting as S5 terminal and need to coordinate with 5-10 frequency exchange times ratio. For example, the input value S5 is 4KHZ, 5-10 is 1.500 times, and output frequency is 40.00*1.5=60.00HZ. 5-04(S5) should be setting as 19.

1-07:Keypad Operation with Up/Down Keys in Run Mode

0000: 'Enter' must be pressed after frequency change with Up/Down Keys on keypad.

0001: Frequency will be changed directly when Up/Down Keys are Pressed

Parameter Group 2 - Manual/Automatic Restart Modes

2-00: Momentary Power Loss and Restart

0000: Momentary Power Loss and Restart Disable

0001: Momentary Power Loss and Restart is Enable

0002: Momentary Power Loss and Restart Enable while CPU is Operating.

2-01 : Momentary Power Loss Ride-Thru Time(sec): 0.0 - 2.0 second

1.) As start of the other load of power supply results in lowering the voltage below the under voltage level, the inverter will stop output at once. If the power supply recovers in the 2-01 preset time, it will spin start tracing from the trip frequency, or the inverter will trip with 'LV-C' displayed.
2.) The allowable power loss time differs with the models. The range is from 1second to 2 second.
3.) 2-00=0000: as power lost, the inverter will not start.
4.) 2-00=0001: if the loss time is less than the value of 2-01, the inverter will Spin Start in 0.5 second as the power supplied and restart times are infinite.
5.) 2-00=0002: the power lost for long time, before the inverter lost the control power for the CPU, the inverter will restart according to the 1-00 and 2-04 setting and status of external switch as the power resupplied.

※Note: 1-00=0001, 2-04=0000, 2-00=0001or 0002 after power lost for a long time, please OFF the power and power switches in case of injury to person and machine by the resupplied power.

2-02：Auto restart Delay Time :0 ~ 800.0 second

2-03：Number of Auto restart Attempts :0 ~ 10 times

1.) 2-03=0：the inverter will not auto restart as trip for accident.

2.) 2-03>0，2-02= 0:

The inverter will conduct SPIN START in 0.5 second after trip for accident. The motor will inertia run to frequency at the trip stop, then according to setting accelerate or decelerate time to target frequency.

3.) 2-03>0，2-02>0：

The output will be stopped for a period which is determined by the 2-02 after accident trip. Then, spin start to present target frequency.

4.) As the inverter is set in braking deceleration or DC braking, it will not perform restart after accident.

2-04 : Start Method:

0000: Enable Speed Search

0001: Normal Start

1.) 2-04=0000：the inverter will detect motor speed and accelerated the setting frequency as speed

search enable.

2.) 2-04=0001：the inverter will accelerated the motor speed from stop (zero speed) to setting frequency.

2-05 :Direct running after power up:
0000: Enable Direct Running After Power Up
0001: Disable Direct Running After Power Up

Danger：

1.) 2-05=0000 and the inverter is set external terminal controlled（1-00=0001）, if the run switch is ON as power is supplied, the inverter will auto start. It is recommend that to cut off the power switch and run switch in case of injury to persons or machine as power is supplied again.

2.) 2-05=0001and the inverter is set external terminal controlled（1-00=0001）, if the run switch is ON as power is supplied, the inverter will not auto start and flash STP1. It is necessary to OFF the run switch and then ON to normally start.

2-06 : Delay-ON Timer (seconds): 0 ~ 300.0 second

As power on and 2-05=0000, the inverter will perform auto restart in the setting time for delay.

2-07: Error reset mode setting 0000: Enable Reset Only when Run Command is Off
0001: Enable Reset when Run Command is On or Off

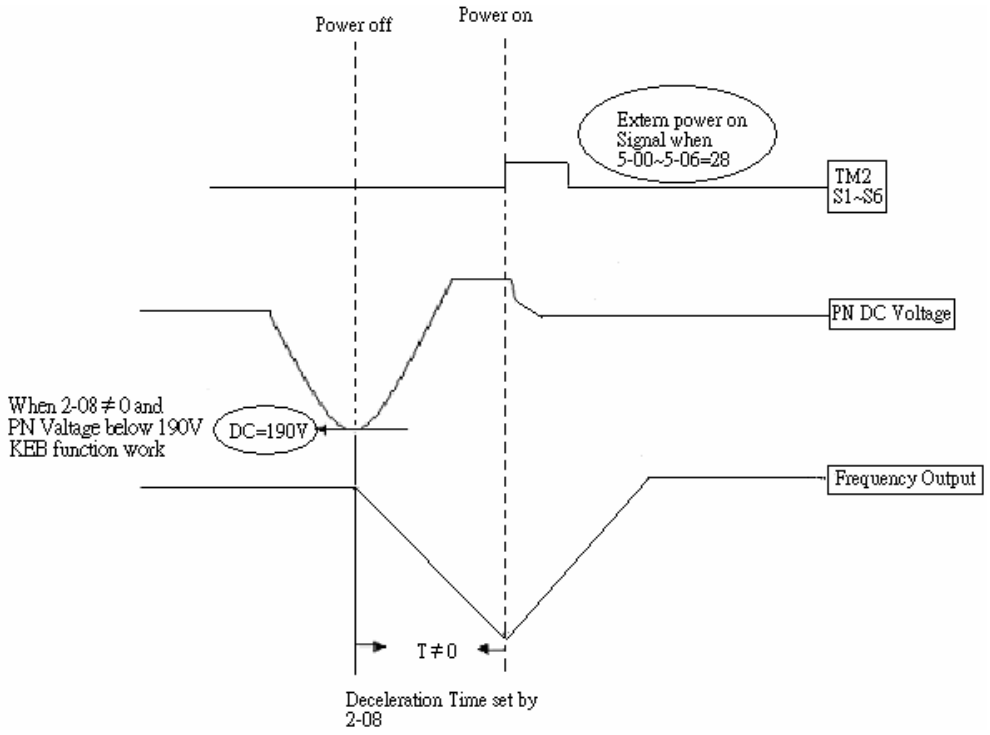
2-07=0000as the inverter is detected the accident, please cut off the Run switch to perform reset, or restarting does not work.

2-08: Kinetic Energy Back-up Deceleration Time:0.00~25.00 second

2-08 = 0 KEB function disable

2-08≠0 KEB function enable

Ex: 220V system



※NOTE:

1.When 2-08≠0，the momentary power loss and Restart is disabled,the inverter will do KEB Function.

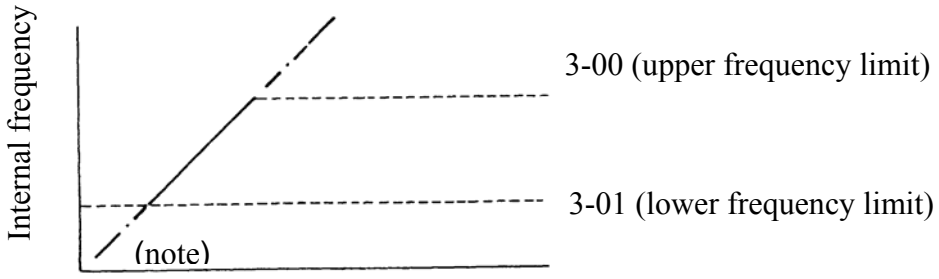
2.When power off，CPU detect the DC Voltage. KEB function enable when DC Voltage below than 190V（220V system）or 380V（440V system）.

3.When KEB function enabled,the inverter decelerate to zero by 2-08,and the inverter stop.

4.IF the power on signal enabled during the KEB function ,the inverter accelerate to original frequency.

Parameter Group 3 - Operating Parameters

3-00: Frequency Upper limit(Hz) : 0.01 - 650.00
3-01: Frequency Lower limit(Hz) : 0.01 - 650.00



※Note: When 3-01 = 0 Hz and frequency command is 0 Hz，the inverter will stop at 0 speed.

When 3-01 > 0 Hz and frequency command ≦3-01，the inverter will output 3-01 preset value.

3-02 : Acceleration Time #1 （second）: 0.1 – 3600.0

3-03 : Deceleration Time #1 （second）: 0.1 – 3600.0

3-04 : S Curve of First Acceleration Stage（second）: 0.0 – 4.0

3-05 : S Curve of Second Acceleration Stage（second）: 0.0 – 4.0

3-06 : Acceleration Time #2 （second）: 0.1 – 3600.0

3-07 : Deceleration Time #2 （second）: 0.1 – 3600.0

3-08 : Jog Acceleration Time（second）: 0.1 –25.5

3-09 : Jog Deceleration Time（second）: 0.1 – 25.5

1.) Formula for calculating acceleration and deceleration time: The denominator is base on the rated frequency of motor.

$$\text{Acceleration time} = \text{3-02 (or 3-06)} \times \frac{\text{Preset frequency}}{\text{0-05}} \text{ , Deceleration time} = \text{3-03 (or 3-07)} \times \frac{\text{Preset frequency}}{\text{0-05}}$$

2.)When 5-00 – 5-06 is set 06 (the second acceleration and deceleration time) , the first acceleration/ deceleration/ S curve or the second acceleration/ deceleration/ S curve will be set by ON the external input terminal.

3.) When 5-00 – 5-06 is set 05 (Jog) , Jog run is controlled by external terminals. The acceleration and deceleration action will be at Jog acceleration and deceleration time.

4.)When 5-00 – 5-06 is set as 05(Jog) and 06(acceleration and deceleration time toggle), to change the acceleration and deceleration time by ON the external terminals, and the list setting:

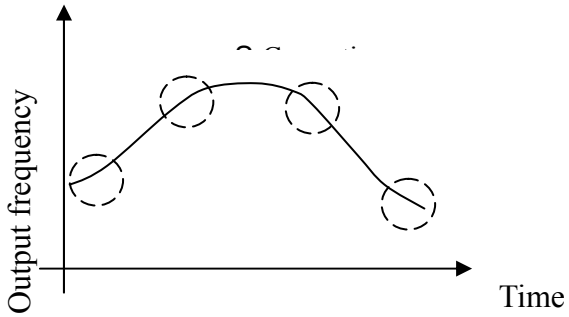
Function / preset value	Acc/ Dec time 1(3-02/3-03)	Acc/ Dec time 2 (3-06/3-07)	JOG Acc/Dec time (3-08/3-09)
	1-06 determines the output frequency	1-06 determines the output frequency	Run at 6-01Jog frequency
5-00~5-05=05 Jog command	Off	Off	On
5-00~5-05=04 Toggle Acc/Dec time.	Off	On	Off

5.)When S curve time (3-04/3-05) is set as 0, the S curve is useless. Namely, acceleration and deceleration is at line.

6.)When S curve time (3-04/3-05) is larger than 0, the acceleration and deceleration action is as following diagram.

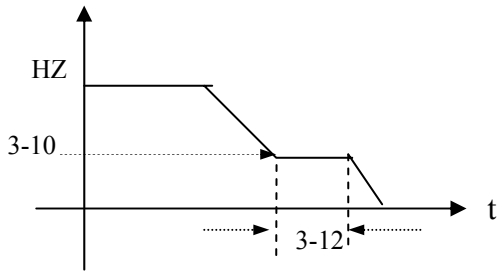
7.)Regardless of the stall prevention period, actual acceleration and deceleration time =preset acceleration / deceleration time + S curve time. For example: acceleration time = 3-03+ 3-04。

8.)During acceleration and deceleration process, there might be residual error in acceleration and deceleration toggling. Please set the S curve time as 0 (3-04/3-05), if you need to toggle acceleration and deceleration time in acceleration / deceleration process.



3-10 : DC Injection Brake Start Frequency (Hz) : 0.1 – 10.0
3-11 : DC Injection Brake Level (%) : 0.0 – 20.0
3-12 : DC Injection Brake Time(second) : 0.0 – 25.5

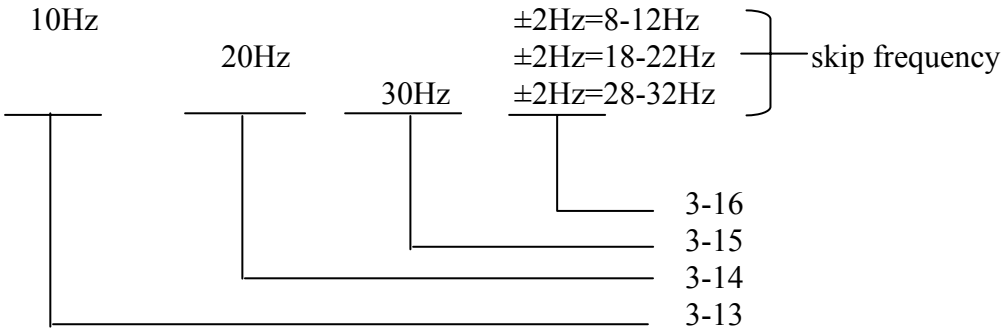
3-12 / 3-10 is the action time and start frequency of DC braking, as graph below:



The upper setting of 3-11 will be corrected 20.0 after manual V2.3.

3-13 : Skip Frequency #1 (Hz) : 0.00 –650.00
3-14 : Skip Frequency #2 (Hz) : 0.00 –650.00
3-15 : Skip Frequency #3 (Hz) : 0.00 –650.00
3-16 : Skip Frequency Bandwidth (± Hz) : 0.00 –30.00

Example: as 3-13is set as 10.0Hz / 3-14 as 20.0 Hz / 3-15a s 30.0 Hz / 3-16 as 2.0Hz



3-17: Parameter lock function

0000: Enable all Functions
0001: 6-00 - 6-08 cannot be changed
0002: All Functions Except 6-00 - 6-08 cannot be changed
0003: Disable All Function

3-18: Copy Unit
0000: Disable
0001: Inverter to Copy Unit
0002: Copy Unit to Inverter
0003: Verify

1.) 3-18=0000：Inverter can not copy parameter.

2.) 3-18=0001：Copy the inverter parameters to module.

3.) 3-18=0002：Copy the module parameters to inverter.

4.) 3-18=0003：Copy the parameters to inverter or module to mutually verify the parameters.

※Note: The copy function is available for the models with same capacity.

3-19: Fan Running Controlling
0000: Auto (Depend on temp.)
0001: Operate while in RUN Mode
0002: Always Run
0003: Always Stop

1.) 3-19=0000：The fan run as the inverter senses temperature rises. Thusly, extend the service period.

2.) 3-19=0001：The fan runs while the inverter is running.

3.) 3-19=0002：The fan is continuously running regardless of the action of the inverter.

4.) 3-19=0003：The fan is always stopping regardless of the action of the inverter.

※Note: Depend on the hardware, the function is disable at 15HP above of 220V class and 20HP above of 440V class. The fan is running after the inverter power on.

3-20: Energy Saving Mode Operation 0000: Disabled
0001: Controlled by MFIT at Set Frequency
3-21: Energy saving operation gain (%): 0-100

1.) In terms of FAN, PUMP or other heavy inertia loads which need greater start torsion, while in operation they need not so high torsion. Consequently, to decline the output voltage to saving energy by setting 3-20 is necessary.

2.) 5-00 ~5-06(Multifunction input terminal) set as10 to saving energy.

3.) 3-20=0001, If the multifunction terminal is set as 10(energy saving control terminal), the output voltage will gradually decline to 'original voltage'×'3-21' preset value as the terminal' is ON. The output voltage will rise to original voltage as the terminal is OFF.

※Note：1.The declining and rising speeds of voltage for energy saving is same as the ones for SPEED SEARCH.

2. Energy saving mode is only available under V/F mode. (0-00 = 0002)。

3-22：Carrier Frequency (KHz) ： 2-16

3-22	Carrier Frequency	3-22	Carrier Frequency	3-22	Carrier Frequency	3-22	Carrier Frequency
2	2KHz	6	6KHz	10	10KHz	14	14KHz
3	3KHz	7	7KHz	11	11KHz	15	15KHz
4	4KHz	8	8KHz	12	12KHz	16	16KHz
5	5KHz	9	9KHz	13	13KHz		

※ Note：The external electronic components maybe interfered, more serious, even the motor vibration due to cutting of the high carrier frequency waveform, although the inverter provides low noise environment in running. Thusly, it is necessary to regulate the carrier frequency.

Parameter Group 4 - Digital Display Operation Mode

4-00：Motor Current Display Selection： 0000: Disable Motor Current Display

0001: Enable Motor Current Display

4-01：Motor Voltage Display Selection： 0000: Disable Motor Voltage Display

0001: Enable Motor Voltage Display

4-02：DC Bus Voltage Display Selection： 0000: Disable Bus Voltage Display

0001: Enable Bus Voltage Display

4-03：PLC Status Display Selection： 0000:Disable PLC Status Display

0001:Enable PLC Status Display

The function is available for LCD operation keypad, but not for LED one.

4-04：Custom Units (Line Speed) Value ： 0-9999

The max preset line value of 4-04 is equal to the rated frequency (0-05) of the motor. For instance, given line speed 1800 is equal to display 900 when output is 30Hz while the operation frequency is 60Hz.

4-05 : Custom Units (Line Speed) Display Mode
0000:Drive Output Frequency is Displayed
0001:Line Speed is Displayed in Integer (xxxx)
0002:Line Speed is Displayed with One Decimal Place (xxx.x)
0003:Line Speed is Displayed with Two Decimal Places (xx.xx)
0004:Line Speed is Displayed with Three Decimal Places (x.xxx)

The preset frequency is displayed as the inverter stops while the operation line speed is displayed as the inverter is running.

4-06：PID Feedback Display 0000:Disabled

0001:Enable

Keypad displays PID feedback value :
Parameter 5-05=20 (That is, S6 is set as the PID feedback analog terminal, refer to PID), 11-0=1(PID is enabled), and 4-06=1(Display S6 as PID analog feedback value 0~100, the formula as follow:)

If feedback signal is 0~10V, (12-6=0000), keypad display value = (S6/10V)*100

If feedback Signal is 4~20mA, (12-6=0001), keypad display value = (S6/20mA)*100

※Note: Please press DSP Key to switch between the output frequency and PID feedback value.

※Note: The inverter displays XXXF as Running, while XXXr as Stop.

Parameter Group 5-Multifunction Input Terminals (MFIT)

Multifunction input terminals (TM2 S1-S6/AIN) controlling：

5-00~06

0000: Forward/Stop Command *1
0001: Reverse/Stop Command *2
0002: Preset Speed # 1 (6-02)
0003: Preset Speed # 2 (6-03)
0004: Preset Speed # 3 (6-05) *3
0005: Jog
0006: Acc/Dec time # 2
0007: Emergency Stop Contact A
0008: Base Block
0009: Speed Search Stop
0010: Energy Saving
0011: Control Signal Selection
0012: Communication Control Signal Selection
0013: Acc/Dec Disabled
0014: Up Command
0015: Down Command
0016: Principal/Auxiliary Speed
0017: PID Function Disabled
0018: Reset
0019: Encoder Input Terminal（Terminal S5）
0020: PID Feedback Signal A12 （Terminal S6）
0021: AI2 Bias Signal 1 Input（Terminal S6）
0022: AI2 Bias Signal 2 Input（Terminal S6）
0023: Analog Input（Terminal AIN）
0024: PLC Application
0025: Traverse Run
0026: Traverse Run Upper Deviation
0027: Traverse Run Lower Deviation
0028: Power Source Detect for KEB Function
0029: Emergency Stop Contact B

A. The terminals S1-AIN on terminal block (TM2) are multifunction input terminals. The above 30 functions can be set in these terminals.

B. Function Description for 5-00~06:

1. 5-00~06=0/1(Forward/Reverse/Stop)

As forward command is ON, the inverter runs while stops as OFF. The 5-00 factory set is forward.

As reverse command is ON, the inverter runs while stops as OFF. The 5-01factory set is reverse.

2. 5-00~06=2-4(Preset speed 1~3)

External multifunction input terminals are ON, the inverter is operation at the preset time, and the duration is determined by the time of the terminal ON. The corresponding frequency parameter is illustrated below:

3. 5-00~06=5(Jog)

To select Jog operation as ON the external input terminals. Now, the inverter operates at the Jog acceleration and deceleration time. The corresponding frequency parameter is illustrated below:

The priority order of frequency: Jog Speed→Preset Speed→Keypad frequency or external frequency signal

Multifunction terminal3 Preset value=04	Multifunction terminal 2 Preset value =03	Multifunction terminal 1 Preset value =02	Jog Command terminal Preset value =05	Output frequency preset value
0	0	0	0	6-00
X	X	X	1	6-01
0	0	1	0	6-02
0	1	0	0	6-03
0	1	1	0	6-04
1	0	0	0	6-05
1	0	1	0	6-06
1	1	0	0	6-07
1	1	1	0	6-08

4. 5-00~06=6 (toggle acceleration and deceleration time)

On the external input terminal, to select the acceleration 1/ deceleration 1/ S curve 1 or acceleration 2/ deceleration 2/ S curve 2.

5. 5-00~06=7 /29：External Emergency Stop Contact A or B.

The inverter will decelerate to stop and Flash E.S as the emergency stop signal received regardless of 1-05 setting. After such signal released, OFF the operation switch then ON or Press Operation Key, the inverter will restart from the start frequency. If the emergency signal was released before the inverter stop completely, the inverter still carries out emergency stop. The 8-02/03 determines the action of the error terminal. As 8-02/0=0: the error terminal does not act when the external emergency signal input. While 8-02/03=9, the error terminal does act when emergency signal input.

6. 5-00~06=8：Base Block

The inverter stop output as receiving STOP command, and the motor Free-Run stops.

7. 5-00~06=9：Speed Search Stop

When starting, the inverter detects the present speed of the motor firstly, then, the inverter accelerates from the present speed to preset speed.

8. 5-00~06=10：Energy-saving operation

In terms of FAN, PUMP or other heavy inertia loads which need greater start torque, while in operation they need not so high torsion. Thusly, to decline the output voltage is to saving energy.

The output voltage gradually declines as the multifunction terminal is ON. It will gradually increase (to the original voltage) as the Multifunction terminal is OFF.

※Note：The acceleration and deceleration speed of energy saving operation is the same as the speed of SPEED SEARCH.

9. 5-00~06=11： Switch of the control signal

External switch terminal is OFF：1-00/01 determines the operation signal and frequency signal.

External switch terminal is ON：Keypad controls the operation signal and frequency signal but not controlled by 1-00/01.

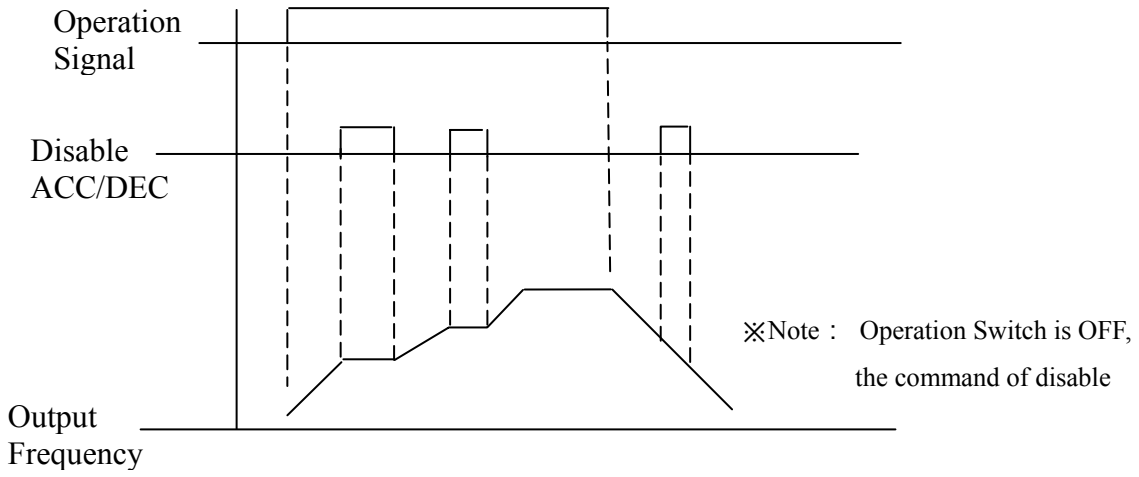
10. 5-00~06=12： Switch of the inverter controlling in communication

External switch terminal is OFF：in communication, the master (PC or PLC) can control the inverter operation and frequency signal and allowably modify the parameters, and the operation signals from Keypad and TM2 are idle. Furthermore, the keypad can only display the voltage, current and frequency, the parameters are readable and not writable, and Emergency Stop is valid.

External switch terminal is ON：in communication, the inverter is controlled by the keypad regardless of the setting of 1-00/1-06 and master. Under such circumstance, the master still can read and write the inverter parameters.

11. 5-00~06=13：Disable acceleration and deceleration

The acceleration and deceleration action is unavailable till the forbid acceleration and deceleration signals are released. The action is illustrated in the graph below:



12. 5-00~06=14,15：UP / DOWN Function (Actual ACC/DEC time is base on the setting)：

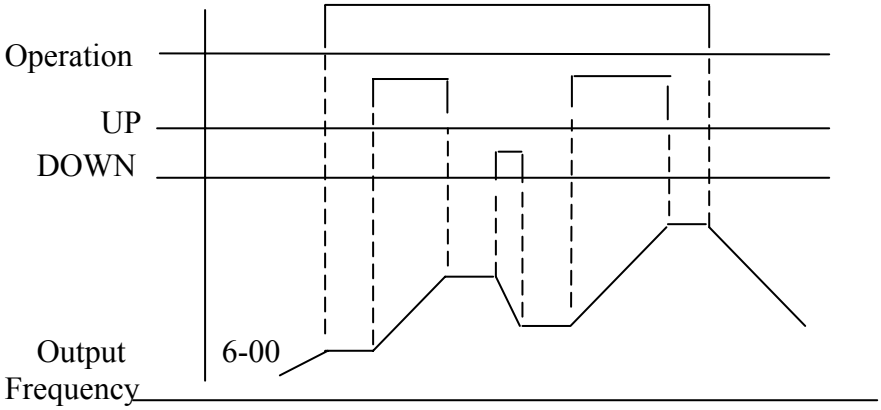
(1)Please set 1-06 = 3 if you want to use the UP/DOWN Function, and the other frequency signals are useless.

(2)Set 5-08 = 0 and 5-09 = 0, the inverter accelerates to the preset value of 6-00 when the operation terminal is ON. Then, it maintains the certain speed. As the inverter receives the UP/DOWN command, it will accelerate / decelerate till the command is released. The inverter runs at the certain speed. The inverter will ramp stop or Free-Fun stop which is determined by the 1-05 as long as the inverter receives the STOP command. And the frequency of Stopping will be stored in 6-00. The UP/DOWN KEY is invalid as the inverter stops. It is necessary to use the Keypad to modify the preset parameter.

(3)Set 5-08 = 1, the inverter will operate from 0Hz when the operation terminal is ON. The action of UP/DOWN is as above description. The inverter will ramp stop or free-run stop which determined by1-05 setting when as it receiving the Stop Command and back to 0Hz. The next operation will start at 0 Hz.

(4) That UP/Down Signal Simultaneously act are invalid

(5) 5-09≠ 0, the inverter will accelerate to the setting of 6-00 and maintain at the speed. When the UP/Down terminal is On, setting frequency is present value 6-00±5-09, and the inverter will accelerate/ decelerate to frequency 6-00. The upper frequency limit and lower frequency limit also restrict the operation. If the signal of UP/ DOWN is maintained over 2 seconds, the inverter will begin to accelerate/ decelerate. If 5-09=0, the operation is the same, till the UP/ DOWN signal stops. Please refer to the time diagram of 5-09.



13. 5-00~06=16 Principal/Auxiliary speed toggle

Multifunction terminal = OFF, the frequency is set by the VR (Master Speed) on the Keypad. Whereas, Multifunction terminal = ON, the frequency is set by the analog signal terminal (Auxiliary Speed) on the TM2 on terminal Block.

14. 5-00~06=17(PID Function Disable)

The PID Function Disable is ON. PID is not controlled by 11-0, while OFF, it is controlled by 11-0.

15. 5-00~06=18(Reset Command)

The Reset command is same as Reset Key on the panel is ON. The command is OFF, and the inverter does not response. The factory set of 5-05 is Reset command.

16. 5-04=19 (Encoder Input terminal)

The multifunction terminal S5 is set 19 means it is the input terminal for PLC program Encoder.

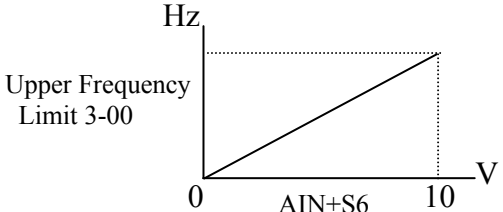
17. 5-05=20 (PID feedback input terminal)

The multifunction terminal S6=20 means the PID feedback input terminal and 0~10V (0~ 20 mA) or 2~10V (4~20mA) is available by the setting of 11-0.

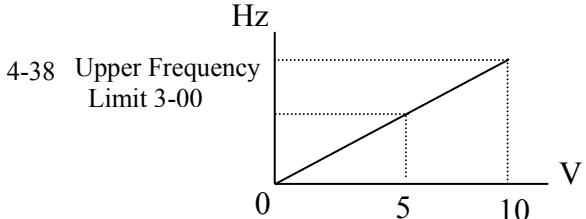
18. 5-05=21 /22(Bias signal 1/2 input)

To regulate the Offset of the Keypad VR or AIN analog input, only the signal of 0~10V (0~ 20 mA) or 2~10V (4~20mA) is available.

5-05=21 Function



5-05=22Function * The value is 0 when AIN+(S6-5V) < 0



19. 5-06=23 (Analog input AIN)

The multifunction terminal AIN = 23. The action is provided for setting the frequency.

20. 5-00~06=24 (PLC Application)

The multifunction terminal S1-AIN=24, which means the terminal is for PLC application. The terminal is provided for the PLC program input.

21. 5-00~06=25 (Traverse Run); 5-00~06=26(Upper Deviation Traverse); 5-00~06=27(Lower deviation Traverse).

The motion description refers to 3-23~3-29 for detail description.

22. 5-00~06=28 (Power Source Detect for KEB Function)

Please refer to the description of 2-08

Digital /Analog input signal scan times:

5-07: Multifunction terminal S1～S6 and AIN signal confirm the scan times (mSec X 4) , 1~100 times

1.TM2 terminal used as scanning, if there are same signals continuously input for N times(Namely, Scan times), the inverter will treated the signal as normal. During performing the signal, if the scan times are less than N, the signal will be as noise.

2. Each scan period is 4ms.

3. The user can specify the scan times interval duration according to the noise environment. If the noise is serious, upper modify the value of 5-07, but the response speed will be slow down.

4. Note: If the S6 and AIN is for digital signal, the voltage level for digital signal above 8V is treated as ON, below 2V is OFF.

Stop Mode Using MFIT:

5-08:

0000: When Up/Down is used, the preset frequency is hold as the inverter stops, and the UP/Down is idle.

0001: When Up/Down is used, the preset frequency is reset to 0 Hz as the inverter stops.

0002: When Up/Down is used, the preset frequency is hold as the inverter stops, and the UP/Down is available.

(1) Set 5-08=0, the inverter will accelerate to the speed of 6-00 as receiving the Run command and run at such certain speed. The inverter begins to accelerate (decelerate) as the UP (Down) terminal is energized. The inverter will hold the speed as the UP/DOWN command released. When the Run Signal releases, the inverter will ramp stop or stop output (determined by the 1-05). It will store the frequency when the operation signal disappeared. UP/DOWN keys are idle when the inverter is stop. The keypad is available for you modify the preset frequency (6-00). If 5-08=0002, the UP/Down is available as the inverter stops.

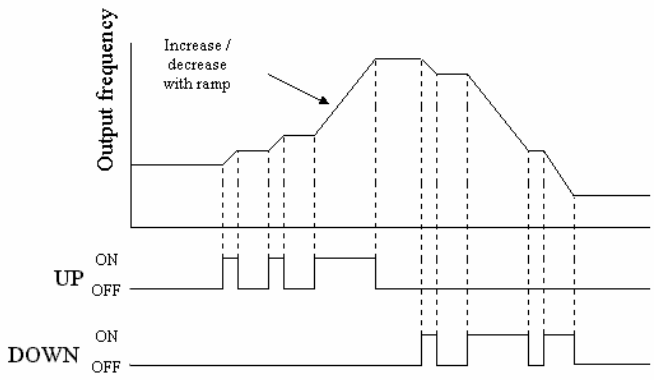
(2)Set 5-08=1, as the Run terminal is energized, the inverter operates from 0 Hz, the Function of UP/DOWN is same as the above description. When the Run Signal released, the inverter will ramp stop or stop output (determined by 1-05) .And back to 0 Hz. The following operation will always begin from 0 Hz.

Step of Up/Down Function (Hz):

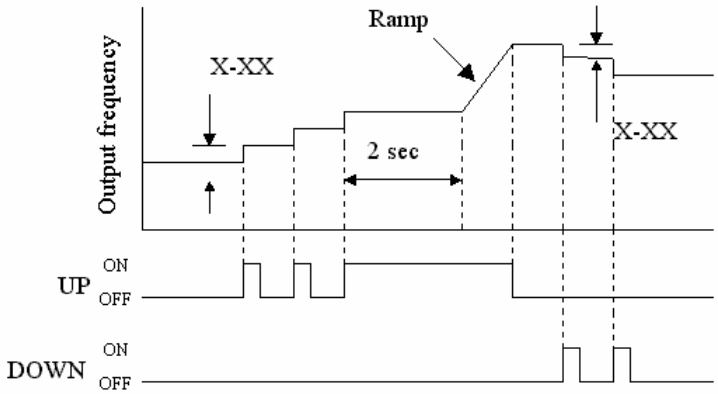
5-09：Up/Down (Hz) 0.00 – 5.00

There are two modes covered below:

(1) 5-09 = 0.00, the function is disable. The operation is just as the original one. As UP terminal is ON, the frequency increases while the DOWN terminal is ON, the frequency decreases. (Refer to the following graph).



(2) 5-09 = 0.01 to 5.00, UP/ DOWN terminal ON, that equivalent to increase/ decrease the frequency of 5-09. If the pressing is over 2second, revive the original UP/DOWN mode (Please refer to the following diagram)



Encoder Impulse Ratio：

5-10 Impulse input frequency time ratio

When frequency source 1-06 be setting as 0005, the impulse signal frequency will be according to this parameter to decide to the real inside frequency of inverter.

The inside calculate formula : Frequency = S5(impulse frequency)*5-10(times ratio)

For example, when S5 impulse is 1KZ(1000), and 5-10 be setting as 1.50 times. The inverter

frequency command is 1000*1.5=1500=15.00HZ. The frequency accuracy of S5 is by base of 100, 1K(1000) present 10.00 HZ.

Reference Source 2：

5-11 Auxiliary frequency source can be selected

Ex.

When frequency source command setting as impulse command, (1-06= 5)

If master speed operating (5-00~5-06 setting to 16 and the terminal is OFF), frequency running as impulse frequency.

If auxiliary speed operating (5-00~5-06 setting to 16 and the terminal is ON), frequency should be decided by 5-11 setting.

The action process as below:

5-11= 0, frequency refer to 6-00.

5-11= 1, frequency refer to the VR analog signal on the Keypad.

5-11= 2, frequency refer to the VR analog signal on TM2.

5-11= 3, frequency refer to the frequency value which is calculated by Up/Down on TM2.

5-11= 4, frequency refer to the input communication frequency.

Parameter Group 6- Jog and Preset (MFIT) Speed Setting on Keypad

Jog and Preset (MFIT) Speed Setting on Keypad：

6-00~08: Set Jog and preset speed by Keypad

A. 5-00~06=2-4(preset speed 1~3)

The external multifunction terminal = ON, the inverter operates at preset speed. The operation time of the 8 stages is base on the ON time of the terminal. Please refer to the corresponding parameters list:

B. 5-00~06=5(Jog terminal)

The external multifunction terminal = ON, the inverter operates in Jog acceleration time/ Jog decelerate time/ON

Function Code No.	LCD Display	Description	Range/Code
6-00	(Keypad Freq)	Keypad Frequency (Hz)	0.00 - 650.00
6-01	(Jog Freq)	Jog Frequency (Hz)	0.00 - 650.00
6-02	(Preset Speed #1)	Preset Speed # 1 (Hz)	0.00 - 650.00
6-03	(Preset Speed #2)	Preset Speed # 2 (Hz)	0.00 - 650.00
6-04	(Preset Speed #3)	Preset Speed # 3 (Hz)	0.00 - 650.00
6-05	(Preset Speed #4)	Preset Speed # 4 (Hz)	0.00 - 650.00
6-06	(Preset Speed #5)	Preset Speed # 5 (Hz)	0.00 - 650.00
6-07	(Preset Speed #6)	Preset Speed # 6 (Hz)	0.00 - 650.00
6-08	(Preset Speed #7)	Preset Speed # 7 (Hz)	0.00 - 650.00

Priority in reading the frequency: Jog > Preset speed > Keypad frequency or external frequency signal

Multifunction terminal3 Preset value=04	Multifunction terminal 2 Preset value =03	Multifunction terminal 1 Preset value =02	Jog Command terminal Preset value =05	Output frequency preset value
0	0	0	0	6-00
X	X	X	1	6-01
0	0	1	0	6-02
0	1	0	0	6-03
0	1	1	0	6-04
1	0	0	0	6-05
1	0	1	0	6-06
1	1	0	0	6-07
1	1	1	0	6-08

Parameter Group 7 - Analog input signal operation mode

Analog Input Signal Operation Mode:
7-00:AIN Gain(%) 0 - 200
7-01:AIN Bias(%) 0 - 100
7-02:AIN Bias Selection: 0000:positive 0001:Negative
7-03:AIN Slope: 0000:positive 0001:Negative
7-04: AIN signal verification Scan Time (AIN, AI2) 1–100 (× 4mSec)
7-05: AI2 Gain (%)(S6) 0 - 200

1. 7-02 = 0 : 0V(0mA) corresponding to Lower Frequency Limit. , 10V (20mA) corresponding to Upper Frequency Limit.

2. 7-02 = 1 : 10V(20mA) corresponding to Lower Frequency Limit , 0V (0mA) corresponding to Upper Frequency Limit.

3.12-6 = 0 : 0~10V(0~20mA)

F= I*(3-00)/20 I>=0 ; SW2= I or F=V*(3-00)/10 V>=0 ; SW2=V

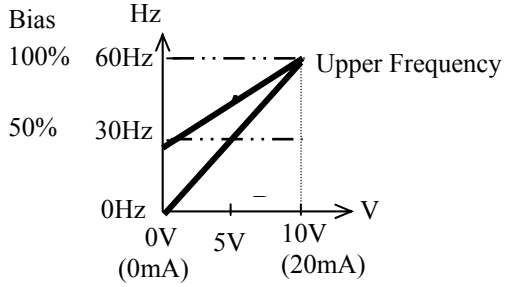
= 1 : 2~10V(4~20mA)

F=(I-4)*(3-00)/16 I>=4 ; SW2= I
F=0 I<4
F=(V-2)*(3-00)/8 V>=2 ; SW2=V or
F=0 V<2

The setting of figure 1:

	7-00	7-01	7-02	7-03	7-05
A	100%	50%	0	0	100%
B	100%	0%	0	0	100%

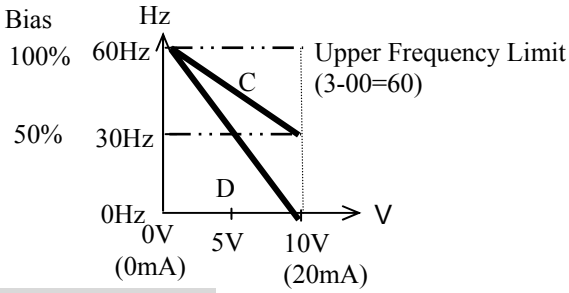
Figure 1



The setting of figure2:

	7-00	7-01	7-02	7-03	7-05
C	100%	50%	0	1	100%
D	100%	0%	0	1	100%

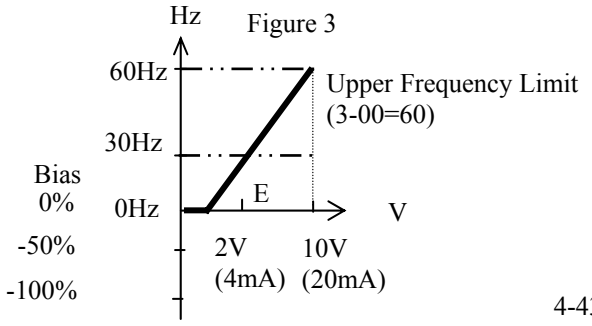
Figure 2



The setting of figure 3:

	7-00	7-01	7-02	7-03	7-05
E	100%	20%	1	0	100%

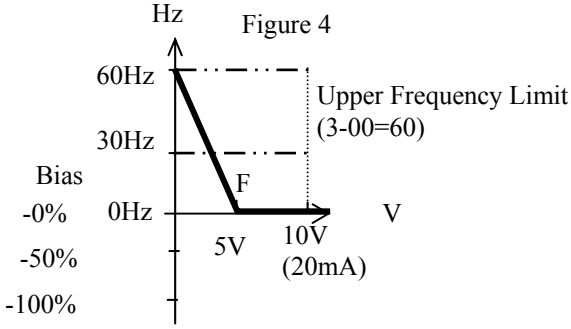
Figure 3



The setting of figure 4:

	7-00	7-01	7-02	7-03	7-05
F	100%	50%	1	1	100%

Figure 4



3. The inverter reads the average value of A/D signals once per (7-04×4ms). Users can determine scan intervals according to noise in the environment. Increase 7-04 in noisy environment, but the respond time will increase accordingly.

Parameter Group 8 - Multifunction output terminal and output signal operation mode

Multifunction analog output control:

8-00：Analog Output Voltage Mode：

0000: Output frequency
0001: Frequency Setting
0002: Output voltage
0003: DC Bus Voltage
0004: Motor current
0005: FEEDBACK Signal of PID

8-01：Analog Output Gain = 0 ~ 200%

The multifunction analog output terminal of the terminal block (TM2), is 0~10Vdc analog output. The output type is determined by the 8-01. The function of 8-01 is: when there is tolerance for the external voltage meter and peripheral equipment, please regulate 8-00.
The FEEDBACK value of PID (That is the input voltage and current of S6) outputs analog value from FM+ terminal. (decide to parameter 4-06) The value is corresponding to the input signal 0~10V(0 ~ 20 mA) or 2~10V (4~20mA).

※Note: The max output voltage is 10V due to the circuit, even the output voltage should be higher than 10V.

Multifunction output terminals control:

8-02：RELAY1(R1C，R1B，R1A terminal on TM2)

8-03：RELAY2(R2C，R2A terminal on TM2)

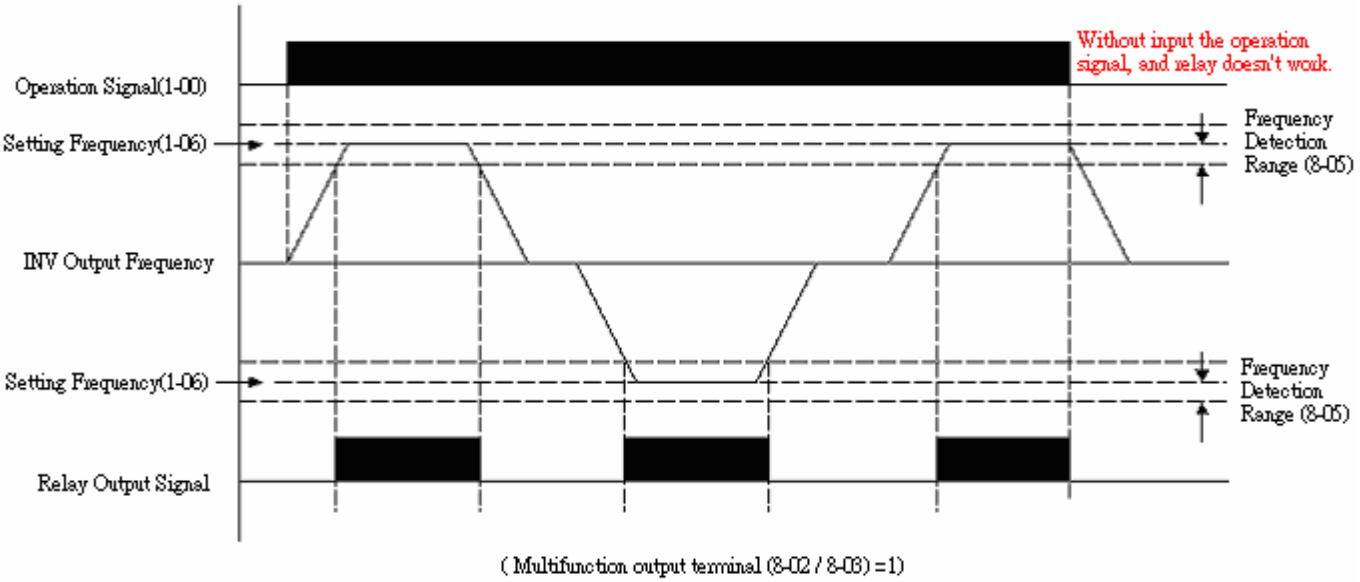
0000: Run
0001: Frequency Reached (Target Frequency) (Set Frequency ± 8-05)
0002: Set Frequency (8-04 ± 8-05)
0003: Frequency Threshold Level (> 8-04) - Frequency Reached
0004: Frequency Threshold Level (< 8-04) - Frequency Reached
0005: Over torque Threshold Level
0006: Fault
0007: Auto-restart
0008: Momentary AC Power Loss
0009: Rapid Stop Mode
0010: Coast-to-Stop Mode
0011: Motor Overload Protection
0012: Drive Overload Protection
0013: PID Feedback Signal Break
0014: PLC Operation
0015: Power On

8-04：Frequency Reached Output Setting =0 ~ 650Hz

8-05：Frequency Output Detection Range =0 ~ 30Hz

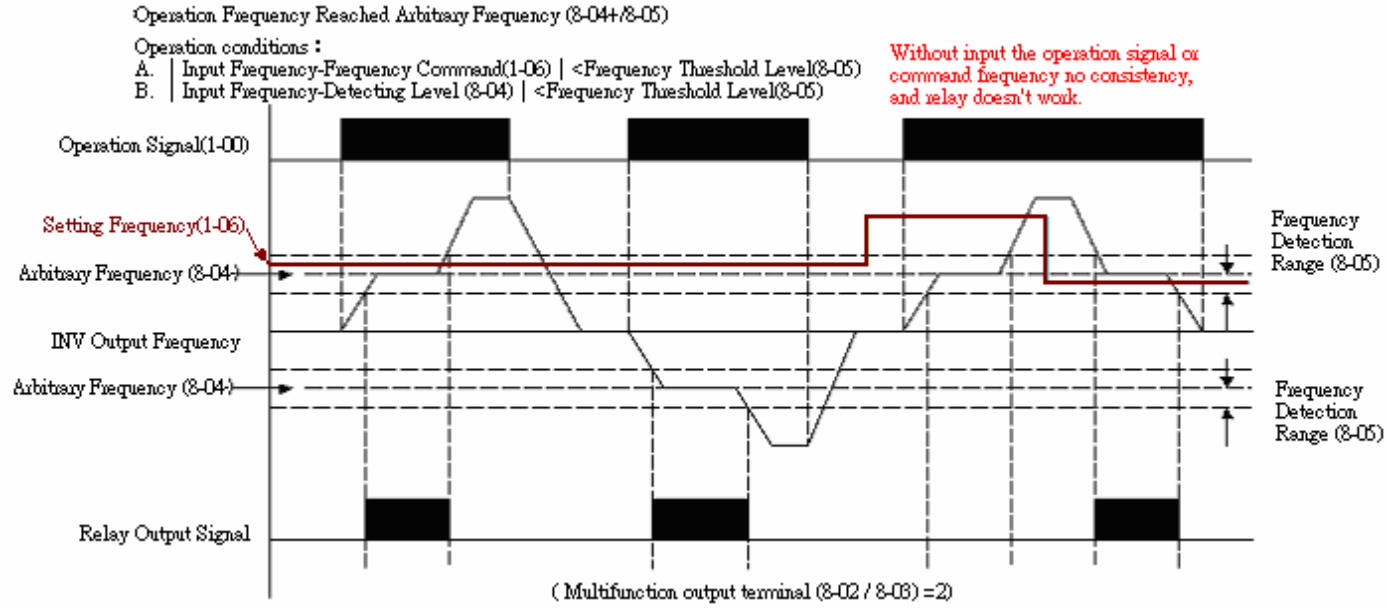
8-02/03= 01 :

The preset frequency is reached (± 8-05)

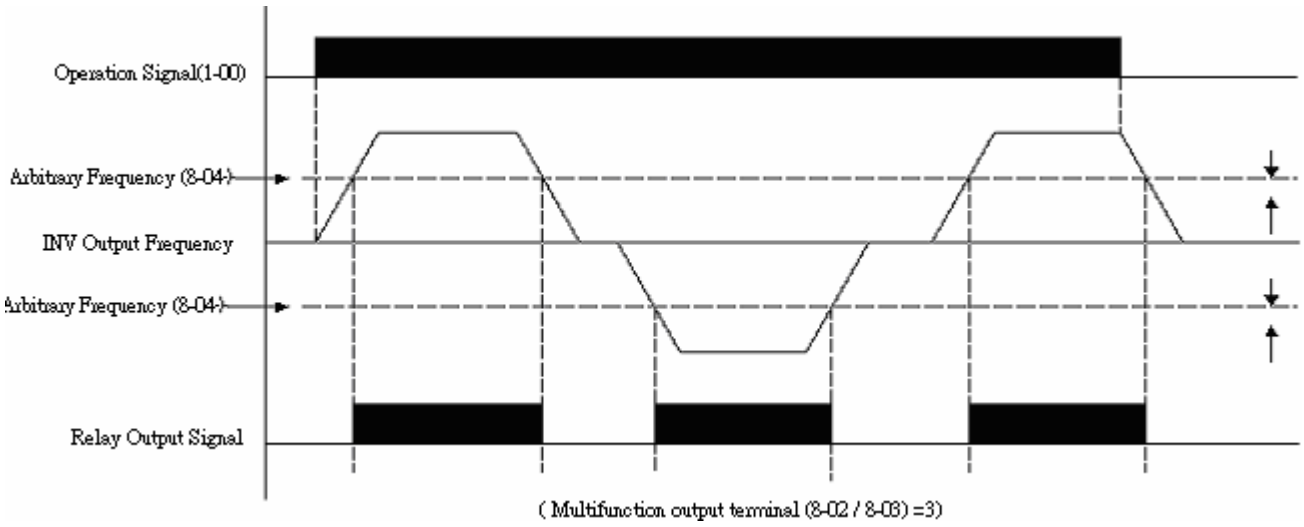


8-02/3= 02 :

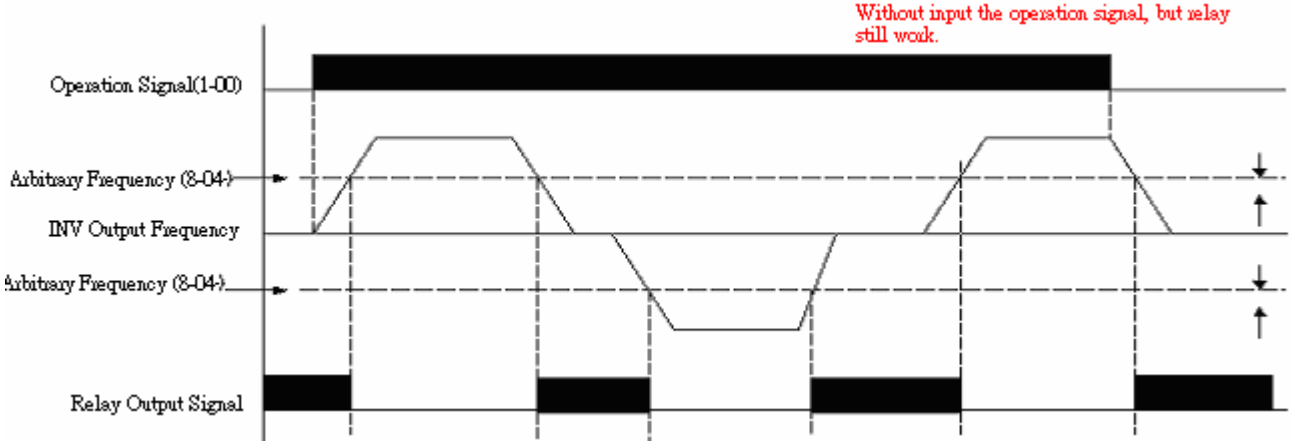
Arbitrary frequency consistency Fout = 8-04 ± 8-05



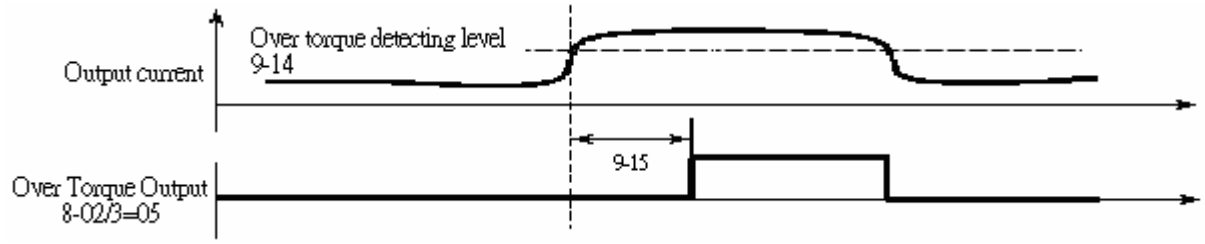
8-02/3 = 03 : frequent detection Fout > 8-04



8-02/3 = 04：frequent detection Fout < 8-04



8-02/3= 05：over torque detection



Parameter Group 9 – Drive and Load Protection Modes

9-00：Trip Prevention Selection During Acceleration:

0000：Enable Trip Prevention During Acceleration

0001：Disable Trip Prevention During Acceleration

9-01：Trip Prevention Level During Acceleration: 50% ~ 300%

9-02：Trip Prevention Selection During Deceleration:

0000：Enable Trip Prevention During Deceleration

0001：Disable Trip Prevention During Deceleration

9-03：Trip Prevention Level During Deceleration: 50% ~ 300%

9-04：Trip Prevention Selection in Run Mode:

0000：Enable Trip Prevention in Run Mode

0001：Disable Trip Prevention in Run Mode

9-05：Trip Prevention Level in Run Mode: 50% ~ 300%

9-06：Trip Prevention Deceleration Time Selection in Run Mode:

0000: Trip Prevention Deceleration Time Set by 3-03
0001: Trip Prevention Deceleration Time Set by 9-07

9-07：Deceleration Time in Trip Prevention Mode (sec): 0.1 ~ 3600.0

1. In acceleration, the inverter will delay the acceleration time if the time is too short resulting in the over current in order to prevent the inverter trips.
2. In deceleration, the inverter will delay the acceleration time if the time is too short resulting in the over voltage of DC VUS in order to prevent the inverter trips with 'OV' displayed.
3. Some mechanical characteristics (such as press) or unusual breakdown (seize due to insufficient lubrication, uneven operation, impurities of processed materials, etc.) will cause the inverter to trip, thus inconvenience users. When the operating torque of the inverter exceeds the setting of 9-05, the inverter will lower the output frequency following the deceleration time set by 9-06, and return to the normal operation frequency after the torque get steady.

9-08：Electronic Motor Overload Protection Operation Mode:

0000：Enable Electronic Motor Overload Protection

0001：Disable Electronic Motor Overload Protection

9-09：Motor Type Selection:

0000：Electronic Motor Overload Protection Set for Non-Inverter Duty Motor

0001：Electronic Motor Overload Protection Set for Inverter Duty Motor

9-10：Motor Overload Protection Curve Selection:

0000：Constant Torque (OL=103%)(150%,1 minute)

0001：Variable Torque (OL=113%)(123%,1 minute)

9-11：Operation After Overload Protection is Activated:

0000：Coast-to-Stop After Overload Protection is Activated

0001：Drive Will not Trip when Overload Protection is Activated (OL1)

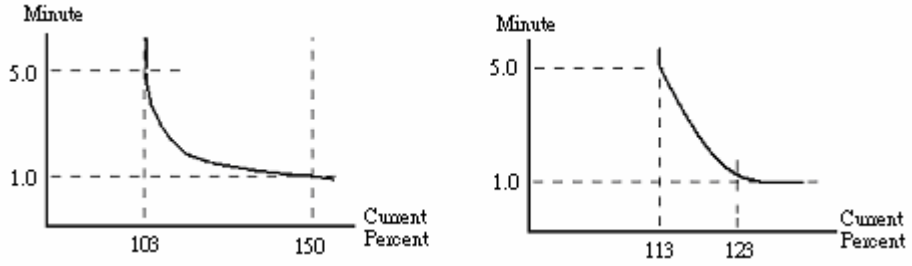
Description of the thermal relay function:

1. 9-10 = 0000：protect the general mechanical load, the load is less than 103% rated current, the motor continue to run. The load is larger than 150% rated current, the motor will run for 1 minute.(Refer to following curve(1).

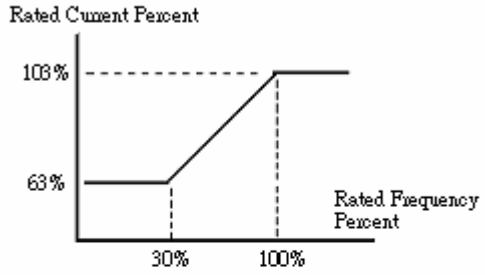
   = 0001：protect HVAC load(FAN、PUMP…so on)：the load is less than 113% rated current, the motor continue to run. The load is larger than 123% rated current, the motor will run for 1 minute.
2. The heat sinking function will declining when the motor run at low speed. So the thermal relay action level will decline at the same time.(The curve 1 will change to curve 2).
3. 9-09 = 0000：set 0-05 as the rated frequency of the serve motor.

   9-11 = 0000：the inverter coast to stop as the thermal relay acts and flash OL1. Press the 'reset' or the external reset terminal to continue to run

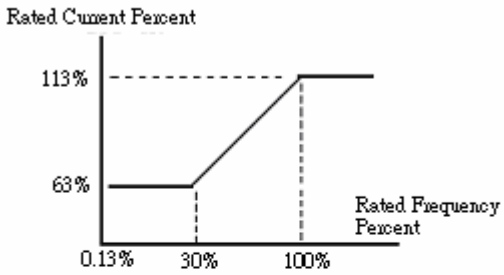
   = 0001：the inverter continues to run as the thermal relay acts and flash OL1. Till the current decline to 103% or 113%(determined by 9-10), OL1 will disappear.



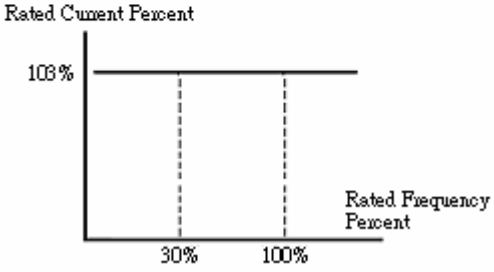
Electronic Motor Overload OL1 protection current and frequency



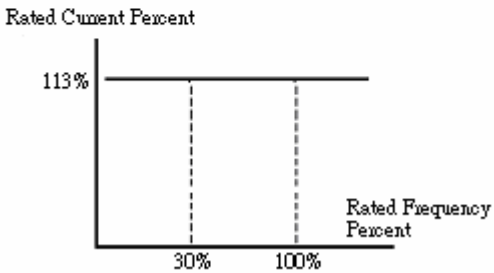
Non-Inverter Duty Motor OL1 Protection Curve
OL=103% Start, 150%/1 Min.



Non-Inverter Duty Motor OL1 Protection Curve
OL=113% Start, 123%/1 Min.



Inverter Duty Motor OL1 Protection Curve
OL=103% Start, 150%/1 Min.



Inverter Duty Motor OL1 Protection Curve
OL=113% Start, 123%/1 Min.

9-12：Over Torque Detection Selection:

= 0000：Disable Over Torque Operation

= 0001：Enable Over Torque Operation Only if at Set Frequency

= 0002：Enable Over Torque Operation while the Drive is in Run Mode

9-13：Operation After Over Torque Detection is Activated:

= 0000：Drive will Continue to Operate After Over Torque is Activated

= 0001：Coast-to-Stop After Over Torque is Activated

9-14：Over Torque Threshold Level (%)：30-200%

9-15：Over Torque Activation Delay Time (s)：0.0-25.0

The over torque is defined as: the output torque is inside parameter 9-15, the voltage level(the inverter rated torque is 100%) is over 9-14 parameter.

9-13 = 0000：If there is over torque, the inverter can continue to run and flashes OL3 till the output torque is less than the 9-14 setting value.

= 0001：If there is over torque, the inverter coasts to stop and flashes OL3. it is necessary to press 'RESET' or external terminal to continue to run.

Parameter8-02,03(Multifunction output terminal) = 05, the output terminal is output over torque signal.

※Note: Over torque output signal will be output as the parameter 9-12=0001or 0002 when the level and time are over the range.

Parameter Group 10 – Volts /Hz Pattern Operation Mode

V/F PATTERN Selection

10-0：V/F PATTERN Selection = 0 – 18

10-1：Torque boost gain(V/F pattern modulation)% = 0.0 – 30.0%

10-2：Motor no load current(Amps AC) ----------

10-3：Motor rated slip compensation(%) = 0.0 – 100.0%

10-4：Max output frequency(HZ) = 0.20 – 650.0Hz

10-5：Max output frequency voltage ratio(%) = 0.0 – 100.0%

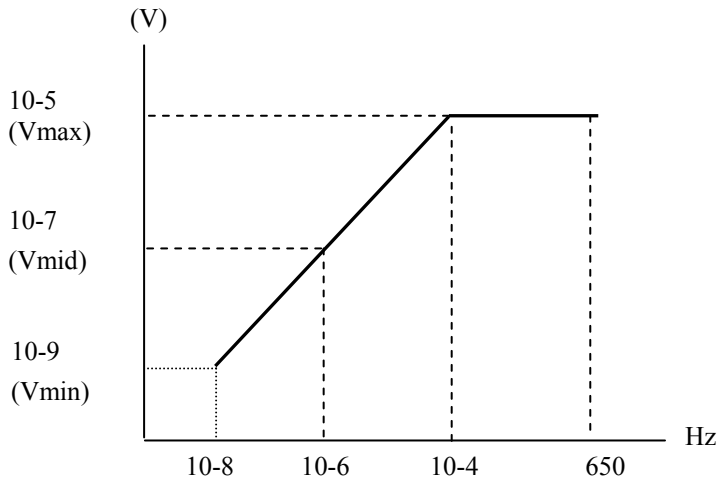
10-6：Medium frequency(HZ) = 0.10 –650.0Hz

10-7：Medium output frequency voltage ratio (%) = 0.0 – 100.0%

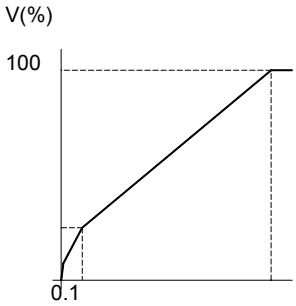
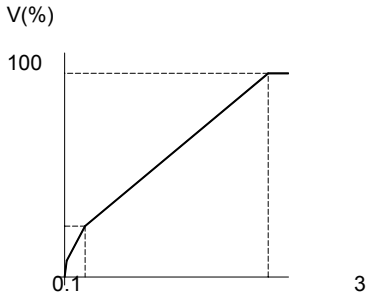
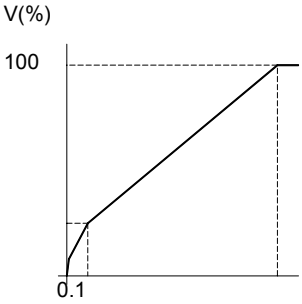
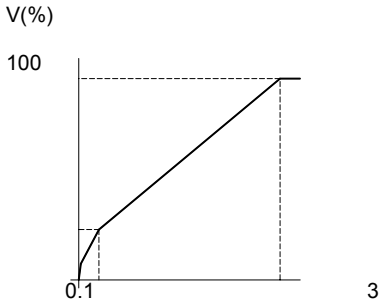
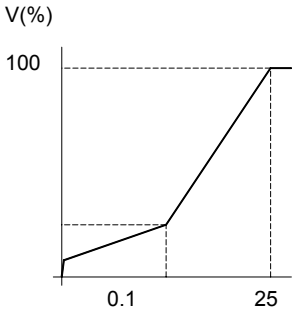
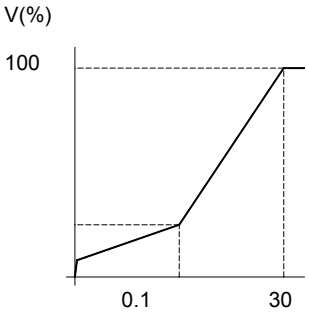
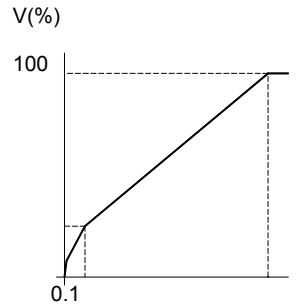
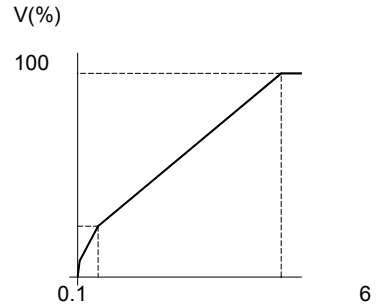
10-8：Min output frequency(HZ) = 0.10 –650.0Hz

10-9：Min output frequency voltage ratio (%) = 0.0 – 100.0%

1. 10-0=18, set the V/F pattern freely complying with 10-4~10-9 (Refer to following diagram)

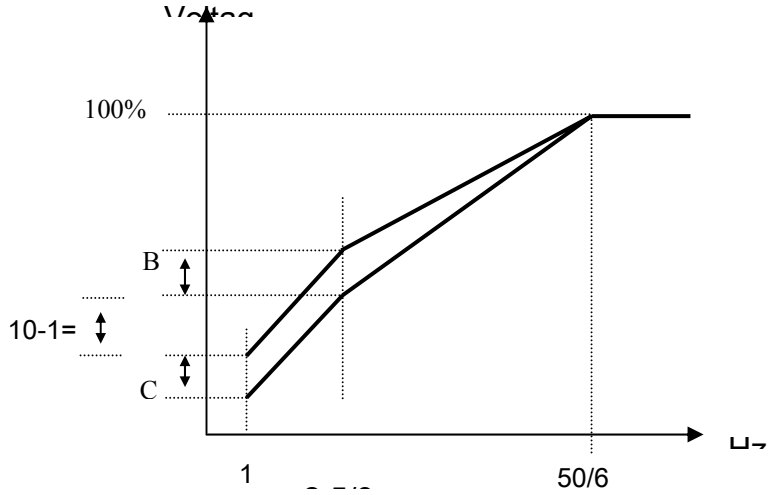


2. 10-0 = 0 – 17 V / F Pattern (Refer to following list)。

Netz-freq.		10-0	V/f-Modell	Netz-freq.		10-0	V/f-Modell
50Hz	Standardanwendung	0		60Hz	Standardanwendung	9	
	Hohes Anzugsdrehmoment	1 2 3			Hohes Anzugsdrehmoment	10 11 12	
	Variables Drehmoment	4 5			Variables Drehmoment	13 14	
	Konstantes Drehmoment	6 7 8			Konstantes Drehmoment	15 16 17	

10-0	B	C
0 / 9	50.0%	1.0%
1 / 10	60.0%	1.0%
2 / 11	65.0%	1.0%
3 / 12	70.0%	1.0%
4 / 13	40.0%	1.0%
5 / 14	35.0%	1.0%
6 / 15	45.0%	1.0%
7 / 16	55.0%	1.0%
8 / 17	65.0%	1.0%

3. The inverter will output the value that B, C voltage (refer to 10-0) plus 10-1 V/F pattern setting. And the start torque will be raised.



※Note: 10-1=0, Torque boost function is invalid

4. When the induction motor is in running, there must be slip due to the load. It is necessary to boost to improve the precision of the speed.

$$\text{Slip frequency boost} = \frac{\text{Output Current-(10-2)}}{\text{(0-02)-(10-2)}} \times \text{(10-3)}$$

Note : 0-02=motor rated current
10-2=motor no load current

10-3 rough value= (Motor synchronization speed– Rated speed) / Motor synchronization speed

Marked on the motor nameplate

$$\text{Motor synchronization speed (RPM)} = \frac{120}{\text{Motor Poles}} \times \text{Motor rated frequency (50Hz or 60Hz)}$$

eg: 4 Poles , 60Hzinduction motor synchronization speed = $\frac{120}{4} \times 60 = 1800$ RPM

※Note: Motor no load current(10-2) differs with the inverter capacities(15-0)(Refer to 0-02 note) , It should be regulated according to the actual condition.

Parameter group 11 - PID operation mode

11-0：PID Operation Selection

0000: PID disable
0001: PID enable (Deviation is D-controlled)
0002: PID Feedback D-controlled
0003: PID D Reverse characteristic controlled
0004: PID Feedback D characteristic controlled
0005: PID, Frequency command + D controlled
0006: PID, Frequency command + Feedback D controlled
0007: PID, Frequency Command + D reverse Characteristic controlled.
0008: PID, Frequency Command + Feedback D reverse Characteristic controlled.

11-0 =1, D is the deviation of (target value –detected value) in the unit time (11-4).
=2, D is the deviation of the detected values in unit time (11-4).
=3, D is the deviation of (target value – detected value) in the unit time (11-4). If the deviation is positive, the output frequency decreases, vice versa.
=4, D is the deviation of detected value in unit time (11-4). When the deviation is positive, the frequency decreases, vice versa.
=5, D is equal to the deviation of (target value – detected value) in unit time (11-4) +Frequency command.
=6, D is equal to the deviation of detected values in unit time + Frequency command.
=7, D is equal to the deviation of (target value – detected value) in unit time +Frequency command. If the deviation is positive, the output frequency decreases, vice versa.
=8, D is equal to the deviation of detected values in unit time + Frequency command. When the deviation is positive, the frequency decreases, vice versa.

11-1：Feedback Calibration Gain(%) ： 0.00 - 10.00

11-1 is the calibration gain. Deviation = (target value – detected value) × 11-1

11-2：Proportion Gain(%) ： 0.00 - 10.00

11-2：Proportion gain for P control.

11-3：Integrate Time（s） ：0.0 - 100.0

11-3：Integrate time for I control

11-4：Differential Time（s） ：0.00 - 10.00

11-4：Differential time for D control

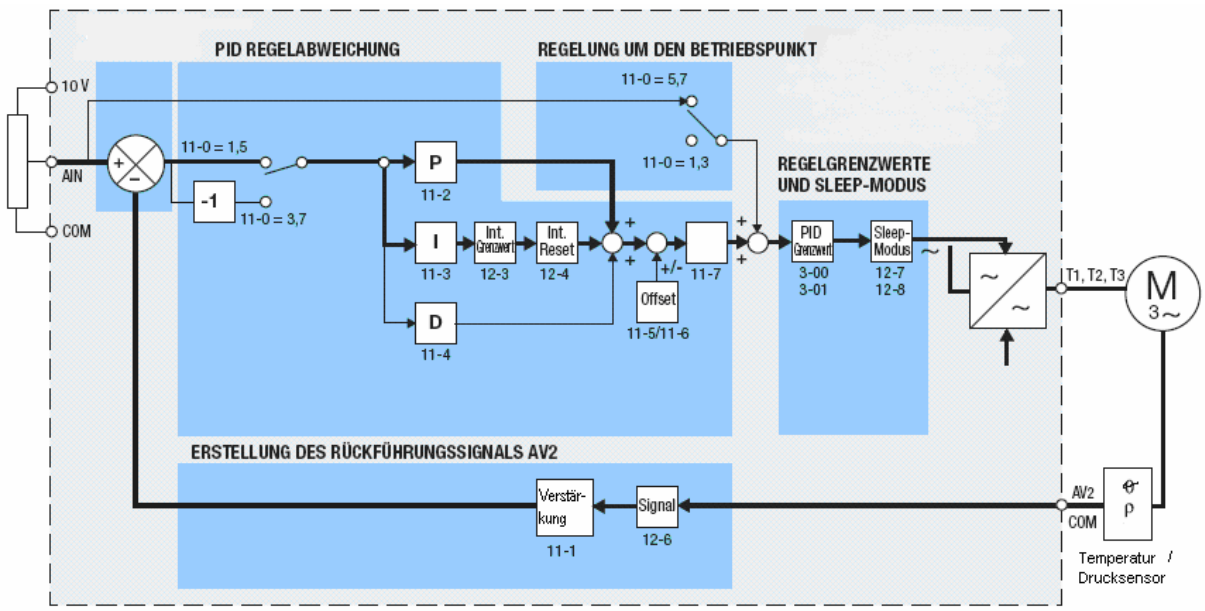
11-5: PID Offset : 0000 : Positive Direction
0001 :Negative Direction
11-6: PID Offset Adjust (%) : -109% ~ +109%

11-5/11-6：PID the calculated result pluses 11-6 (the sign of 11-6 is determined by 11-5).

11-7：Output Lag Filter Time (s) ：0.0 - 2.5

11-7：update time for output frequency.

※Note: PID Function is available for controlling the output flow, external fan flow and temperature.
The controlling flow is as follow:



1. Performing PID control, set 5-05=23, AI2 (S6) on TM2 as PID feedback signal.
2. The target value of above diagram is the 1-06 input frequency.
3. There are two ways to see the PID feedback signal, one is using the Keypad switch display (4-06 must be setting as 1), the other is using analog output FM+ (8-00 must be setting as 5).

Parameter Group 12 - PID "Limits" and "Out of Range" Mode

12-0：Feedback Loss Detection Mode: 0000:Disable

0001:Enable – Drive Continues to Operate After Feedback Loss
0002:Enable – Drive "STOPS" After Feedback Loss

12-0= 0：Disable; 12-0= 1：detect to run and display PDER；12-0= 2：detect to stop and display PDER。

12-1：Feedback Loss Detection Mode (%)：0 - 100

12-1is the level for signal loss. Deviation = Command value – Feedback value. While the deviation is larger than the loss level, the feedback signal is lost.

12-2：Feedback Loss Detection Delay Time (s)：0.0 -25.5

12-2：the action lay time as the feedback signal lost.

12-3：Integrate Limit Value (%)：0 - 109

12-3：the Limiter to prevent PID saturating.

12-4：Integrator Reset to 0 when Feedback Signal Equals the Intended Value:

0000:Disable
0001:1 second
0030: 30 seconds

12-4=0：As PID feedback value reaches the command value, the integrator will not be reset to 0.

12-4=1~30：As PID feedback value reaches the target value, reset to 0 in 1~30 seconds and inverter stops output. The inverter will output again as the feedback value differs from the target value.

12-5：Allowable Integration Error Margin (Unit Value) (1 Unit = 1/8192)：0 - 100

12-5=0 ~ 100% unit value：restart the tolerance after the integrator reset to 0.

12-6：PID Feedback Signal：0000: 0~10V or 0~20mA

0001: 2~10V or 4~20mA

12-6：Feedback signal selection, 12-6=0：0~10V or 0~20mA (signal V or I decide to SW2)

12-6=1：2~10V or 4~20mA(signal V or I decide to SW2)

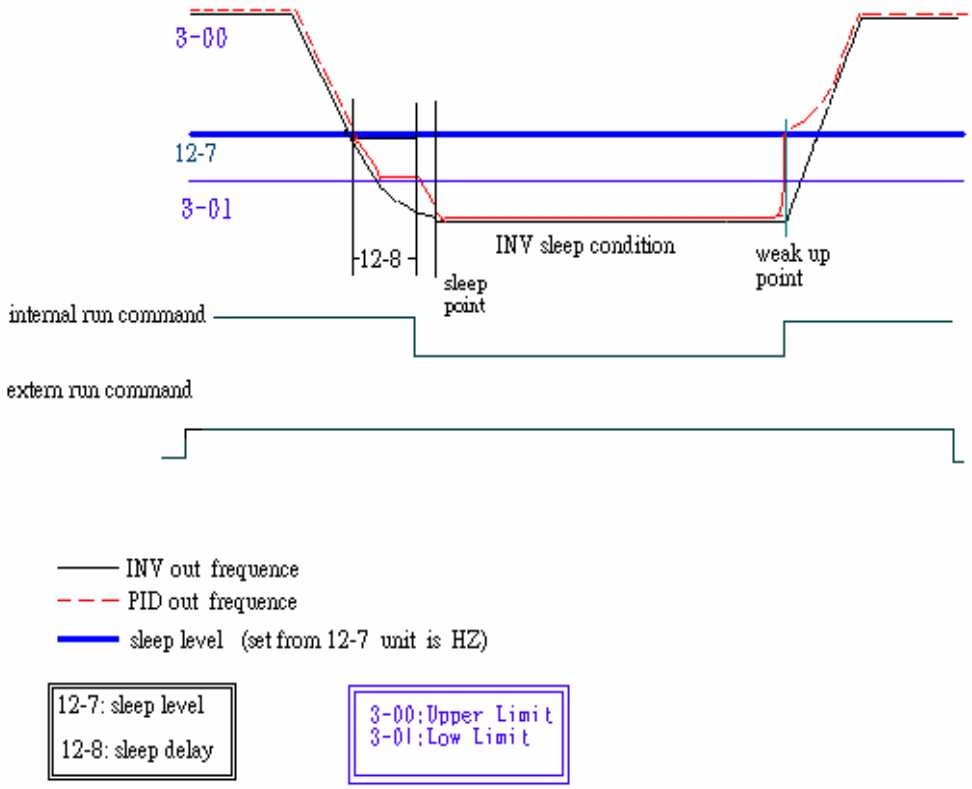
12-7, 12-8：PID Sleep Mode

PID SLEEP MODE:
11-0=1(PID Enable)
5-05=20(PID FEEDBACK Enable)
1-06=PID setting frequency source (Target Value)

12-7 Set the frequency for sleep start, Unit：HZ

12-8 Set the Time for sleep delay, Unit：sec

When PID output frequency is less than the frequency for sleep start and the reaches the time of sleep delay, the inverter will decelerate to 0 and enter PID sleep mode.
When PID output frequency is larger than the frequency for sleep start the inverter will be awaked and enter PID awake mode. The time diagram is as follow:



Parameter Group 13 - Communication mode

13-0：Assigned Communication Station Number：1 - 254

13-0: to set the communication station codes which are suitable for driving more than one inverters situations.

13-1：Baud Rate setting (bps)： 0000: 4800

0001: 9600
0002: 19200
0003: 38400

13-2：Stop Bit Selection：0000: 1 stop bit

0001: 2 stop bit

13-3：Parity Selection ：0000 : no parity

0001 : even parity
0002 : odd parity

13-4：Data Format Selection：0000 :8 bit data

0001 :7 bit data

1.RS-485 Communication：

(1)1 vs 1 Controlling：to control one inverter by a PC or PLC or controller.(set 13-0 = 1~254)

(2)1 vs more Controlling：to control more than one inverters by PC or PLC or Controller (The max number of inverter could be 254. set 13-0 = 1~254), when the inverter receives the communication station code = 0, the communication controlling is acceptable regardless the setting value of 13-0.

2. RS-232communication: (RS232 interface is required)
1vs1 controlling: to control one inverter by a PC or PLC or controller. (Set 13-0 = 1~254)

※Note:

a. The BAUD RATE (13-1) of PC (or PLC or Controller) and the one of the inverter should be set as the same .Communication format (13-2/13-3/13-4) should be set as the same.
b. The inverter will confirm the parameter efficient as PC modifies the parameter of the inverter.
c. Please refer to the 7300CV Communication PROTOCOL.

Parameter Group 14 - Auto Tuning

14-0：Stator Resistance(Ohms) Gain

14-1：Rotator Resistance(Ohms) Gain

14-2：Equivalent Inductance(mH) Gain

14-3：Magnetized Current(Amps AC) Gain

14-4：Ferrit Loss Conduction (gm) Gain

1. If 0-00=0 or 1(vector mode) is selected, as power ON, set 0-06=1, the motor will run as the inverter performs auto tuning. As the motor stop, it means that auto tuning finished. The inverter will write the internal parameter of the motor to 14-0~ 14-4, and auto reset the 0-06 as 0.
2. Auto tuning must be carried out as long as the motor changed. If the internal parameters is known already, they can be input to 14-0~14-4 directly.
3. 0-06=1 ， to perform auto tuning, after finished, 0-06 auto reset to 0, the Keypad displays END.
4. The parameter group only affect the current vector.

Parameter Group 15 - Operation Status and Function Reset

15-0：Drive Horsepower Code

15-0	Inverter Model	
2P5	JNTHBCBA	R500AC/BC
201		0001AC/BC
202		0002AC/BC
203		0003AC/BC
205		0005BC
208		7R50BC
210		0010BC
215		0015BC
220		0020BC
225		0025BC
230		0030BC
240		0040BC

15-0	Inverter Model	
401	JNTHBCBA	0001BE
402		0002BE
403		0003BE
405		0005BE
408		7R50BE
410		0010BE
415		0015BE
420		0020BE
425		0025BE
430		0030BE
440		0040BE
450		0050BE
460		0060BE
475		0075BE

15-1：Software Version

15-2：Fault Jog（Latest 3 times）

1. When the inverter doesn't work normally, the former fault log stored in2.xxxx will be transferred to 3.xxxx, then, the one in 1.xxxx to 2.xxxx. The present fault will be stored in the blank 1.xxxx. Thusly, the fault stored in 3.xxxx is the earliest one of the three, while the one 1.xxxx is the latest.
2. Enter 15-2, the fault 1.xxxx will be displayed firstly, press▲, you can read 2.xxx→3.xxx→1.xxx, whereas▼, the order is 3.xxx→2.xxx→1.xxx→3.xxx.
3. Enter 15-2, the three fault log will be cleared as the reset key is pressed. The log content will changed to 1.--- ，2.--- ，3.---.

4. E.g. if the fault log content is '1.OCC' which indicates the latest fault is OC-C, and so on.

15-3：Accumulated Operation Time 1 (Hours): 0 – 9999

15-4：Accumulated Operation Time 2 (Hours X 10000): 0 - 27

15-5：Accumulated Operation Time Mode: 0000: Power on time

0001: Operation time

1. When the operation time is to 9999 as the operation duration 1 is set. The next hour will be carried to operation duration 2. Meanwhile, the recorded value will be cleared to 0000, and the record value of operation duration 2 will be 01.
2. Description of operation time selection:

Preset value	Description
0	Power on, count the accumulated time.
1	Inverter operation, count the accumulated operation time

15-6：Reset the factory setting: 1110: Reset the 50Hz factory setting

1111: Reset the 60Hz factory setting

1112: Reset PLC program

As 15-6 is set as 1111, the parameter will be reset to factory setting. The max output voltage will comply with the voltage and frequency (0-01/0-05) on the nameplate of the motor. The output frequency is 60Hz if the upper frequency limit is not set.

※Note:

Motor parameters (14-0~14-4) will be modified under V/F control mode when reset factory setting. On the contrary, motor parameters (14-0~14-4) will not be modified under vector control mode when reset factory setting.

4.5 Specification Description on Built-in PLC Function

7300CV has Built-in simple PLC function, user can download Ladder Diagram from PC (Windows base software) or PDA (WinCE base software) very friendly.

4.5.1 Basic Instruction

				P			NO / NC
Input Instruction					I	i	I1~I7 / i1~i7
Output Instruction	Q	Q	Q	Q	Q	q	Q1~Q2 / q1~q2
Auxiliary Instruction	M	M	M	M	M	m	M1~MF / m1~mF
Special Register							V1~V7
Counter Instruction	C				C	c	C1~C4 / c1~c4
Timer Instruction	T				T	t	T1~T8 / t1~t8
Analog Comparing Instruction	G				G	g	G1~G4 / g1~g4
Encoder Comparing Instruction	H				H	h	H1~H4 / h1~h4
Operation Instruction	F				F	f	F1~F8 / f1~f8

Description for Special Register

V1: Setting Frequency Range: 0.1~650.0Hz
V2: Operation Frequency Range: 0.1~650.0Hz
V3: AIN Input value Range: 0~1000
V4: S6 Input Value Range: 0~1000
V5: Keypad VR Input Value Range: 0~1000
V6: Operation Current Range: 0.1~999.9A
V7: Torque Value Range: 0.1~200.0%

	Upper differential	**Lower differential**	**Other Instruction Symbol**
Differential Instruction	D	d	
SET Instruction			
RESET Instruction			
P Instruction			P

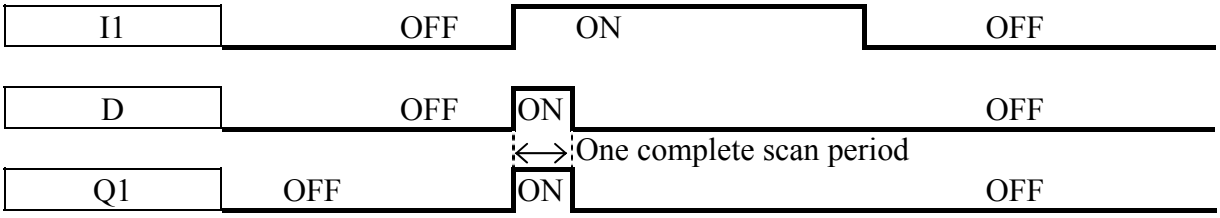
Open circuit (On status)	“ ”	
Short circuit (Off status)	“ -- ”	

Connection symbol	**Description**
─	Connecting left and right Components
┴	Connecting left, right and upper Components
┼	Connecting left, right, upper and lower Components
┬	Connecting left, right and lower Components

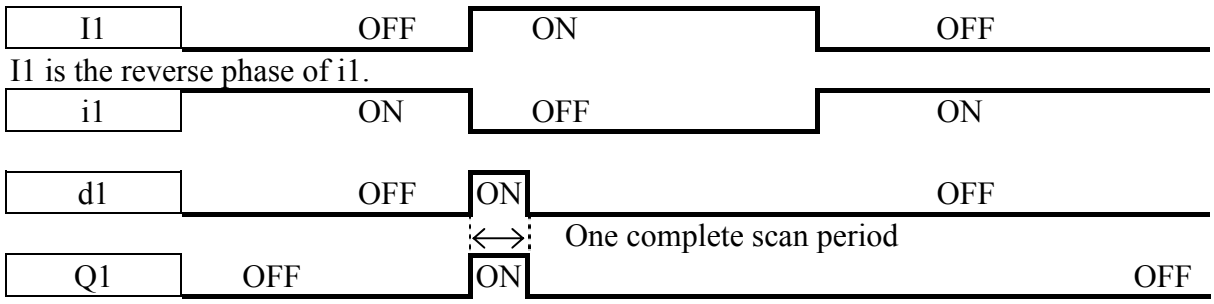
4.5.2 Function of Basic Instruction

□ Function D (d) Command

Sample 1: I1─D ──[Q1

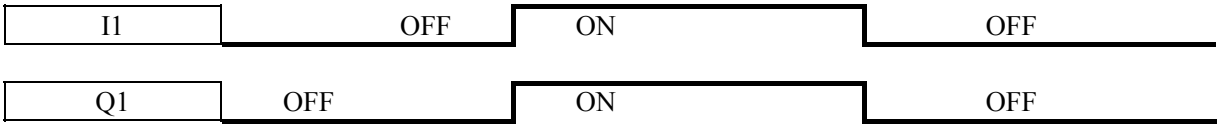


Sample 2: i1─d ──[Q1



□ NORMAL (- [ ) Output

I1 ── [Q1

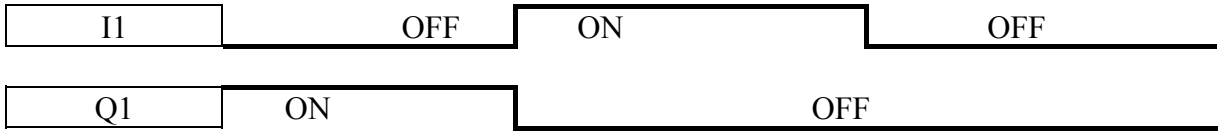


◎ SET (∧) Output

I1 ── ∧Q1

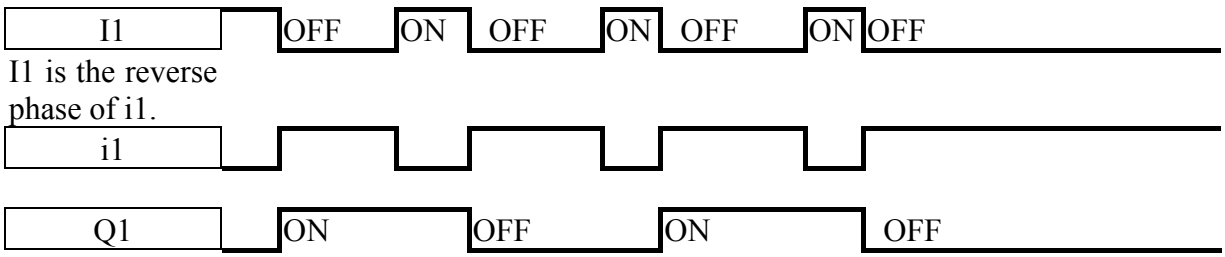
□ RESET (∨) Output

I1 ── ∨Q1



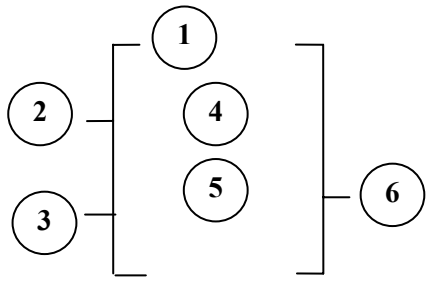
□ P Output

i1 ──PQ1



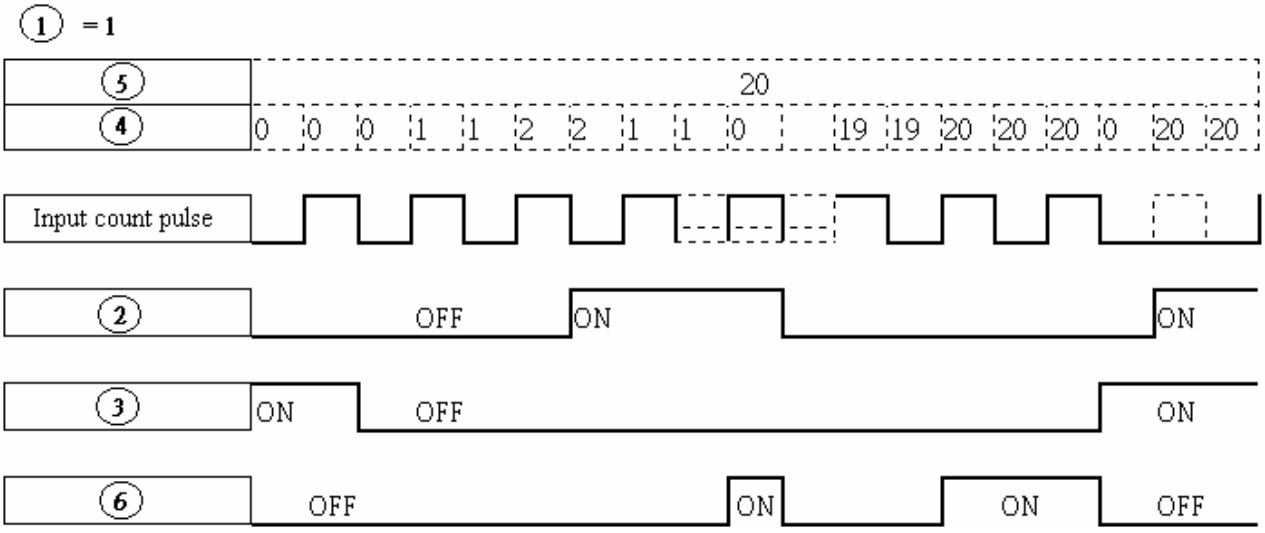
4.5.3 Application Instructions

 Counter



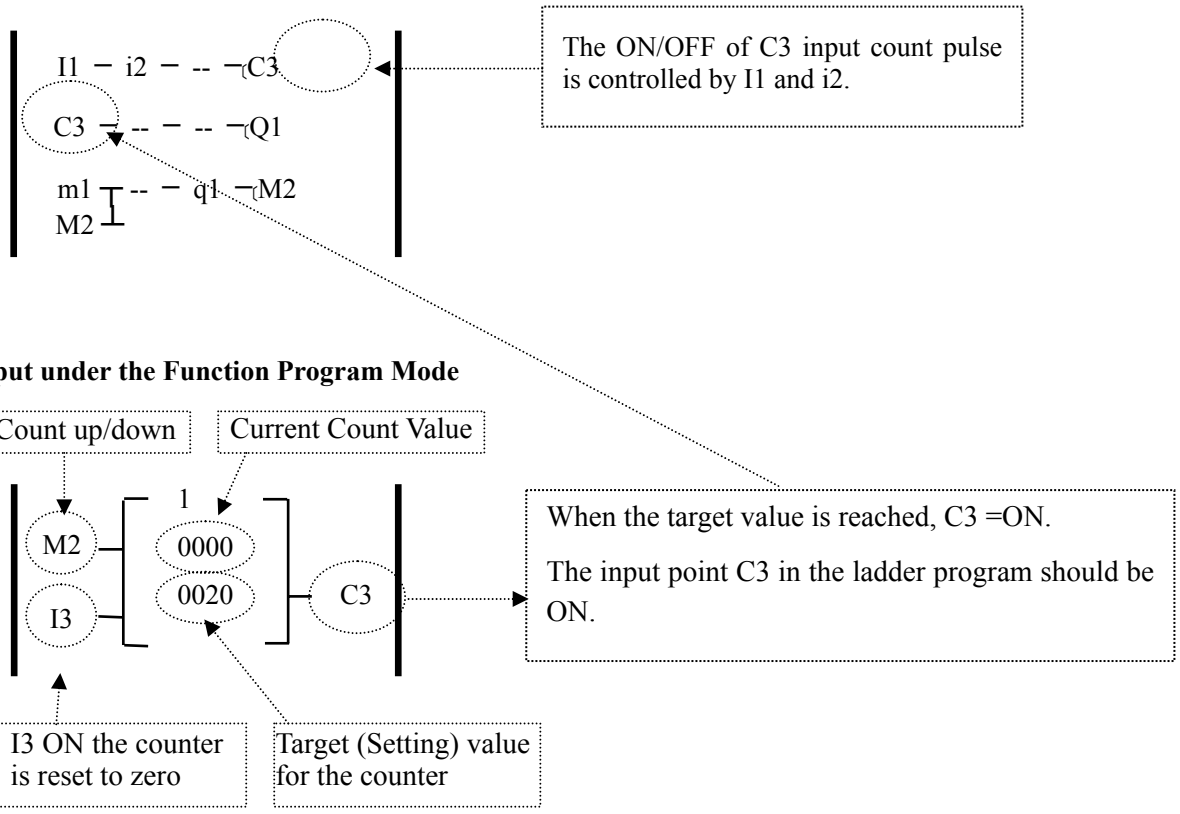
Symbol	Description
①	Counting Mode (1-4)
②	Use (I1 ~ f8) to set counting up or counting down OFF: counting up (0, 1, 2, 3, 4….) ON: counting down (….3, 2, 1, 0)
③	Use (I1 ~ f8) to RESET the counting value ON: the counter is initialized to zero and ⑥ OFF OFF: the counter continues to count
④	Preset Counting Value
⑤	Target (Setting) Value
⑥	Code of the counter (C1 ~ C4 total: 4 groups).

(1) Counter Mode 1



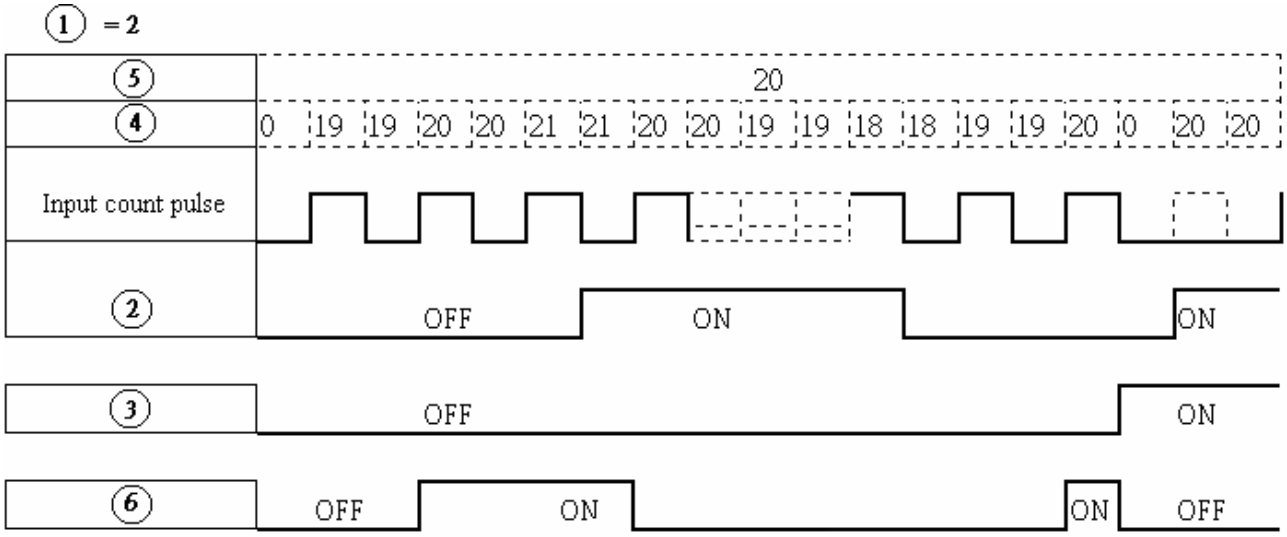
Sample:

Input under the Ladder Program Mode



Input under the Function Program Mode

(2) Counter Mode 2

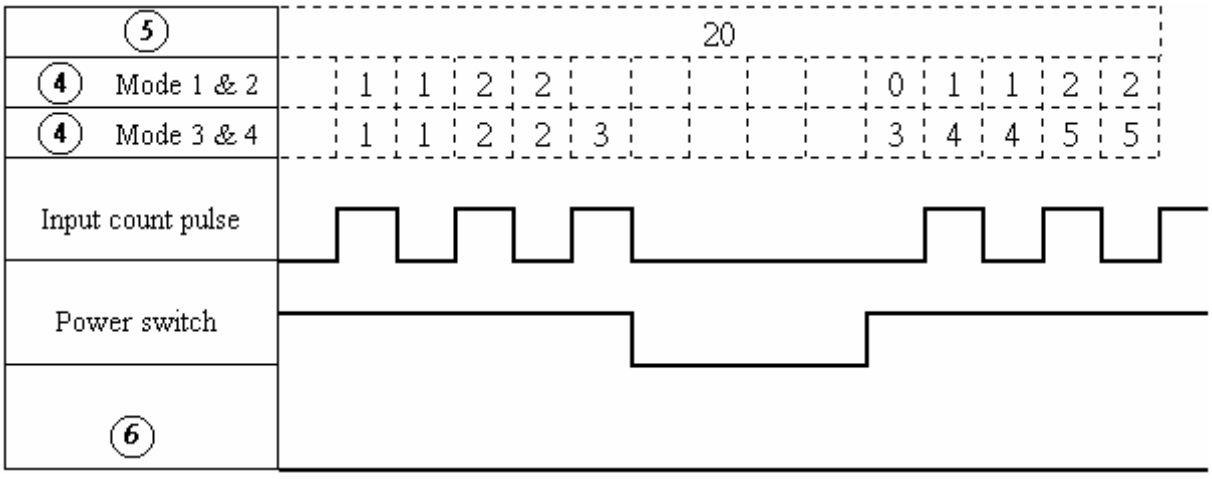


※Note:

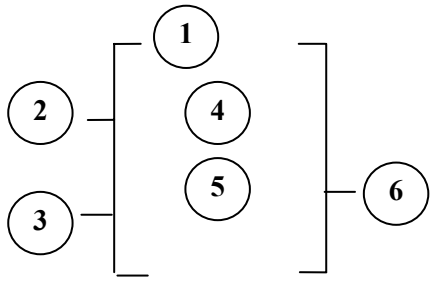
Under this Mode, the counting preset value appeared will be greater than 20, unlike the Mode 1 in which the value is locked at 20.

(3) The counter Mode 3 is similar to the counter Mode 1 except that the former can memory the recorded value after the power is cut off and continued counting when the power is turned on at the next time.

(4) The counter Mode 4 is similar to the counter Mode 2 except that the former can memory the recorded value after the power is cut off and continued counting when the power is turned on at the next time.

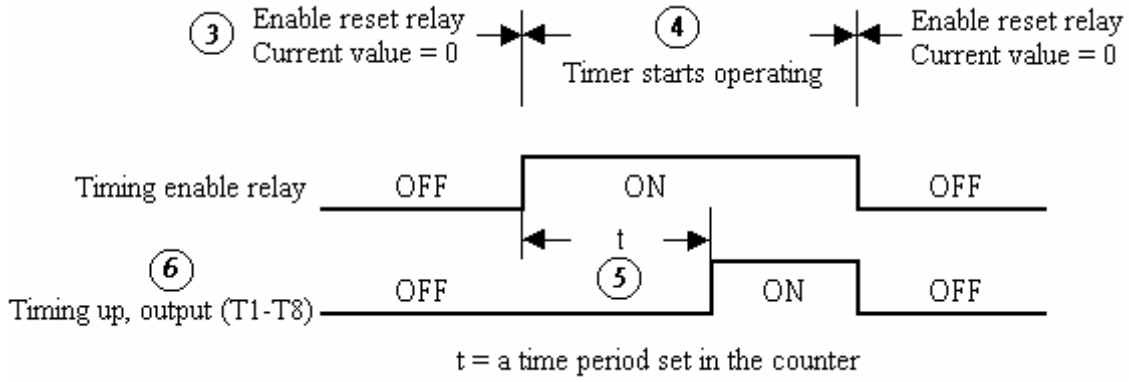


 Timer



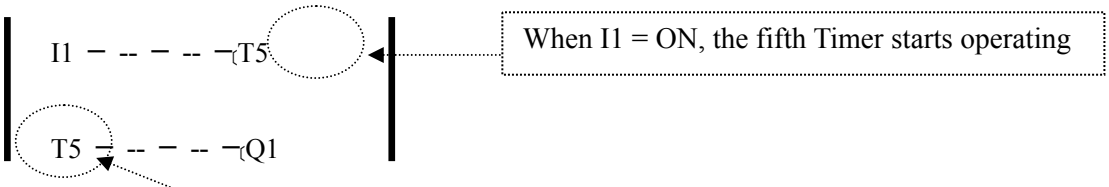
Symbol	Description
①	Timing Mode (1-7)
②	Timing unit 1: 0.0 – 999.9 sec 2: 0 – 9999 sec 3: 0 – 9999 min
③	Use (I1 ~ f8) to RESET the timing value. ON: the counter is reset to zero and ⑥ OFF OFF: the counter continues to count
④	Preset Timing Value
⑤	Target (setting) Timing Values
⑥	The code of the Timer (T1 ~T8 total: 8 groups).

(1) Timer Mode 1 (ON-Delay A Mode)

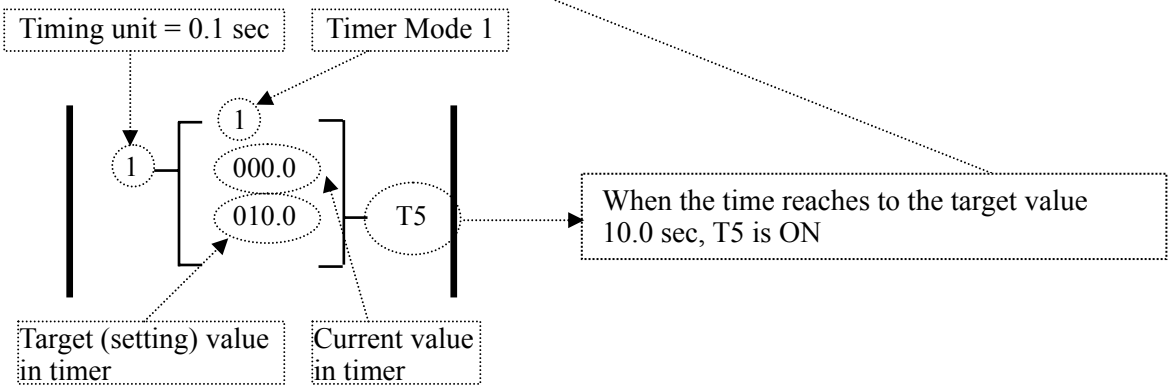


Sample:

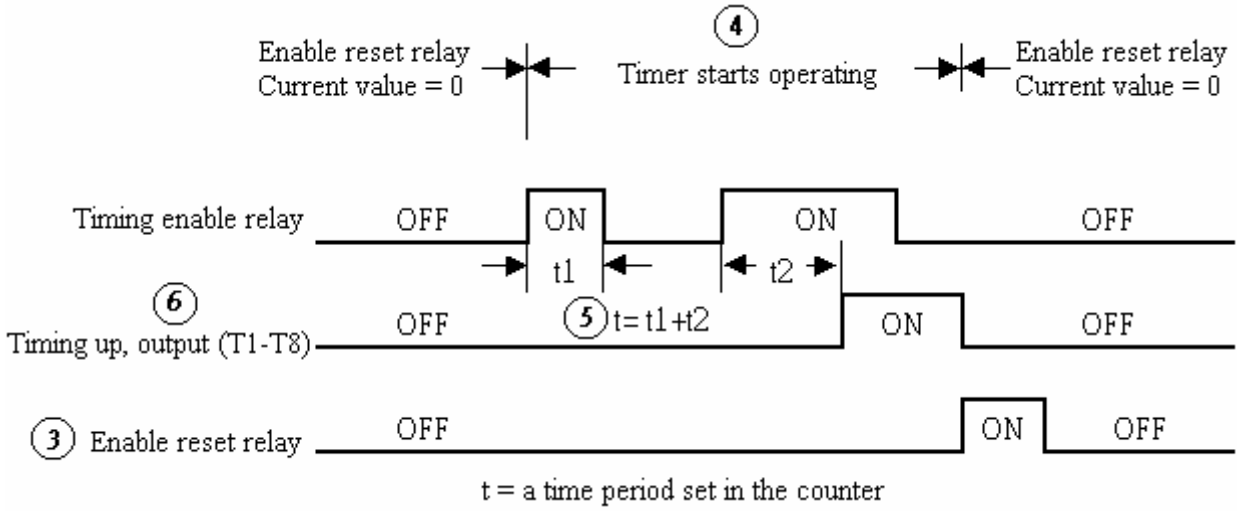
Input under the Ladder Program Mode



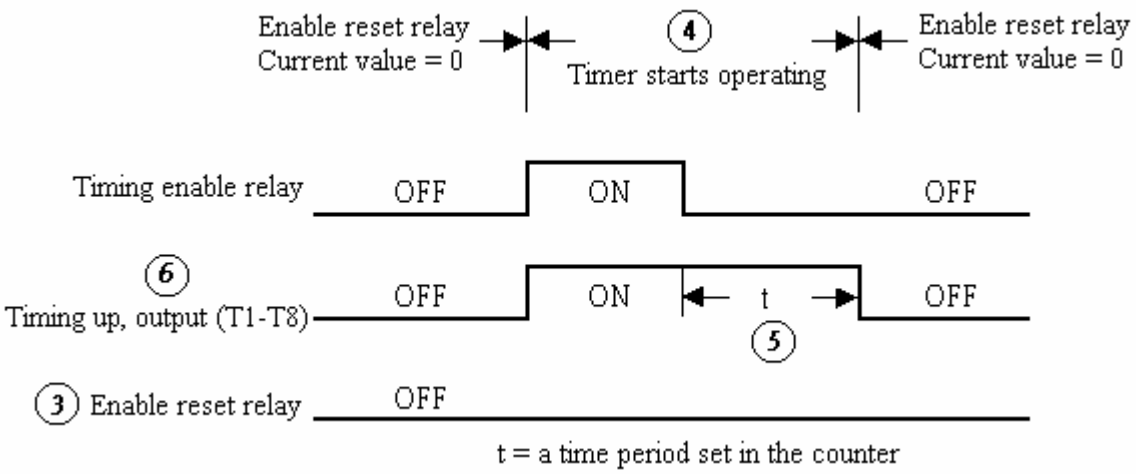
Input under the Function Program Mode

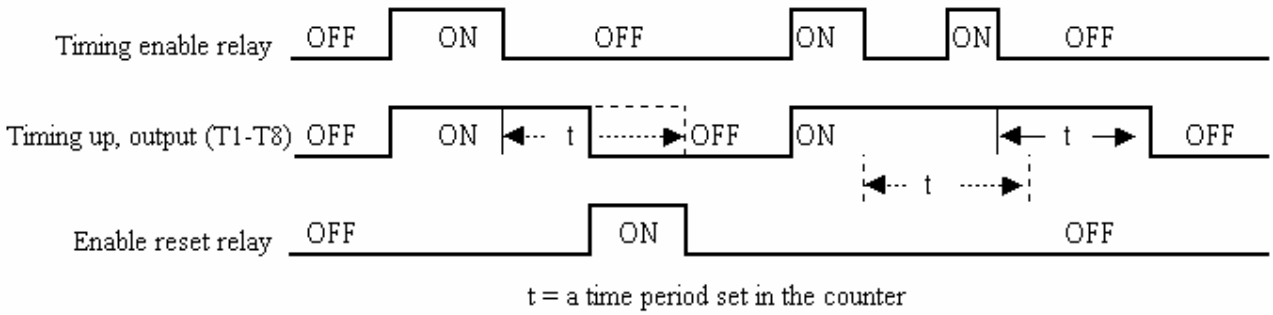


(2) Timer Mode 2 (ON-Delay B Mode)

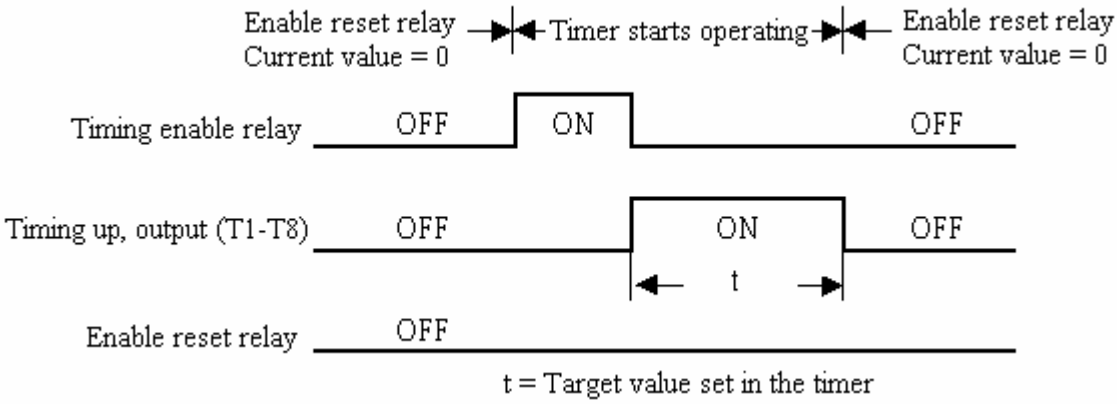


(3) Timer Mode 3 (OFF-Delay A Mode)

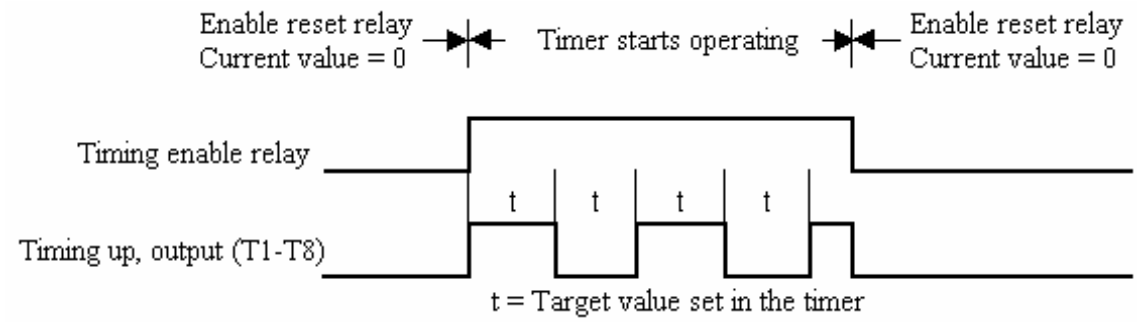




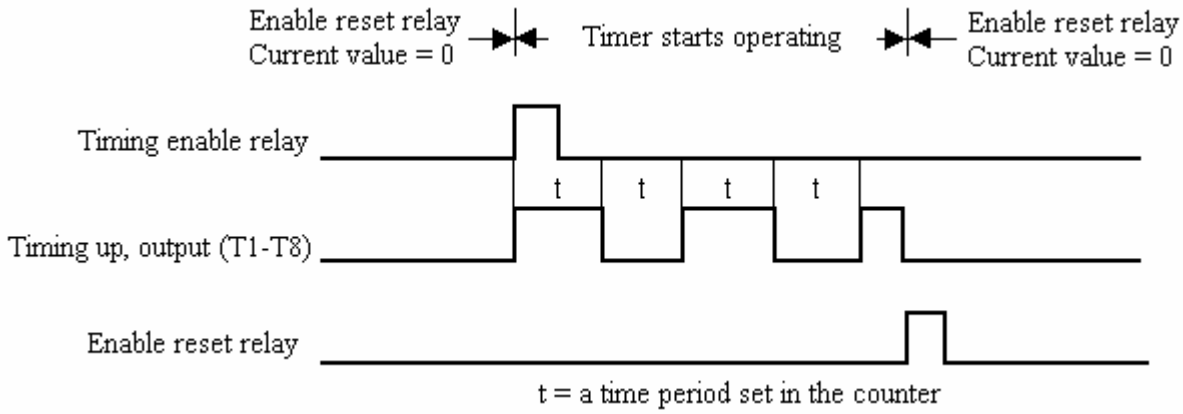
(4) Timer Mode 4 (OFF-Delay B Mode)



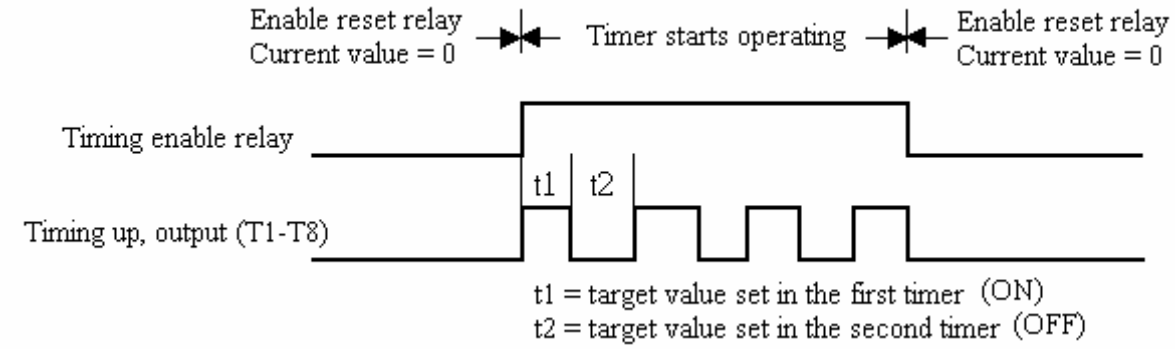
(5) Timer Mode 5 (Flash A Mode)



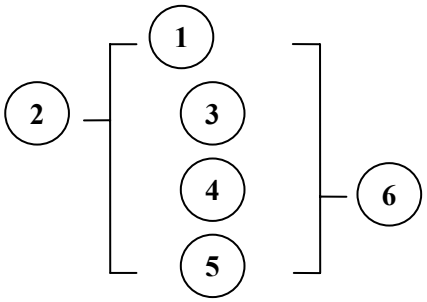
(6) Timer Mode 6 (Flash B Mode)



(7) Timer Mode 7 (Flash C Mode)



 Analog comparator



Symbol	Description
①	Analog comparison mode (1-3)
②	Selection of the input comparison value
③	Analog input value
④	Setting reference comparison value (upper limit)
⑤	Setting reference comparison value (lower limit)
⑥	Output terminals of analog comparator (G1-G4)

Analog Comparison Mode (1-3)

(1) Analog comparator mode 1 (③ ≤ ⑤, ⑥ ON)

(2) Analog comparator mode 2 (③ ≥ ④, ⑥ ON)

(3) Analog comparator mode 3 (⑤ ≤ ③ ≤ ④, ⑥ ON)

Selection of the input comparison value (V1-V7)

(1) The input comparison value =V1: Setting Frequency

(2) The input comparison value =V2: Operation Frequency

(3) The input comparison value =V3: AIN Input Value

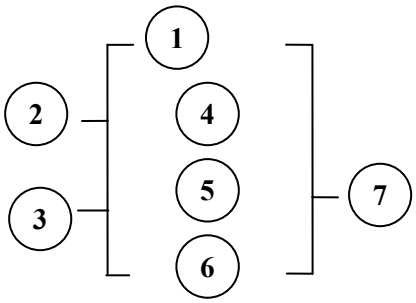
(4) The input comparison value =V4: AI2 Input Value

(5) The input comparison value =V5: Keypad VR input Value

(6) The input comparison value =V6: Operation Current

(7) The input comparison value =V7: Torque Value

□ Encoder input Comparing Instruction



Symbol	Description
①	Encoder control mode (1-2)
②	Use (I1 ~ f8) to set counting up or counting down OFF: counting up (0, 1, 2, 3, 4….) ON: counting down (….3, 2, 1, 0)
③	Use (I1~f8) to Reset counting value.
④	A1, Encoder Input Value/Encoder dividing ratio(⑥)
⑤	A2, Setting comparing value
⑥	C, Encoder dividing ratio
⑦	Encoder comparing output terminal, H1~H4

(1) Control Mode 1

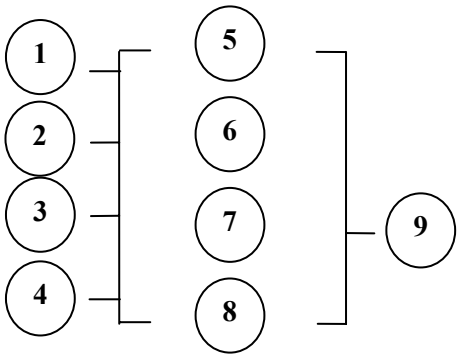
Encoder Comparing Function: A1/C□A2 Comparing Output

(2) Control Mode 2

Encoder Comparing Function: A1/C□A2 Comparing Output

※Comparison Enable/ Disable of the Encoder input value is determined by the Ladder Program ON/OFF.

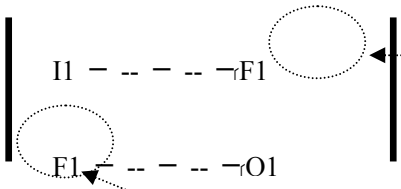
□ Running Instruction



Symbol	Description
①	Running mode could be set via I1~f8 OFF：(FWD) ON：(REV)
②	Segment Speed could be set via I1~f8 OFF：Operating at the frequency set on ⑦ ON：Operating at the frequency set on ⑧
③	Select constant or V3, V5 for Setting Frequency
④	Select constant or V3, V5 for Preset Speed
⑤	Acceleration Time
⑥	Deceleration Time
⑦	Setting Frequency (Could be a constant or V3, V5)
⑧	Segment Speed (Could be a constant or V3, V5)
⑨	, Total: 8 Groups)

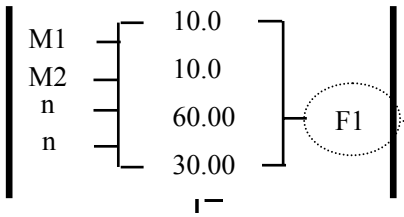
Sample:

Input under the Ladder Program Mode



ON/ OFF of I1 controls the Run/Stop status of F1.

Input under the Function Program Mode



When Inverter operating, F1=ON.

The input terminal of F1 in the ladder program mode should be ON.

Chapter 5 Troubleshooting and maintenance

5.1. Error display and remedy

5.1.1. Errors which can not be recovered manually

	Display	Error	Cause	Remedy
	CPF	Program problem	External noise interference	Connect a parallel RC burst absorber across the magnetizing coil of the magnetic contactor that causes interference
	EPR	EEPROM problem	Faulty EEPROM	Replace EEPROM
@	**-OV-**	Voltage too high during stop	Detection circuit malfunction	Send the inverter back for repairing
@	**-LV-**	Voltage too low during stop	1. Power voltage too low 2. Restraining resistor or fuse burnt out. 3. Detection circuit malfunctions	1. Check if the power voltage was correct or not 2. Replace the restraining resistor or the fuse 3. Send the inverter back for repairing
@	**-OH-**	The inverter is overheated during stop	1. Detection circuit malfunctions 2. Ambient temperature too high or bad ventilation	1. Send the inverter back for repairing 2. Improve ventilation conditions
	CTER	Current Sensor detecting error	Current sensor error or circuit malfunctions	Send the inverter back for repairing

※ Note： 〝@〞 the Failure contact does not function.

5.1.2. Errors which can be recovered manually and automatically

Display	Error	Cause	Remedy
OC-S	Over current at start	1. the motor wind and enclosure short circuit 2. the motor contacts and earth short circuit 3. the IGBT module ruined	1.inspect the motor 2.inspect the wire 3.replace the transistor module
OC-D	Over-current at deceleration	The preset deceleration time is too short.	Set a longer deceleration time
OC-A	Over-current at acceleration	1. Acceleration time too short 2. The capacity of the motor higher than the capacity of the inverter 3. Short circuit between the motor coil and the shell 4. Short circuit between motor wiring and earth 5. IGBT module damaged	1. Set a longer acceleration time 2. Replace a inverter with the same capacity as that of the motor 3. Check the motor 4. Check the wiring 5. Replace the IGBT module
OC-C	Over-current at fixed speed	1. Transient load change 2. Transient power change	1.Increase the capacity of the inverter 2.Rerun parameter auto tuning (0-06 = 1) 3. Reduce stator resistance (14-0) if the above remedies are helpless
OV-C	Voltage too high during operation/ deceleration	1. Deceleration time setting too short or large load inertia 2. Power voltage varies widely	1. Set a longer deceleration time 2. Add a brake resistor or brake module 3. Add a reactor at the power input side 4. Increase inverter capacity
Err4	Illegal interrupt of CPU	Outside noise interference	Send back to repair if it happens many times
OVSP	Over speed during operating	1. Moter load too big or Inverter capacity too small 2. Moter parameter error (vector mode) 3. The gain is too big during vector mode operating 4. The Current detect circuit fault	1. Increase acceleration / deceleration time (3-02/3-03) 2. Input correct motor Parameter 3.Change stator Resistance gain and Rotator resistance gain (14-0/14-1), suggest that decrease 50~100, until 0 4. Send back to Teco

5.1.3 Errors which can be recovered manually but not auto matically

Display	Error	Cause	Remedy
OC	Over-current during stop	1. Detection circuit malfunctions 2. Bad connection for CT signal cable	1.Check the noise between Power line and motor line 2.Send the inverter back for repairing
OL1	Motor overload	1. Heavy load 2. Inappropriate settings of 0-02, 9-08~11	1. Increase the motor capacity 2. set 0-02, 9-08~11 properly
OL2	Inverter overload	Heavy Load	Increase the inverter capacity
OL3	Over torque	1. Heavy Load 2. Insufficient settings of 9-14, 9-15	1. Increase the inverter capacity 2. set 9-14, 9-15 properly
LV-C	Voltage too low during operation	1. Power voltage too low 2. Power voltage varies widely	1. Improve power quality or increase the value of 2-01 2. Set a longer acceleration time 3. Increase inverter capacitor 4. Add a reactor at the power input side
OH-C	Heatsink temperature too High during operation	1. Heavy load 2. Ambient temperature too high or bad ventilation	1. Check if there are any problems with the load 2. Increase inverter capacity 3. Improve ventilation conditions

5.1.4 Special conditions

Display	Error	Description
STP0	Zero speed stop	Happened when preset frequency <0.1Hz
STP1	Fail to start directly	1. If the inverter is set as external terminal control mode (1-00=1) and direct start is disabled (2-04=0001), the inverter cannot be started and will flash STP1 when operation switch turned to ON after applying power (refer to descriptions of 2-04). 2. Direct start is possible when 2-04=0001.
STP2	Keypad emergency stop	1. If the inverter is set as external control mode (1-00=0001) and Stop key is enabled (1-03=0000), the inverter will stop according to the setting of 1-05 when Stop key is pressed. STP2 flashes after stop. Turn the operation switch to OFF and then ON again to restart the inverter. 2. If the inverter is in communication mode and Stop key is enabled (1-03=0000), the inverter will stop in the way set by 1-05 when Stop key is pressed during operation and then flashes STP2. The PC has to send a Stop command then a Run command to the inverter for it to be restarted. 3. Stop key cannot perform emergency stop when 1-03=0001
E.S.	External emergency stop	The inverter will ramp stop and then flash E.S., when input external emergency stop signal via the multifunctional input terminal (refer to descriptions of 5-00~5-06).
b.b.	External base block	The inverter stops immediately and then flashes b.b., when external base block is input through the multifunctional input terminal (refer to descriptions of 5-00~5-06).
ATER	Auto-tuning faults	1. Motor data error resulting in for auto-tuning failure 2. Stop the inverter emergently during Auto-tuning
PDER	PID feedback loss	PID feedback loss detect

5.1.5 Operation errors

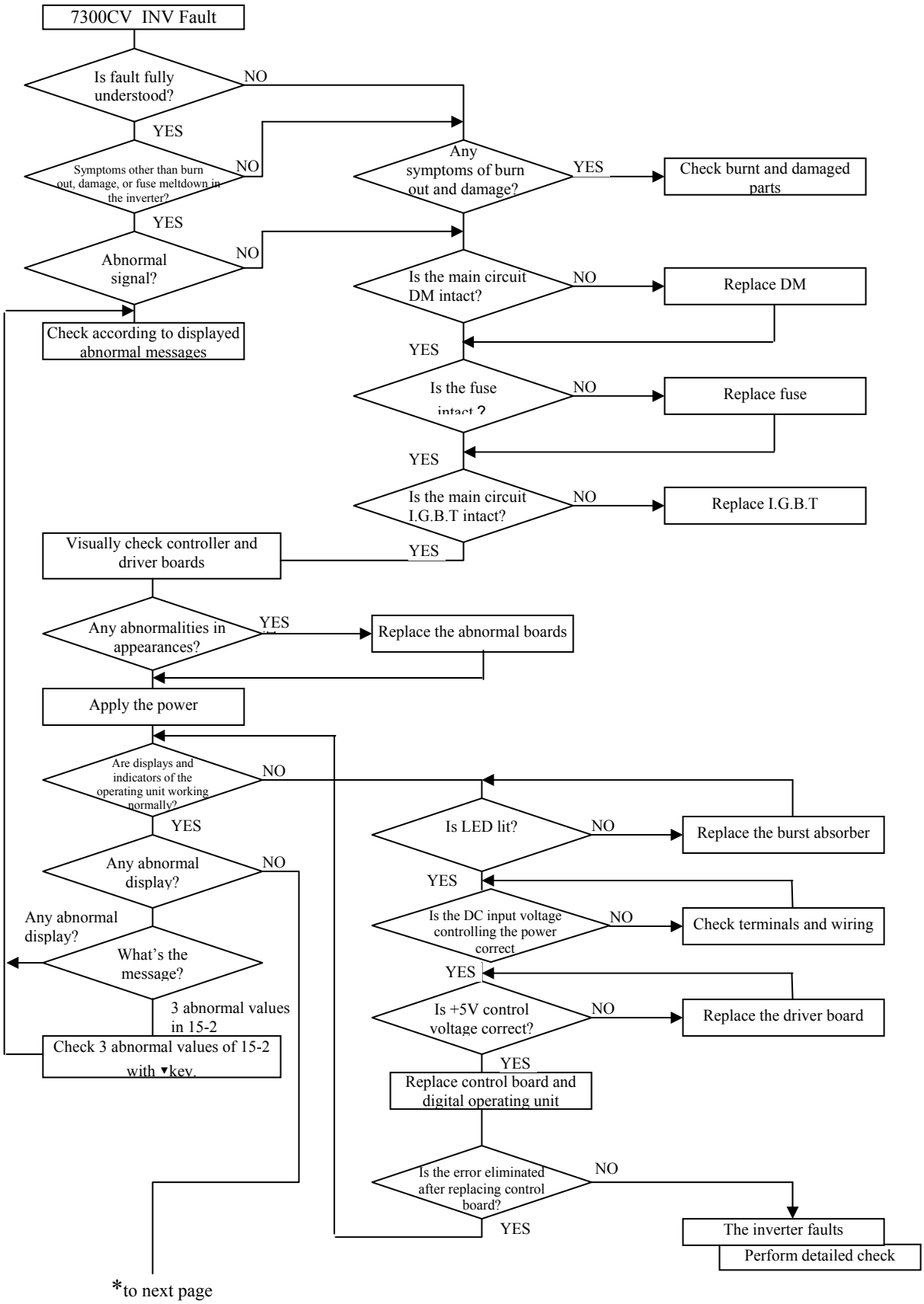
Display	Error	Cause	Remedy
LOC	Parameter and frequency reverse already locked	1.Attempt to modify frequency /parameter while 3-17>0000 2.Attempt to reverse while 1-02=0001	1.Set 3-17=0000 2. Set 1-02=0000
Err1	Key operation error	1.Press ▲ or ▼while 1-06>0 or running at preset speed. 2.Attempt to modify the parameter can not be modified during operation (refer to the parameter list).	1.The ▲ or▼ is available for modifying the parameter only when 1-06=0 2.Modify the parameter while STOP
Err2	Parameter setting error	1. 3-01in the range of 3-13 ± 3-16 or 3-14 ± 3-16or 3-15 ± 3-16 2. 3-00≤3-01 3.The setting error as performing Auto tuning(e.g. 1-00 ≠ 0 , 1-06 ≠ 0)	1.Modify 3-13~3-15or 3-16 2. 3-00>3-01Set 1-00=0, 1-06=0 during Auto tuning
Err5	Modification of parameter is not available in communication	1.Issue a control command during communication disabled 2.Modify the function 13-1~13-4 during communication	1.Issue enable command before communication 2.Set the very parameter of the function before communication
Err6	Communication failed	1.Wiring error 2.Communication parameter setting error. 3.Sum-check error 4.Incorrect communication protocol	1.Check hardware and wiring 2.Check Function 13-1~13-4
Err7	Parameter conflict	1.Attempt to modify the function 15-0 or 15-7 2.Voltage and current detection circuit is abnormal	If Reset inverter is not available, please send the inverter back for repair
Err8	Factory setting error	When PLC is Running, Perform factory setting	Please perform factory setting before PLC stops.
EPr1	Parameter setting error copy unit failed	1.Set 3-18=1.2 without connecting copy unit. 2. Copy unit failed.	1.Modify 3-18 2.Replace copy unit
EPr2	Parameter not match	Copy the parameter to inverter to verify the parameter is not match.	1.Rewrite again 2.Replace copy unit

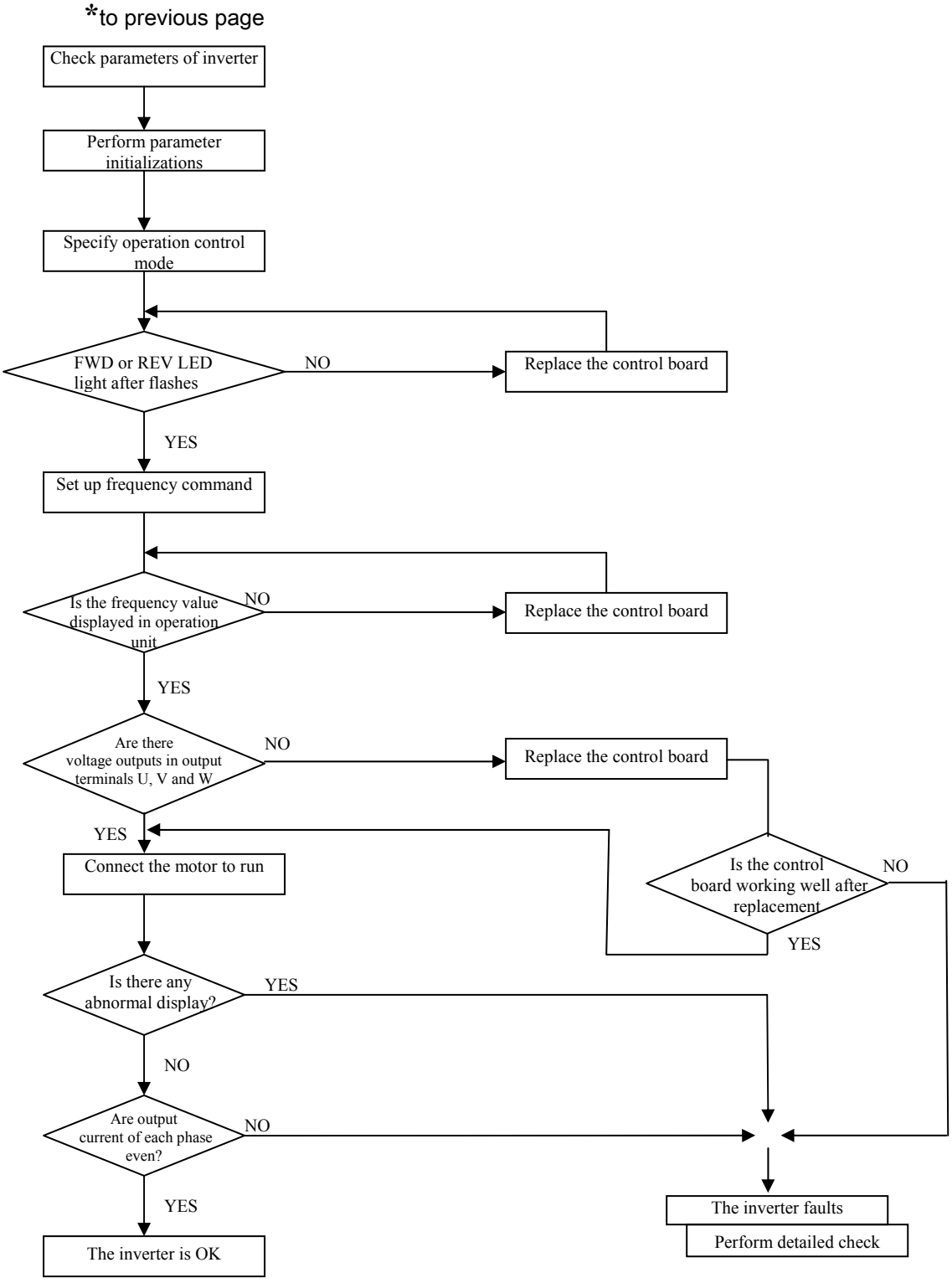
5.2 General troubleshooting

Status	Checking point	Remedy
Motor can not run	Is power applied to L1(L), L2, and L3(N) terminals (is the charging indicator lit)?	·Is the power applied? ·Turn the power OFF and then ON again. ·Make sure the power voltage is correct. ·Make sure screws are secured firmly.
	Are there voltage across the output terminal T1, T2, and T3?	·Turn the power OFF and then ON again.
	Is overload causing the motor blocked?	·Reduce the load to let the motor running.
	Are there any abnormalities in the inverter?	·See error descriptions to check wiring and correct if necessary.
	Is forward or reverse running command issued?	
	Has analog frequency signal been input?	· Is analog frequency input signal wiring correct? ·Is voltage of frequency input correct?
	Is operation mode setting correct?	·Operate operations through the digital panel.
Motor runs inversely	Are wiring for output terminals T1, T2, and T3 correct?	·Wiring must match U, V, and W terminals of the motor.
	Are wiring for forward and reverse signals correct?	·Check wiring are correct if necessary.
The motor speed can not be regulated.	Are wiring for analog frequency inputs correct?	·Check wiring are correct if necessary.
	Is the setting of operation mode correct?	·Check the operation mode of the operator.
	Is the load too heavy?	·Reduce the load.
Motor running speed too high or too low	Are specifications of the motor (poles, voltage…) correct?	·Confirm the motor's specifications.
	Is the gear ratio correct?	·Confirm the gear ratio.
	Is the setting of the highest output frequency correct?	·Confirm the highest output frequency.
Motor speed varies unusually	Is the load too heavy?	·Reduce the load.
	Does the load vary largely?	·Minimize the variation of the load. ·Increase capacities of the inverter and the motor.

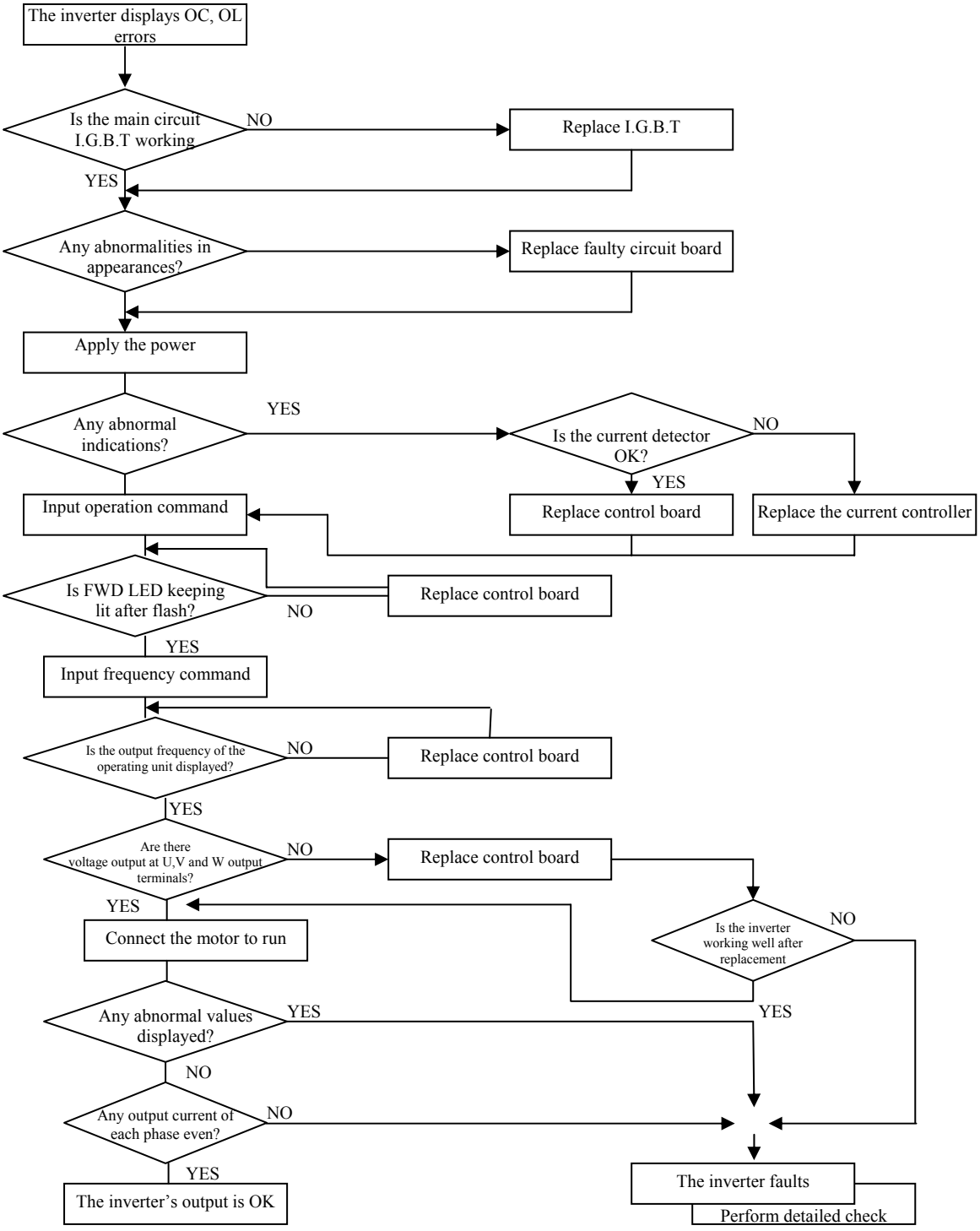
	Is the input power lack of phase?	·Add an AC reactor at the power input side if using single-phase power. ·Check wiring if using three-phase power.

5.3 Quick troubleshooting of 7300CV

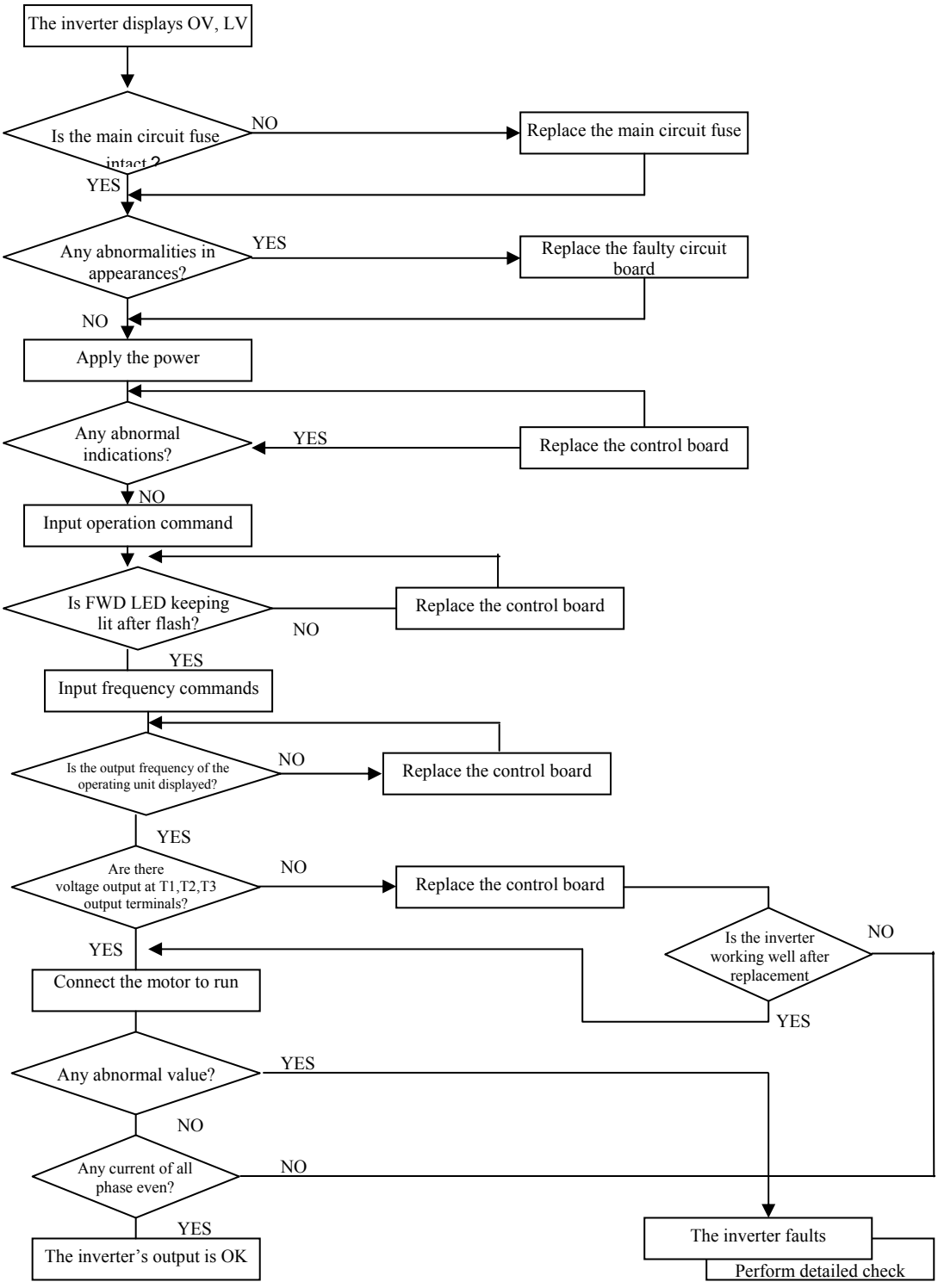



*to previous page
Check parameters of inverter
Perform parameter initializations
Specify operation control mode
FWD or REV LED light after flashes
NO
Replace the control board
YES
Set up frequency command
Is the frequency value displayed in operation unit
NO
Replace the control board
YES
Are there voltage outputs in output terminals U, V and W
NO
Replace the control board
YES
Connect the motor to run
Is the control board working well after replacement
NO
YES
Is there any abnormal display?
YES
NO
Are output current of each phase even?
NO
YES
The inverter is OK
The inverter faults
Perform detailed check

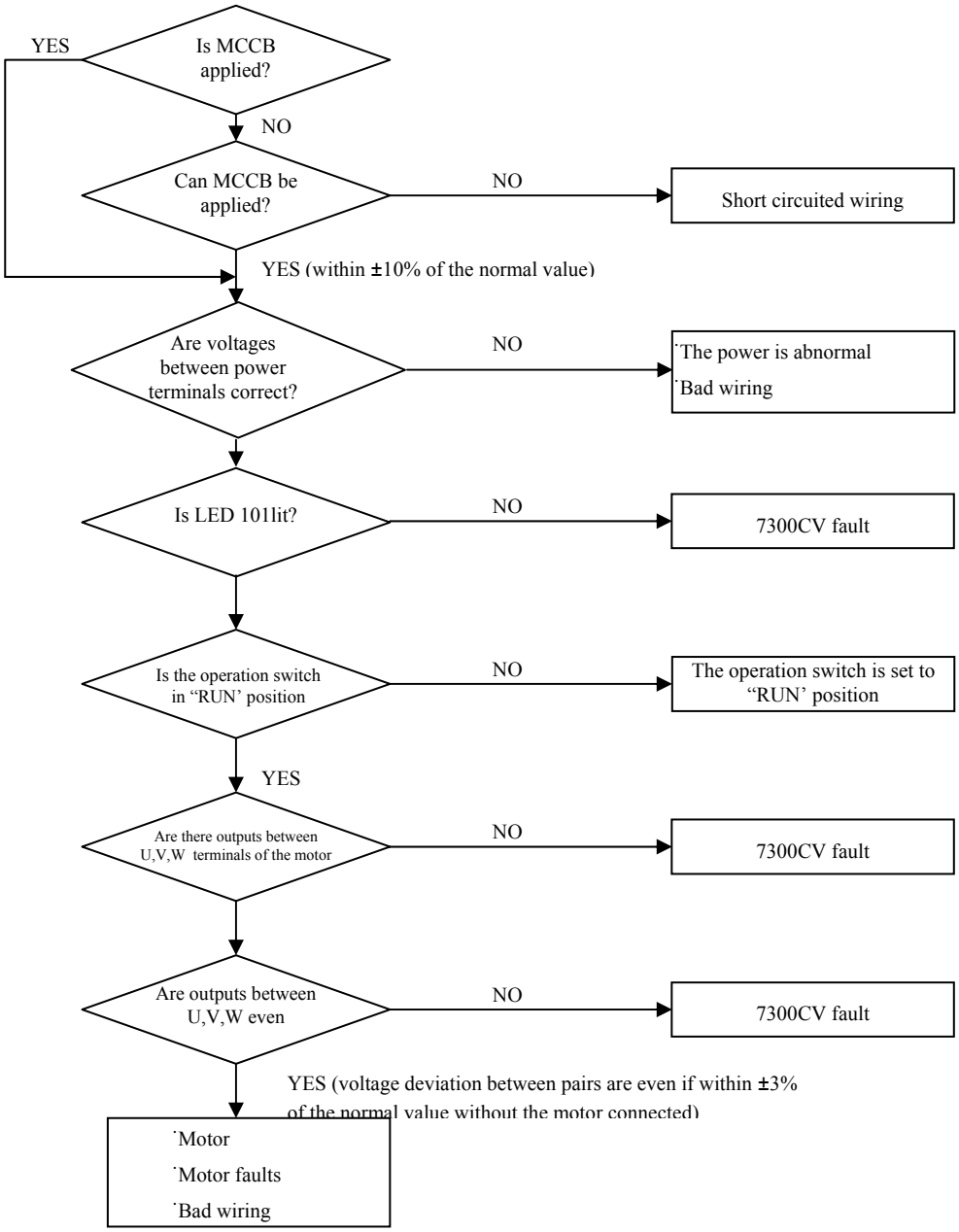
Troubleshooting for OC, OL error displays



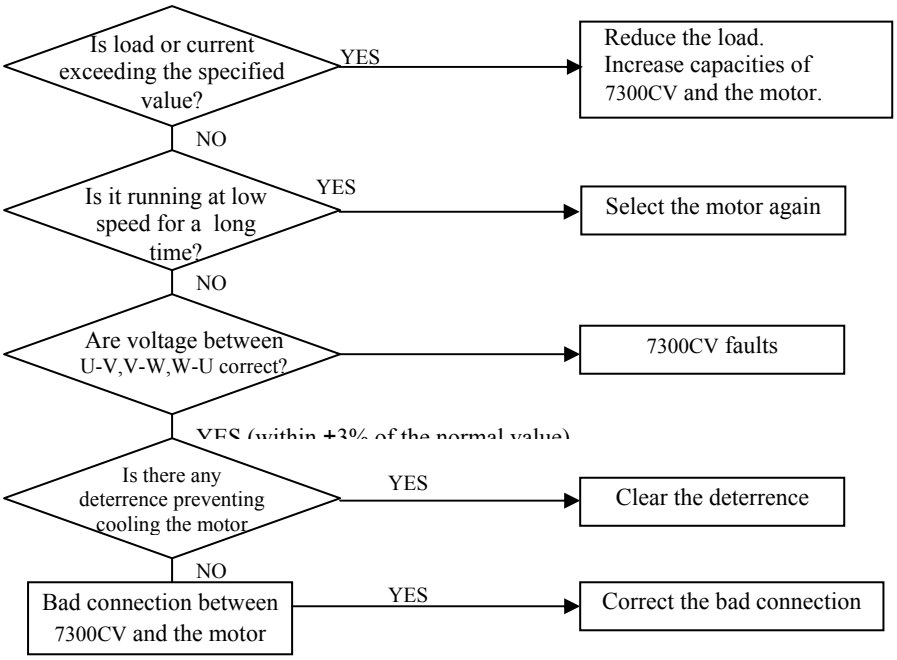
Troubleshooting for OV, LV error



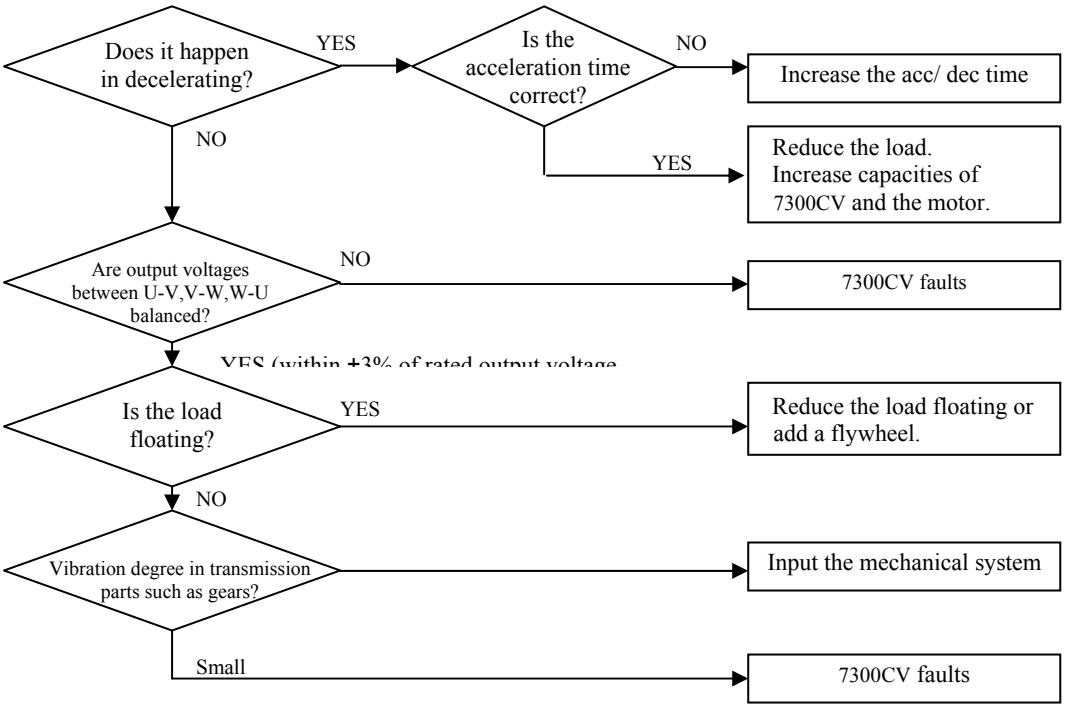
The motor can not run



The motor is overheated



Motor runs unevenly



5.4 Routine inspection and period inspection

To ensure stable and safe operations, check and maintain the inverter regularly and periodically.

The table below lists the items to be check to ensure stable and safe operations.

Check these items 5 minutes after the "Charge" indicator goes out to prevent service persons from being hurt by residual electric power.

Items	Details	Checking period		Methods	Criteria	Remedies
		Daily	1Year			
Circumstances around the machine	Confirm the temperature and humidity around the machine	○		Measure with thermometer and hygrometer according to installation notices.	Temperature: -10 – 40°C Humidity: Below 95% RH	Improve the circumstances
	Are there inflammables piled up around?	○		Visual check	No foreign matters	
Installation and grounding of the inverter	Any unusual vibration from the machine	○		Visual, hearing	No foreign matters	Secure screws
	Is the grounding resistance correct?		○	Measure the resistance with a multi-tester	200V series: below 100Ω 400V series: below 10Ω	Improve the grounding
Input power voltage	Is the voltage of the main circuit correct?	○		Measure the voltage with a multi-tester	Voltage must conform with the specifications	Improve input voltage
External terminals and internal mounting screws of the inverter	Are secure parts loose?		○	Visual check Check with a screwdriver	No abnormalities	Secure or send back for repair
	Is the terminal base damaged?		○			
	Obvious rust stains		○			
Internal wiring of the inverter	Deformed or crooked		○	Visual check	No abnormalities	Replace or send back for repair
	Any damage of the wrapping of the conducting wire		○			
Heat sink	Heap of dust or mingled trifles	○		Visual check	No abnormalities	Clean up heaped dust
Printed circuit board	Heap of conductive metal or oil sludge		○	Visual check	No abnormalities	Clean up or replace the circuit board
	Discolored, overheated, or burned parts		○			
Cooling fan	Unusual vibration and noise		○	Visual or hearing check	No abnormalities	Replace the cooling fan
	Heap of dust or mingled trifles	○		Visual check		Clean up
Power component	Heap of dust or mingled trifles		○	Visual check	No abnormalities	Clean up
	Check resistance between each terminals		○	Measure with a multi-tester	No short circuit or broken circuit in three-phase output	Replace power component or inverter
Capacitor	Any unusual odor or leakage	○		Visual check	No abnormalities	Replace capacitor or

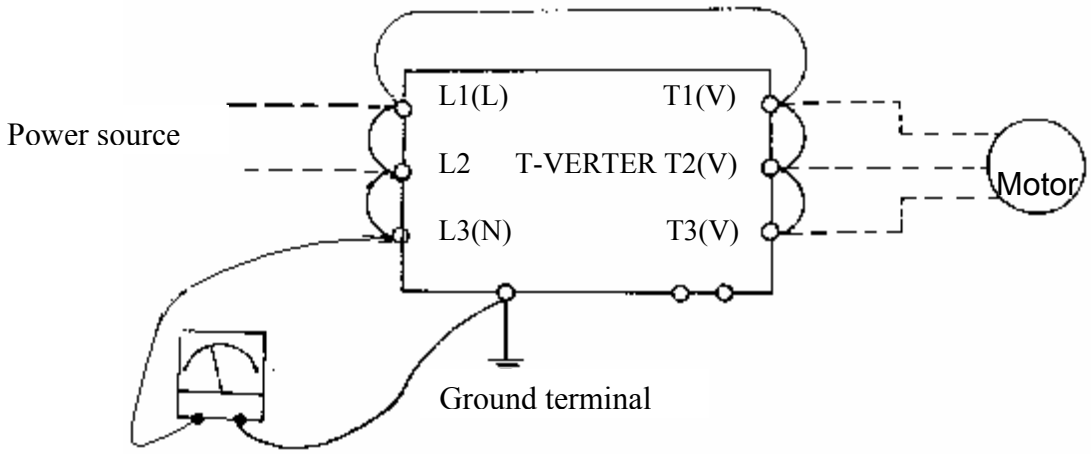
	Any inflation or protrusion	○				inverter

5.5 Maintenance and Inspection

Inverter doesn't need daily inspection and maintenance.
To ensure long-term reliability, follow the instructions below to perform regular inspection. Turn the power off and wait for the charge indicator (LED101) to go out before inspection to avoid potential shock hazard possibly caused by charges resides in high-capacity capacitors.

(1) Clean up the accumulation of muck inside the inverter.
(2) Check if there are any loose terminal screws and securing screws. Tighten all loose screws.
(3) Insulation tests
   (a) Disconnect all leads connecting T-VERTER with external circuit when performing insulation tests against external circuit.
   (b) Internal insulation test should be performed against the main circuit of the T-VERTER body only. Use a high resistance DC 500V meter with insulating resistance higher than 5MΩ.

   Caution! Do not perform this test against the control circuit.



DC-500V high resistance meter

Chapter 6 Peripherals Components

6.1 Reactor specification at Input side

Model		AC inductance at input side	
		Current (A)	Inductance (mH)
JNTHXXBA-	R500-AC/BC	5.0	2.1
	0001-AC/BC	5.0	2.1
	0002-AC/BC	10.0	1.1
	0003-AC/BC	15.0	0.71
	0005-BC	20.0	0.53
	7R50-BC	30.0	0.35
	0010-BC	40.0	0.265
	0015-BC	60.0	0.18
	0020-BC	80.0	0.13
	0025-BC	90.0	0.12
	0030-BC	120.0	0.09
	0040-BC	160.0	0.07

Model		AC inductance at input side	
		Current (A)	Inductance (mH)
JNTHXXBA-	0001-BE	2.5	8.4
	0002-BE	5.0	4.2
	0003-BE	7.5	3.6
	0005-BE	10.0	2.2
	7R50-BE	15.0	1.42
	0010-BE	20.0	1.06
	0015-BE	30.0	0.7
	0020-BE	40.0	0.53
	0025-BE	50.0	0.42
	0030-BE	60.0	0.36
	0040-BE	80.0	0.26
	0050-BE	90.0	0.24
	0060-BE	120.0	0.18
	0075-BE	150.0	0.15

6.2 Reactor specification at DC side

Model		DC inductance at input side	
		Current (A)	Inductance (mH)
JNTHXXBA-	R500-AC/BC	3.1	5.65
	0001-AC/BC	4.5	3.89
	0002-AC/BC	7.5	2.33
	0003-AC/BC	10.5	1.67
	0005-BC	17.5	1.00
	7R50-BC	26	0.67
	0010-BC	35	0.50
	0001-BE	2.3	15.22
	0002-BE	3.8	9.21
	0003-BE	5.2	6.73
	0005-BE	8.8	3.98
	7R50-BE	13	2.69
	0010-BE	17.5	2.00
	0015-BE	25	1.40

6.3 Braking unit and braking resistor

7300CV series braking current calculation

Inverter Model	Braking Unit		Brake Resistor	Suitable Motor Capacity (HP)	Suitable Motor Capacity (KW)	Brake resistor Specification		Brake resistor ED(%)	Brake torque (%)	Resistor dimension (L*W*H) mm
	Model	Number used	Type			(W)	(Ω)			
R500-AC/BC	-	-	JNBR-150W200	0.5	0.4	150	200	10	238	251*28*60
0001-AC/BC	-	-	JNBR-150W200	1	0.75	150	200	10	119	251*28*60
0002-AC/BC	-	-	JNBR-150W100	2	1.5	150	100	10	119	251*28*60
0003-AC/BC	-	-	JNBR-260W70	3	2.2	260	70	10	115	274*34*78
0005-BC	-	-	JNBR-390W40	5	3.7	390	40	10	119	395*34*78
7R50-BC	-	-	JNBR-520W30	7.5	5.5	520	30	10	108	400*40*100
0010-BC	-	-	JNBR-780W20	10	7.5	780	20	10	119	400*40*100
0015-BC	-	-	JNBR-2R4KW13R6	15	11	2400	13.6	10	117	535*50*110 (*2 pcs)
0020-BC	-	-	JNBR-3KW10	20	15	3000	10	10	119	615*50*110 (*2 pcs)
0025-BC	JNTBU-230	1	JNBR-4R8KW8	25	18.5	4800	8	10	119	535*50*110 (*4 pcs)
0030-BC	JNTBU-230	1	JNBR-4R8KW6R8	30	22	4800	6.8	10	117	535*50*110 (*4 pcs)
0040-BC	JNTBU-230	2	JNBR-3KW10	40	30	3000	10	10	119	615*50*110 (*2 pcs)
0001-BE	-	-	JNBR-150W750	1	0.75	150	750	10	126	251*28*60
0002-BE	-	-	JNBR-150W400	2	1.5	150	400	10	119	251*28*60
0003-BE	-	-	JNBR-260W250-	3	2.2	260	250	10	126	274*34*78
0005-BE	-	-	JNBR-400W150-	5	3.7	400	150	10	126	395*34*78
7R50-BE	-	-	JNBR-600W130-	7.5	5.5	600	130	10	102	470*50*100
0010-BE	-	-	JNBR-800W100	10	7.5	800	100	10	99	535*50*110
0015-BE	-	-	JNBR-1R6KW50	15	11	1600	50	10	126	615*50*110
0020-BE	-	-	JNBR-1R5KW40	20	15	1500	40	10	119	615*50*110
0025-BE	JNTBU-430	1	JNBR-4R8KW32	25	18.5	4800	32	10	119	535*50*110 (*4 pcs)
0030-BE	JNTBU-430	1	JNBR-4R8KW27R2	30	22	4800	27.2	10	117	535*50*110 (*4 pcs)
0040-BE	JNTBU-430	1	JNBR-6KW20	40	30	6000	20	10	119	615*50*110 (*4 pcs)
0050-BE	JNVPHV-0060	1[*5]	JNBR-4R8KW32	50	37	4800	32	10	119	535*50*110 (*4 pcs)
0060-BE	JNVPHV-0060	1[*5]	JNBR-4R8KW27R2	60	45	4800	27.2	10	117	535*50*110 (*4 pcs)
0075-BE	JNTBU-430	2	JNBR-6KW20	75	55	6000	20	10	126	615*50*110 (*4 pcs)

□ Formula for brake resistor: **W= (Vpnb * Vpnb) * ED% / Rmin**

1. **W :** brake resistor consumption power
2. **Vpnb:** brake voltage (220V=380VDC, 440V=760VDC)
3. **ED%:** braking effective period
4. **Rmin:** allowable minimum brake resistor
5. **Another choice:** 0050-BE: (JNTBU-430 + JNBR-9R6KW32) × 2
   0060-BE: (JNTBU-430 + JNBR-4R8KW27R2) × 2

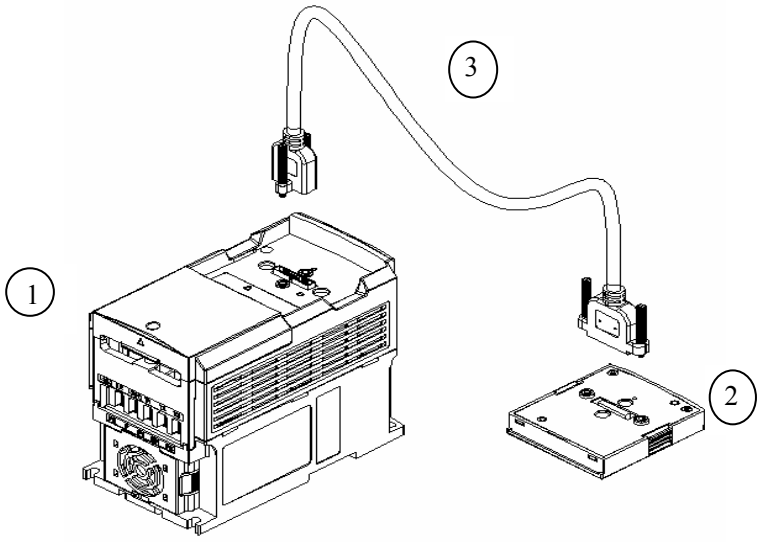
□ Above 25HP, please add Braking Unit: 200V JNTBU-230
400V JNTBU-430
400V JUVPHV-0060

About the detail information, please contact with your supplier.

6.4 Digital operator and extension cable

A. Remote Cable Kit

Inverter Model	Extension Cable Kit	Cable Length (Meter)
All models	JNSW-30P5	0.5
	JNSW-3001	1.0
	JNSW-3002	2.0
	JNSW-3003	3.0
	JNSW-3005	5.0



B. Content

① Inverter

② LED (JNSDOP-LED) or LCD (JNSDOP-LCD) Keypad

③REMOTE Cable for Keypad

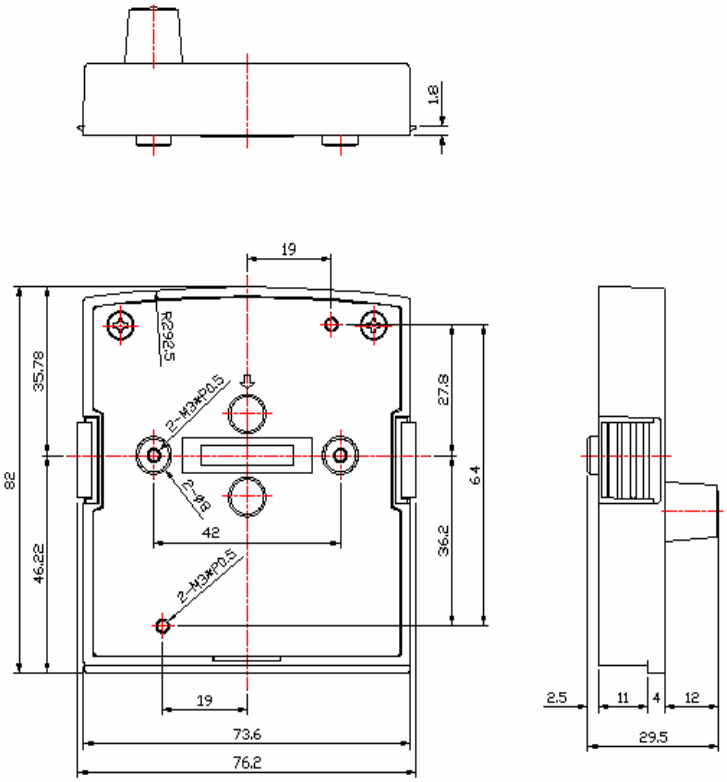
C. Operation procedure:

Warning: Turn OFF the power supply. The following procedures should be performed after there is no display on the keypad.

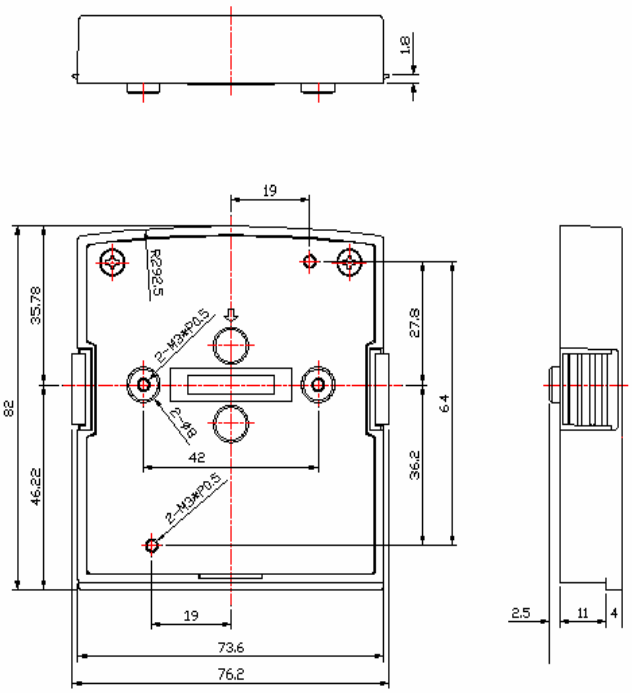
1. Remove the keypad from the Inverter.
2. Please refer to Diagram before mounting the keypad to your machine or Panel.
3. Connect the inverter and the keypad with the remote cable in accordance with the above Diagram.

Supply the power to operate ONLY after all elements are securely fixed.

LED Keypad(JNSDOP-LED)Mounting Dimensions Unit：mm



LCD Keypad(JNSDOP-LCD)Mounting Dimensions Unit：mm



6. 5 EMC Filter

The inverter adopts rapid switching components to improve the efficiency of the motor and to reduce the motor noise. Using the EMC Filter allows the EMI (Electromagnetic Interference) and RFI (Radio Frequency interference) to be controlled within certain range.

EMC Directives

The inverter with optional filter complies with the EMC directives 89/336/EEC, limiting the environmental EMI and RFI. Independent tests have demonstrated compliance to the following standards when the optional filters are used.

EMI radio standard、EMS immunity standard

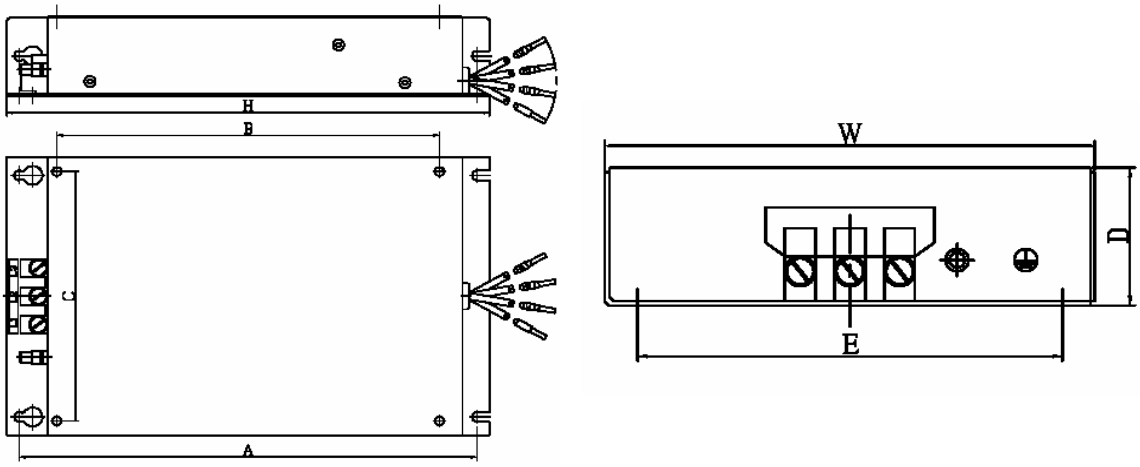
EN 61800-3 1996/A11: 2000：First Environment Unrestricted Distribution (Class B).

EN 61800-3 1996/A11: 2000：First Environment Restricted Distribution

Filter Selection

Inverter Model		Rating (INPUT)	Filter Model	
			First Environment Restricted Distribution	First Environment Unrestricted Distribution
JNTHBCBA	R500AC-UF	1 ϕ 170 ~264V	Built in	FS 6146-11-07
	0001AC-UF	1 ϕ 170~264V	Built in	FS 6146-11-07
	0002AC-UF	1 ϕ 170~264V	Built in	FS 6146-27-07
	0003AC-UF	1 ϕ 170 ~264V	Built in	FS 6146-27-07
	R500AC-U	1 ϕ 170 ~264V	FS 6146-11-07	--
	0001AC-U	1 ϕ 170~264V	FS 6146-11-07	--
	0002AC-U	1 ϕ 170~264V	FS 6146-27-07	--
	0003AC-U	1 ϕ 170 ~264V	FS 6146-27-07	--
	R500BC-U	3 ϕ 170 ~264V	FS 6147-8.9-07	--
	0001BC-U	3 ϕ 170 ~264V	FS 6147-8.9-07	--
	0002BC-U	3 ϕ 170 ~264V	FS 6147-8.9-07	--
	0003BC-U	3 ϕ 170 ~264V	FS 6147-19-07	--
	0005BC-U	3 ϕ 170 ~264V	FS 6147-19-07	--
	7R50BC-U	3 ϕ 170 ~264V	FS 6147-39-07	--
	0010BC-U	3 ϕ 170 ~264V	FS 6147-39-07	--
	0001BE-UF	3 ϕ 323~528 V	Built in	FS 6149-4.6-07
	0002BE-UF	3 ϕ 323~528 V	Built in	FS 6149-4.6-07
	0003BE-UF	3 ϕ 323~528 V	Built in	FS 6149-10-07
	0005BE-UF	3 ϕ 323~528 V	Built in	FS 6149-10-07
	7R50BE-UF	3 ϕ 323~528 V	Built in	FS 6149-28-07
	0010BE-UF	3 ϕ 323~528 V	Built in	FS 6149-28-07
	0015BE-UF	3 ϕ 323~528 V	Built in	FS 6149-28-07
	0001BE-U	3 ϕ 323~528 V	FS 6149-4.6-07	--
	0002BE-U	3 ϕ 323~528 V	FS 6149-4.6-07	--
	0003BE-U	3 ϕ 323~528 V	FS 6149-10-07	--
	0005BE-U	3 ϕ 323~528 V	FS 6149-10-07	--
	7R50BE-U	3 ϕ 323~528 V	FS 6149-28-07	--
	0010BE-U	3 ϕ 323~528 V	FS 6149-28-07	--
	0015BE-U	3 ϕ 323~528 V	FS 6149-28-07	--
	0020BE-U	3 ϕ 323~528 V	JUNF34048S-MA	--
	0025BE-U	3 ϕ 323~528 V	KMF370A	--
	0030BE-U	3 ϕ 323~528 V	KMF370A	--
	0040BE-U	3 ϕ 323~528 V	KMF3100A	--
	0050BE-U	3 ϕ 323~528 V	KMF3100A	--
	0060BE-U	3 ϕ 323~528 V	KMF3150A	--
	0075BE-U	3 ϕ 323~528 V	KMF3180A	--

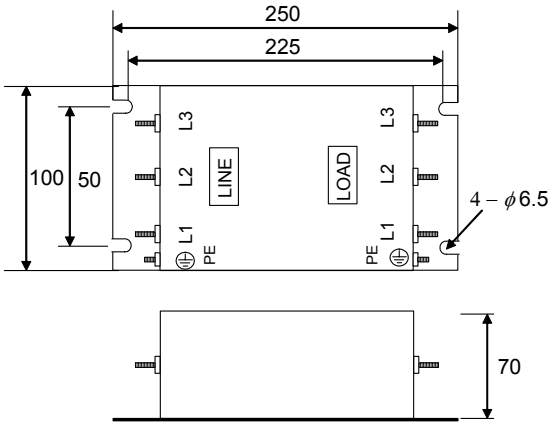
7300CV External Filter Size

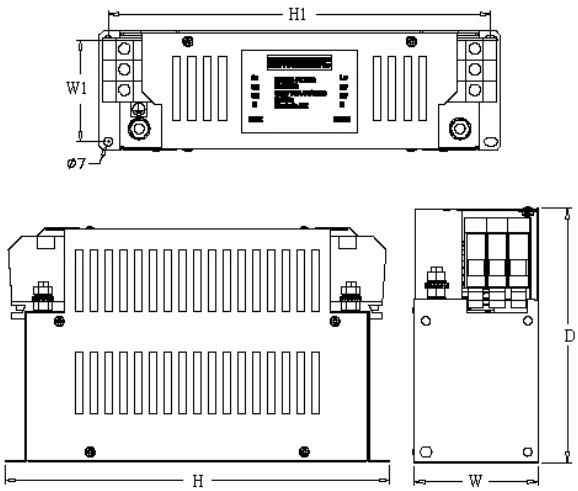


SIZE / MODEL	Inverter Mounting Dimensions (C*B)	External Filter Size (W*H*D)	External Filter Mounting Dimensions(E*A)
FS 6146 - 11 - 07 FS 6147 - 8.9 - 07 FS 6149- 4.6 - 07	**78 * 150**	**91 * 192 * 28**	**74 * 181**
FS 6146 - 27 – 07 FS 6147 - 19 –07 FS 6149 - 10 - 07	**114.6 * 170.5**	**128 * 215 * 37**	**111 * 204**
FS 6147 - 39 – 07 FS 6149 - 28 - 07	**173 * 244**	**188 * 289 * 42**	**165 * 278**

JUNF34048S-MA

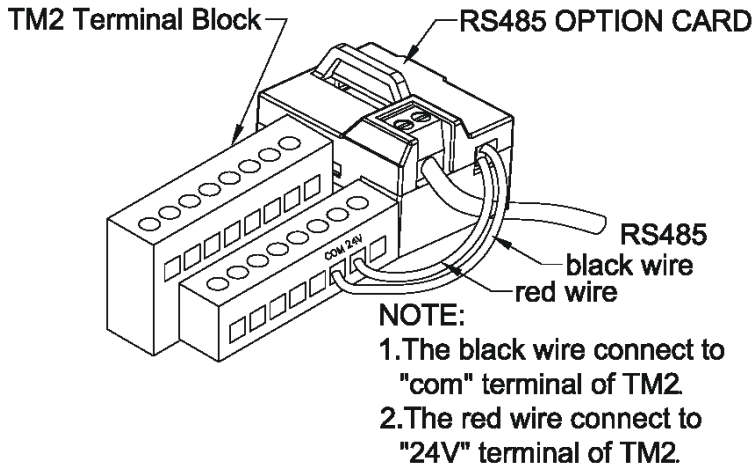
Model	Dimensions (mm)						
	W	W1	H	H1	D	d	M
KMF370A	93	79	312	298	190	7	M6
KMF3100A	93	79	312	298	190	7	M6
KMF3150A	126	112	312	298	224	7	M6
KMF3180A	126	112	312	298	224	7	M6



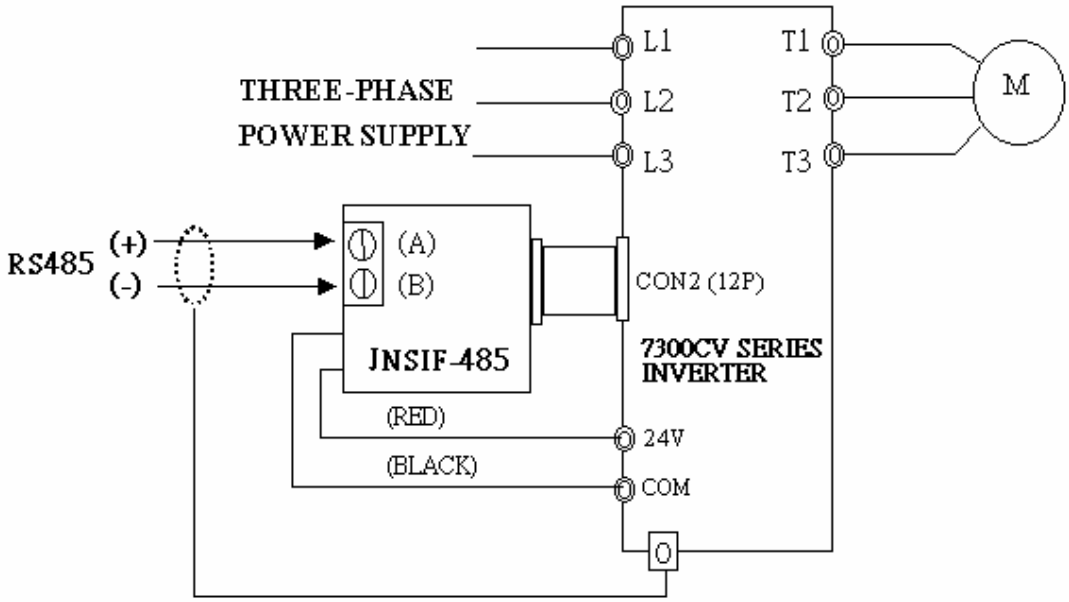


6.6 Interface Card

6.6.1 RS-485 Interface Card (Model : JNSIF-485)



JNSIF-485 Wiring Diagram：

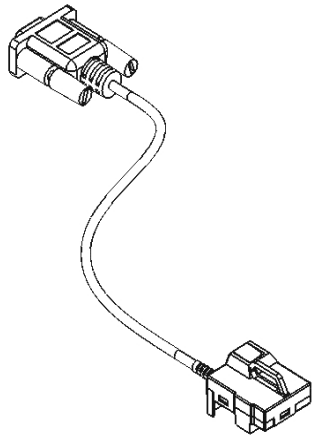


Note:

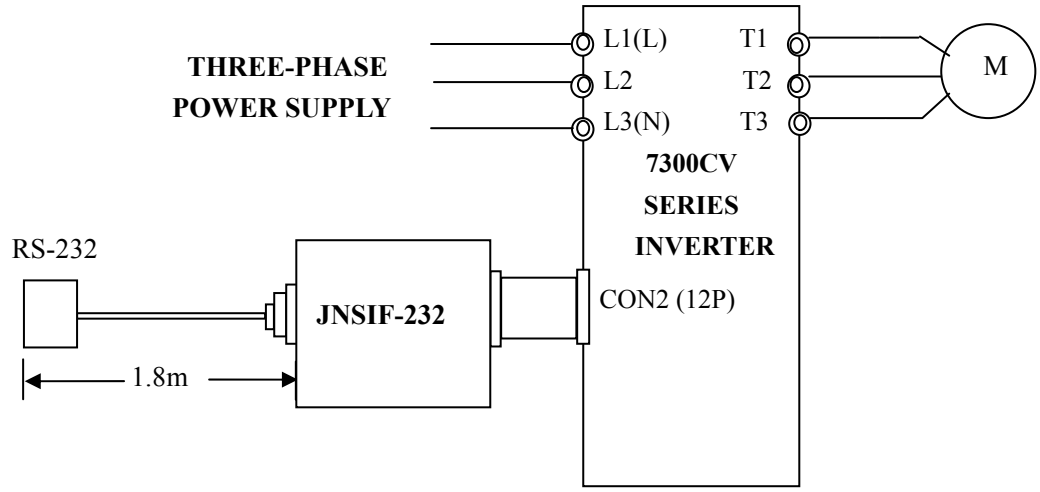
Please put on the cover of inverter to avoid the Interface Card disturbed by outside static electricity.

Please using isolated RS232 / RS485 converter to link PC and interface card to avoid damage equipment.

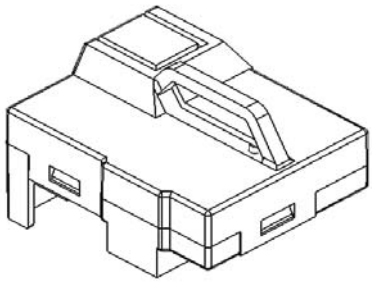
6.6.2 RS-232 Interface Card (Model : JNSIF-232)



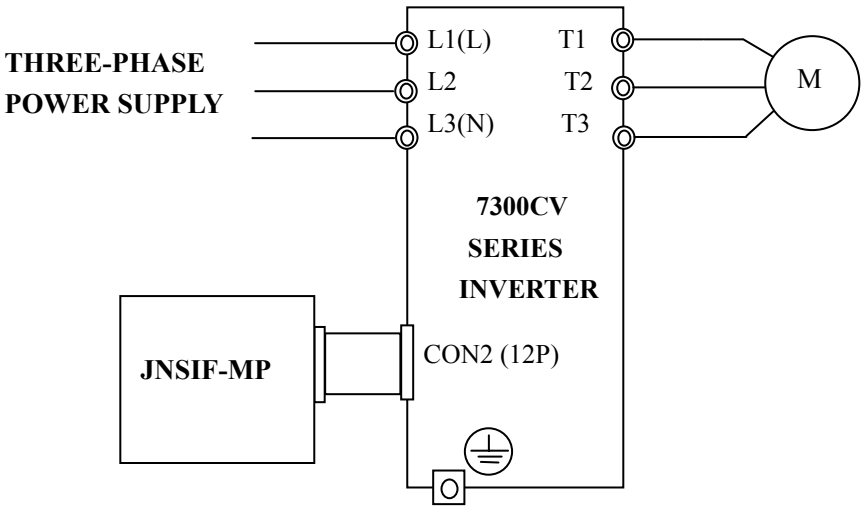
JNSIF-232Wiring Diagram：



6.6.3 Program Copy Unit (Model: JNSIF-MP)

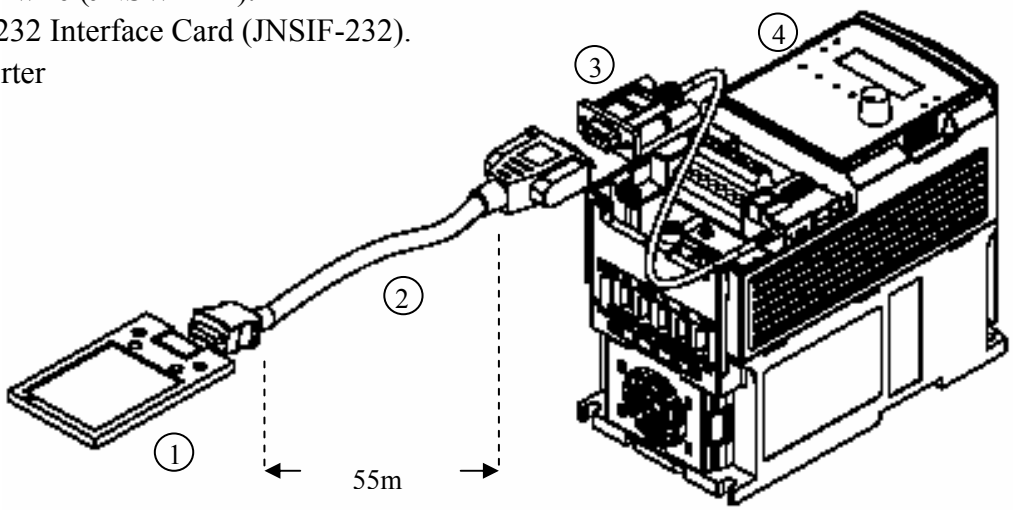


JNSIF-MP Wiring Diagram



6.6.4 PDA Link

①. HP iPAQ Pocket PC h2210. (PDA)
②. PDA wire (JNSWPDA).
③. RS-232 Interface Card (JNSIF-232).
④. Inverter



Appendix 1: 7300CV Motor Internal Parameter List

Factory Setting of the Motor Internal Parameters：

Model \ Parameter		14-0 (Stator Resistance)	14-1 (Rotor Resistance)	14-2 (Equivalent Inductance)	14-3 (Magnetization Current)	14-4 (Iron Loss Conductance)
JNTHBCBA	R500AC/BC	200	200	800	7200	0
	0001AC/BC 0001BE	380	300			
	0002AC/BC 0002BE	300	280			
	0003AC/BC 0003BE	280	240			
	0005BC 0005BE	260	200			
	7R50BC 7R50BE	240	160			
	0010BC 0010BE	220	150			
	0015BC 0015BE	200	140			
	0020BC 0020BE	180	130		4100	205
	0025BC 0025BE					
	0030BC 0030BE					
	0040BC 0040BE					
	0050BE					
	0060BE					
	0075BE					

※Note：

1. The above motor internal parameters are idle under V/F Control Mode. These parameters are usable under vector control mode.

2. The motor parameters (14-0~14-4) are not be modified when factory setting under vector mode. The internal parameters will be maintained at the ones after auto tuning (refer to Auto Tuning and Description on motor Internal Parameter).

3: The motor parameters (14-0~14-4) will be modified to factory setting completely under whatever operation mode.

Appendix 2: 7300CV parameter setting list

Customer				Inverter Model			
Using Site				Contact Phone			
Address							
Parameter Code	Setting Content	Parameter Code	Setting Content	Parameter Code	Setting Content	Parameter Code	Setting Content
0-00		3-14		6-06		10-7	
0-01		3-15		6-07		10-8	
0-02		3-16		6-08		10-9	
0-03		3-17		7-00		11-0	
0-04		3-18		7-01		11-1	
0-05		3-19		7-02		11-2	
0-06		3-20		7-03		11-3	
0-07		3-21		7-04		11-4	
0-08		3-22		7-05		11-5	
1-00		3-23		8-00		11-6	
1-01		3-24		8-01		11-7	
1-02		3-25		8-02		12-0	
1-03		3-26		8-03		12-1	
1-04		3-27		8-04		12-2	
1-05		3-28		8-05		12-3	
1-06		3-29		9-00		12-4	
1-07		4-00		9-01		12-5	
2-00		4-01		9-02		12-6	
2-01		4-02		9-03		13-0	
2-02		4-03		9-04		13-1	
2-03		4-04		9-05		13-2	
2-04		4-05		9-06		13-3	
2-05		5-00		9-07		13-4	
2-06		5-01		9-08		14-0	
3-00		5-02		9-09		14-1	
3-01		5-03		9-10		14-2	
3-02		5-04		9-11		14-3	
3-03		5-05		9-12		14-4	
3-04		5-06		9-13		15-0	
3-05		5-07		9-14		15-1	
3-06		5-08		9-15		15-2	
3-07		5-09		10-0		15-3	
3-08		6-00		10-1		15-4	
3-09		6-01		10-2		15-5	
3-10		6-02		10-3		15-6	
3-11		6-03		10-4			
3-12		6-04		10-5			
3-13		6-05		10-6			